



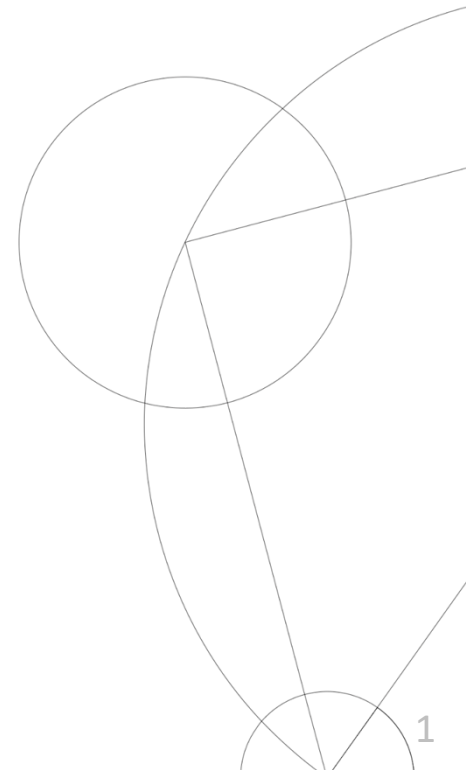
PROBABILISTIC VISUAL LEARNING OBJECT DETECTION A SUMMARY

ADVANCED METHODS APPLIED STATISTICS – ARTICLE SUMMARY

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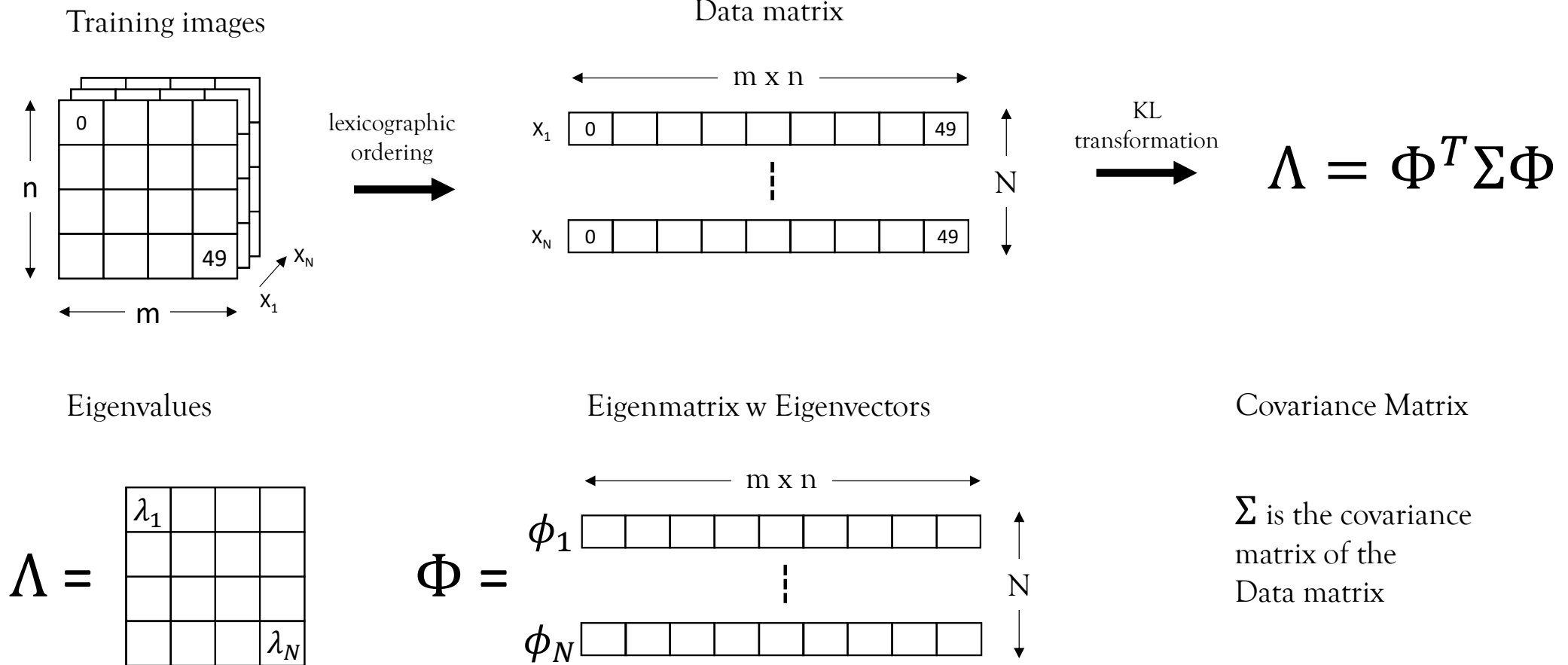
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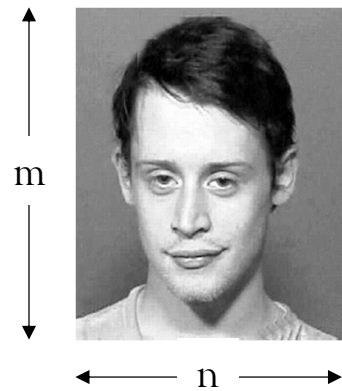
Transforming the training data





Analyzing a new image

New (random) image, x

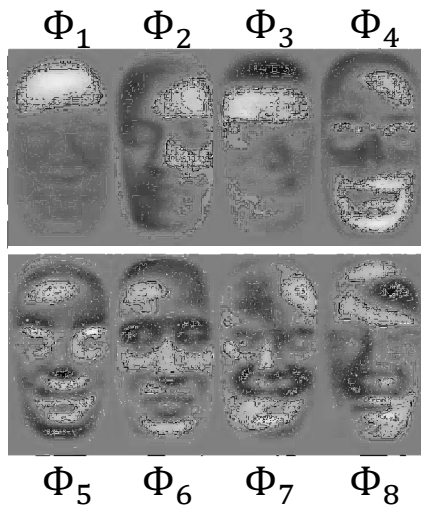


$$\tilde{x} = x - \bar{x}$$

$$y = \Phi^T \tilde{x} = \begin{matrix} \leftarrow m \times n \rightarrow \\ \uparrow \downarrow N \\ \begin{array}{|c|c|c|c|} \hline & & & \\ \hline & & & \\ \hline & & & \\ \hline & & & \\ \hline \end{array} \end{matrix} \cdot \begin{matrix} 1 \\ \uparrow \downarrow m \times n \\ \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} \end{matrix} = \begin{matrix} 1 \\ \uparrow \downarrow N \\ \begin{array}{|c|} \hline \omega_1 \\ \hline \\ \hline \\ \hline \omega_N \\ \hline \end{array} \end{matrix}$$

PCA, choosing
M highest eigenvalues

$$y_M = \Phi_M^T \tilde{x} = \begin{matrix} \leftarrow m \times n \rightarrow \\ \uparrow \downarrow M \\ \begin{array}{|c|c|c|c|} \hline & & & \\ \hline & & & \\ \hline & & & \\ \hline & & & \\ \hline \end{array} \end{matrix} \cdot \begin{matrix} 1 \\ \uparrow \downarrow m \times n \\ \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \end{array} \end{matrix} = \begin{matrix} 1 \\ \uparrow \downarrow M \\ \begin{array}{|c|} \hline \omega_1 \\ \hline \omega_M \\ \hline \\ \hline \omega_N \\ \hline \end{array} \end{matrix}$$



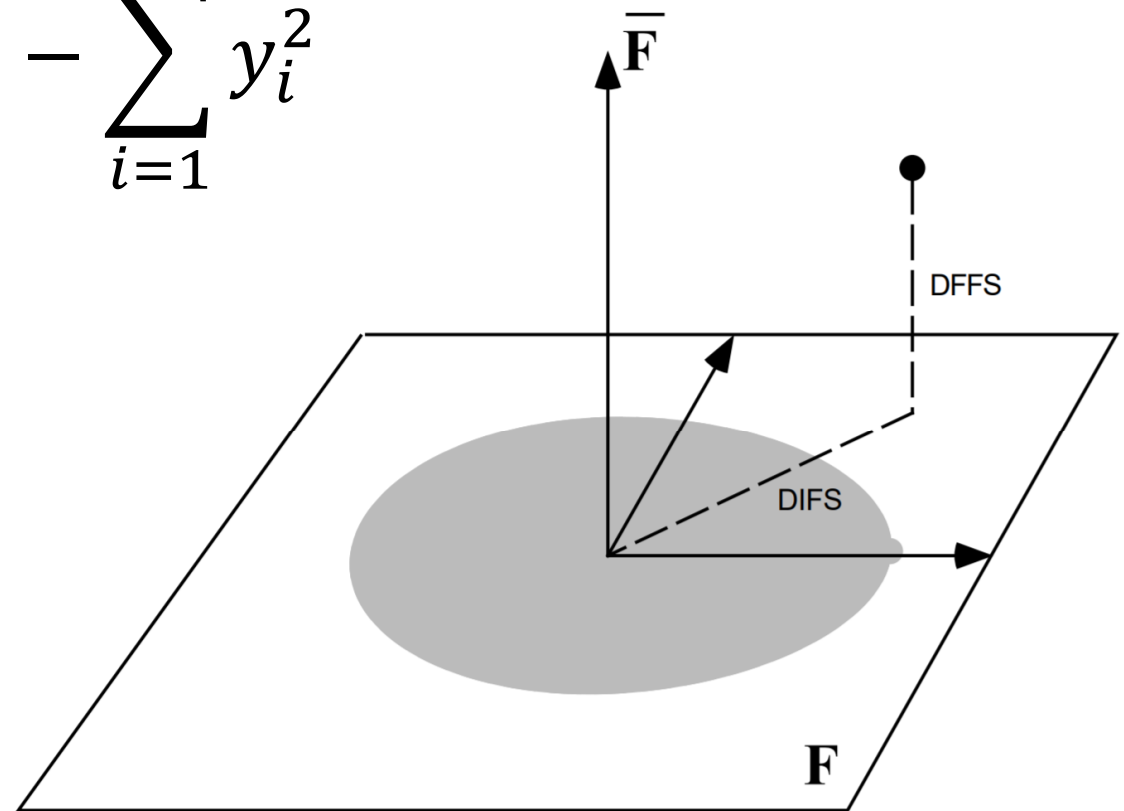


Distance From Feature Space (DFFS)

$$\epsilon^2(\mathbf{x}) = \sum_{i=M+1}^N y_i^2 = \|\tilde{\mathbf{x}}\|^2 - \sum_{i=1}^M y_i^2$$

$$F = \{\Phi_i\}_{i=1}^M$$

$$\bar{F} = \{\Phi_i\}_{i=M+1}^N$$



Maximum Likelihood (ML)



$$g(\mathbf{x}) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}\right)$$

Rewriting the gaussian to a Likelihood:

$$\mu - x = \phi_i^T \tilde{\mathbf{x}} = y_i \quad \sigma^2 = \lambda_i$$

$$P(\mathbf{x}|\mathbf{\Omega}) = \frac{1}{(2\pi)^{N/2} \prod_{i=1}^N \lambda_i^{1/2}} \exp\left(-\frac{1}{2} \sum_{i=1}^N \frac{y_i^2}{\lambda_i}\right)$$

Maximum Likelihood (ML)



$$P(\mathbf{x}|\mathbf{\Omega}) = \frac{1}{(2\pi)^{N/2} \prod_{i=1}^N \lambda_i^{1/2}} \exp\left(-\frac{1}{2} \sum_{i=1}^N \frac{y_i^2}{\lambda_i}\right)$$

$$\hat{P}(\mathbf{x}|\mathbf{\Omega}) = P_F(\mathbf{x}|\mathbf{\Omega}) \cdot \hat{P}_F(\mathbf{x}|\mathbf{\Omega})$$

$$\hat{P}(\mathbf{x}|\mathbf{\Omega}) = \frac{\exp\left(-\frac{1}{2} \sum_{i=1}^M \frac{y_i^2}{\lambda_i}\right)}{(2\pi)^M \prod_{i=1}^M \lambda_i^{1/2}} \cdot \frac{\exp\left(-\frac{\epsilon^2(\mathbf{x})}{2\rho}\right)}{(2\pi\rho)^{(N-M)/2}}, \quad \rho^* = \frac{1}{N-M} \sum_{i=M+1}^N \lambda_i$$



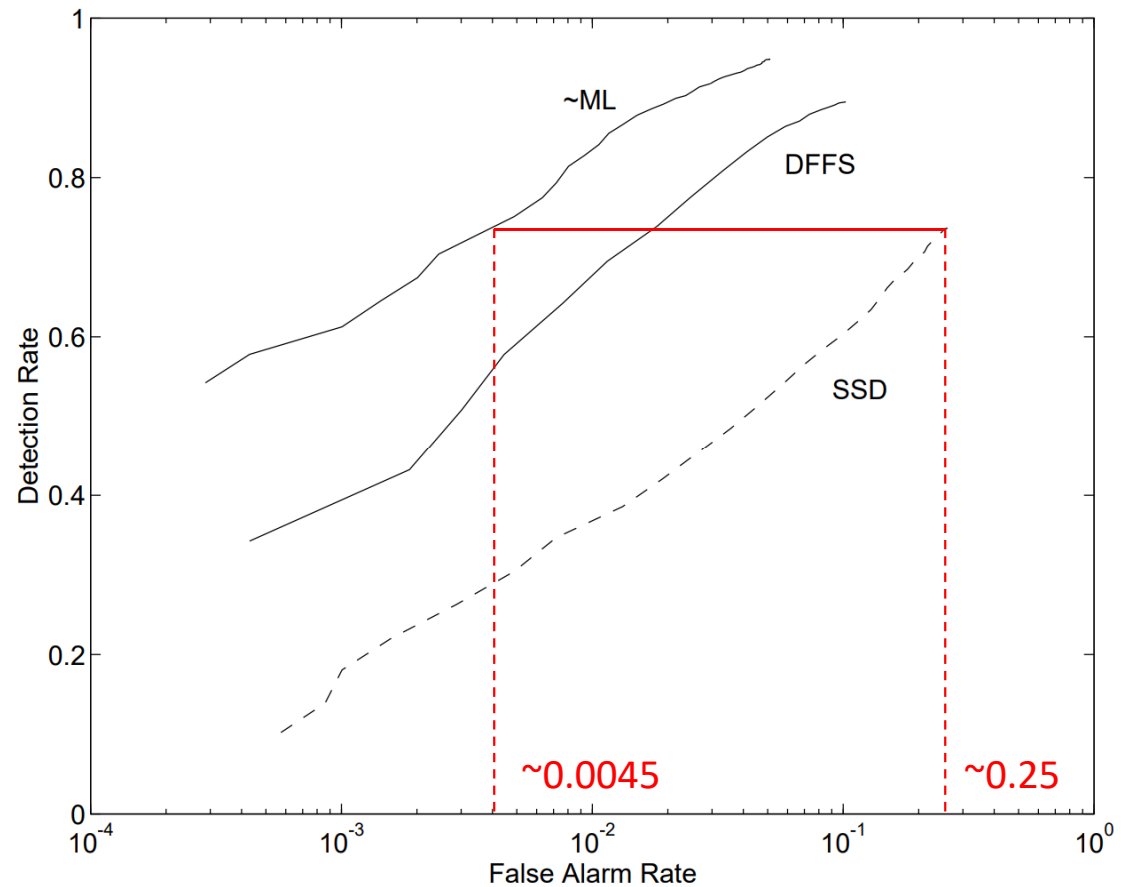
Results I

Eigenvectors based on $\sim 7,600$ “mugshots”

Test images analyzed $\sim 7,000$

5 dimension principal subspace for DFFS & ML

- ML detector exhibits best detection vs. false-alarm trade-off
- ML detector yields highest detection rate (of 95%)
- ML has a false-alarm rate nearly 2 orders of magnitudes lower than SSD





Example w 8 dim. Principal Subspace

ϕ_1 ϕ_2 ϕ_3 ϕ_4 ϕ_5 ϕ_6 ϕ_7 ϕ_8



$$\Phi_8^T \tilde{x} = y_8 = [\omega_1, \dots, \omega_8]$$



JPEG reconstruction
using 5x more data
than Eigenvector
reconstruction



Summary & what's next...



What they learned back in 1995 @ MIT:

- Eigenspace decomposition & PCA for dimensional reduction
- Estimation of density functions of high-dimensional image space
- Maximum likelihood method for object detection

What they recommended for further studies:

A Bayesian prior to improve the false-alarm rate.

Ω represents different class objects (requires new training data), not only faces. This will improve/reduce false-positives.

$$P(\Omega_i|\mathbf{x}) = \frac{P(\mathbf{x}|\Omega_i) \cdot P(\Omega_i)}{\sum_{j=1}^n P(\mathbf{x}|\Omega_j) \cdot P(\Omega_j)}$$