

# ***Laser System Status***

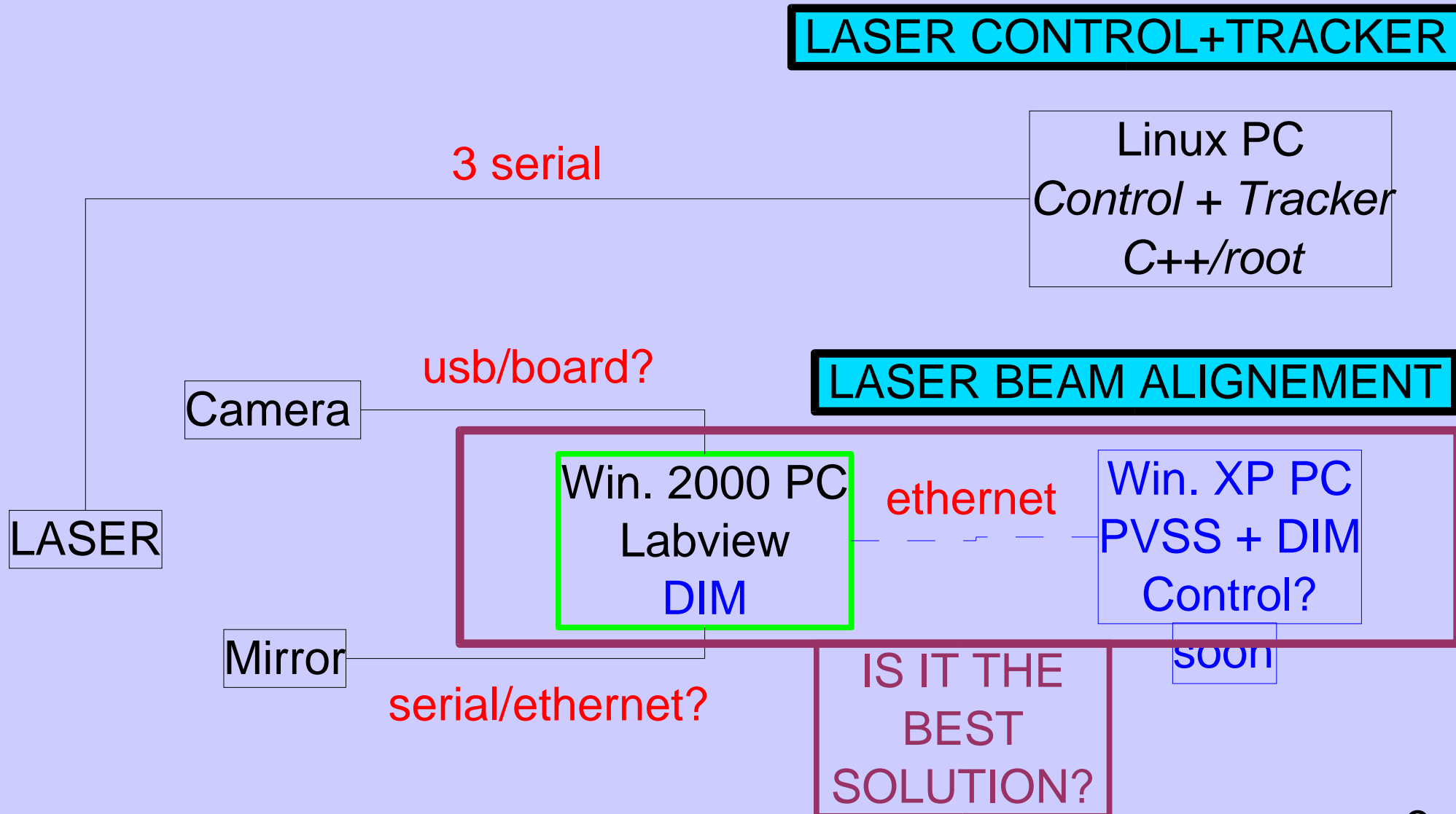
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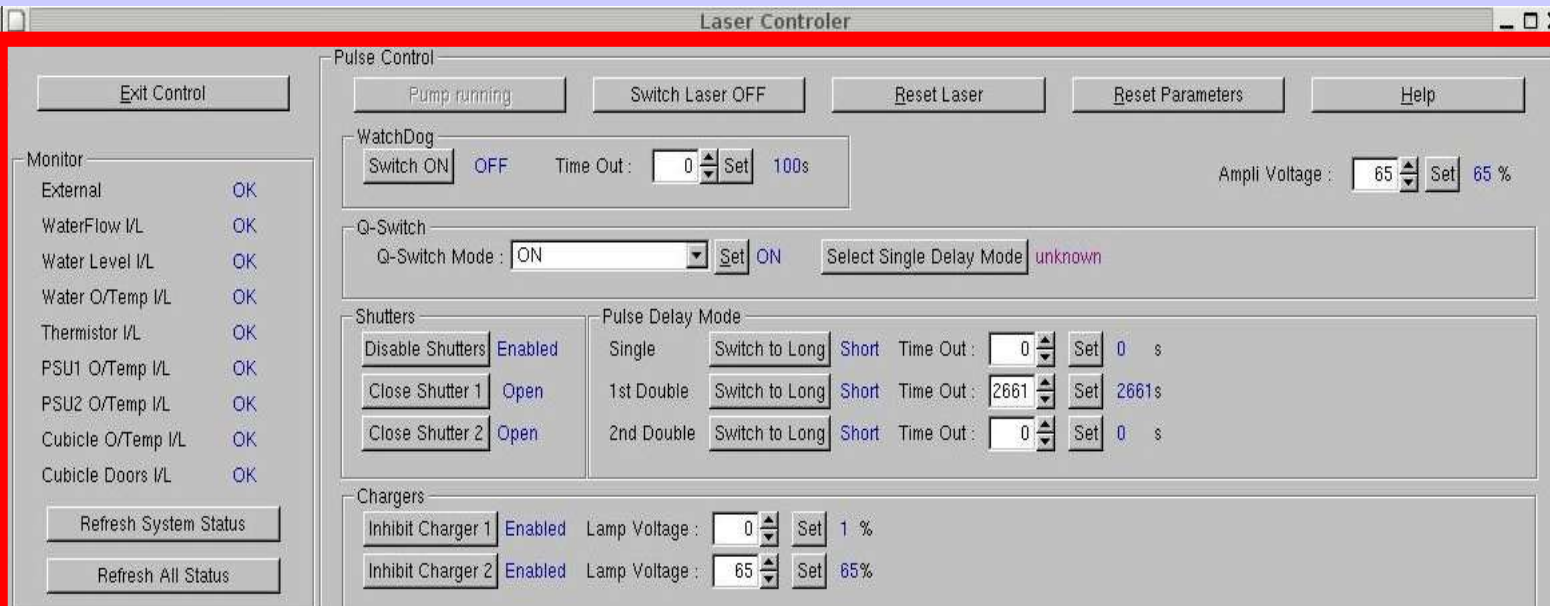
# *Outlines*

- Laser Setup at Niels Bohr Institute
- Laser Control and Tracker
- Laser beam alignment issue
- Open questions
- Conclusion

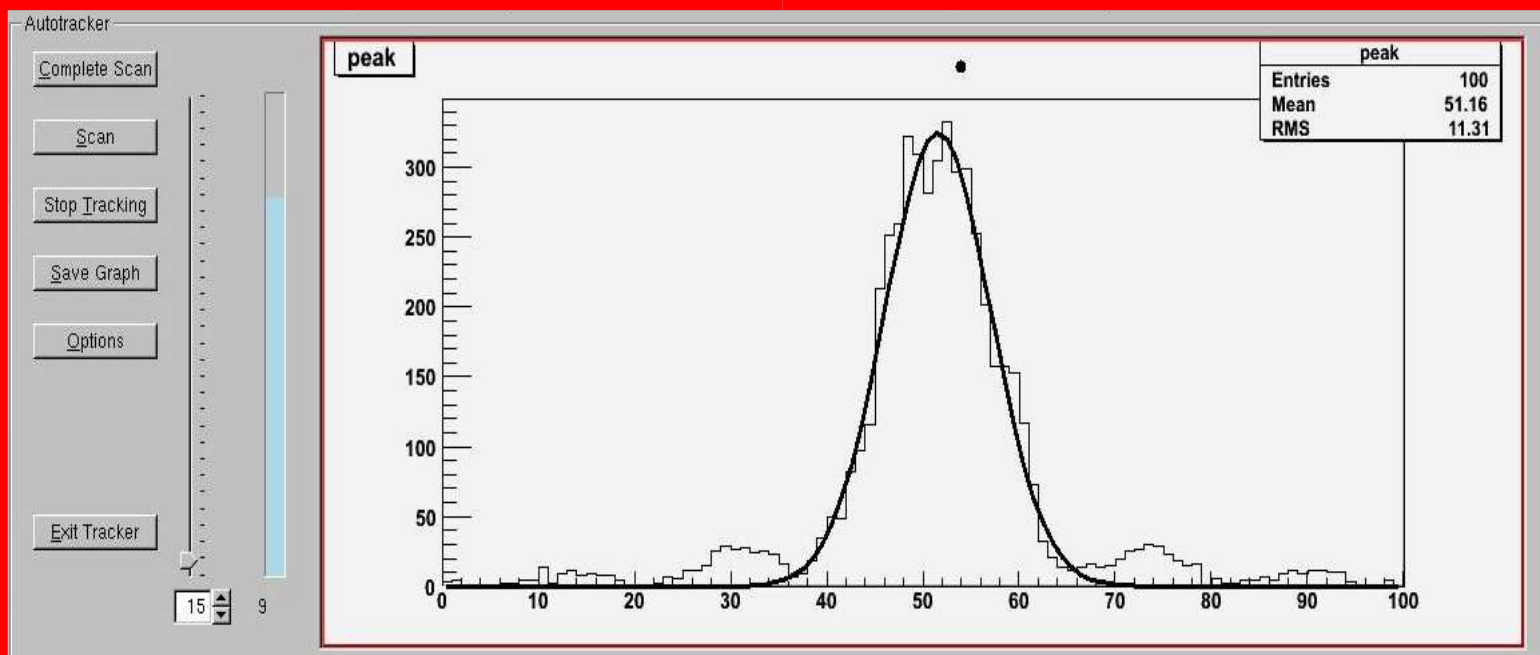
# Laser Setup at NBI



# Laser Control+Tracker



Laser Control



Laser Tracker

# *Laser Control+Tracker*

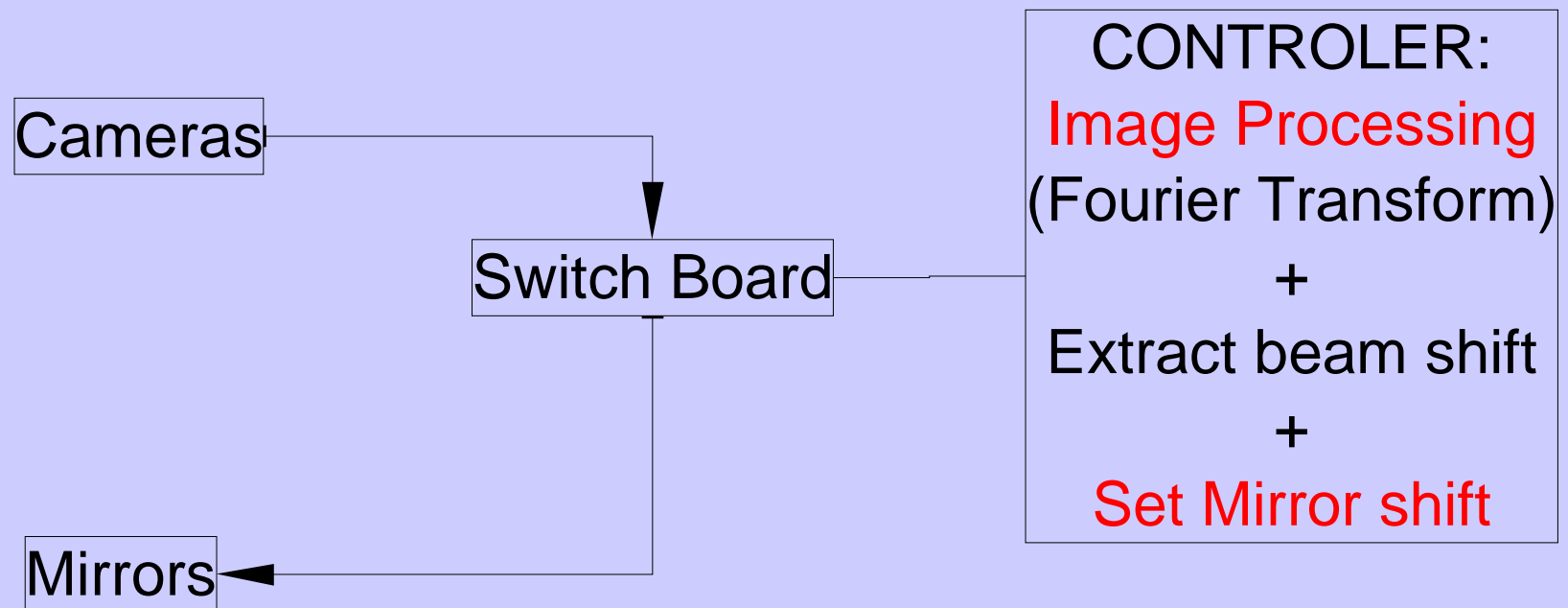
ONE DEDICATED PC  
AND  
DIRECT COMMUNICATION TO THE LASER

- Controls
  - Pump ON
  - Laser ON/OFF
  - Shutters Open/Close
  - Q-switch Trigger
  - Set Parameters:
    - Amplification Voltage
    - Trigger method...
- Monitors
  - Water temperature...
- Tracker:
  - 532 nm to 266 nm optimized by crystal angle
- Loop:
  - Monitor Gain
  - Adjust the angle

# *Mirrors and Cameras*

NEED ONE DEDICATED PC  
AND  
DIRECT COMMUNICATION

- ◆ Aim: automatic alignment of the laser beam thanks to cameras and mirrors



# *Open questions*

c++/root VS PVSS  
Processing VS Monitoring

- Laser dos drivers ported to linux.
- Laser Control with PVSS?
  - Read status / Set parameters.
- Laser Tracker with PVSS?
  - c++ algorithm portable to PVSS?
- Image processing with PVSS?
- Drivers issues for Laser, Camera, Mirror under linux, Labview, Windows

# *Conclusion*

- Laser Control + Tracker are working
- First good tests on image processing
- Work done under linux and c++/root code
- Need to choose tools : Labview, c++/root, PVSS