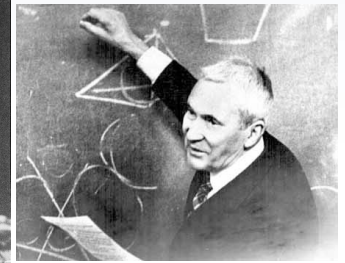
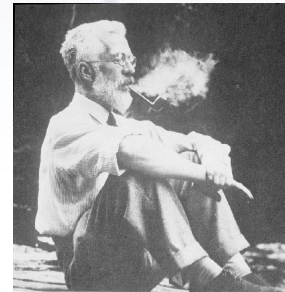
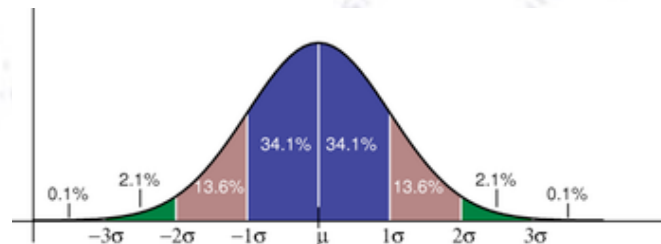


# Applied Statistics

## Probability Density Functions (PDFs)

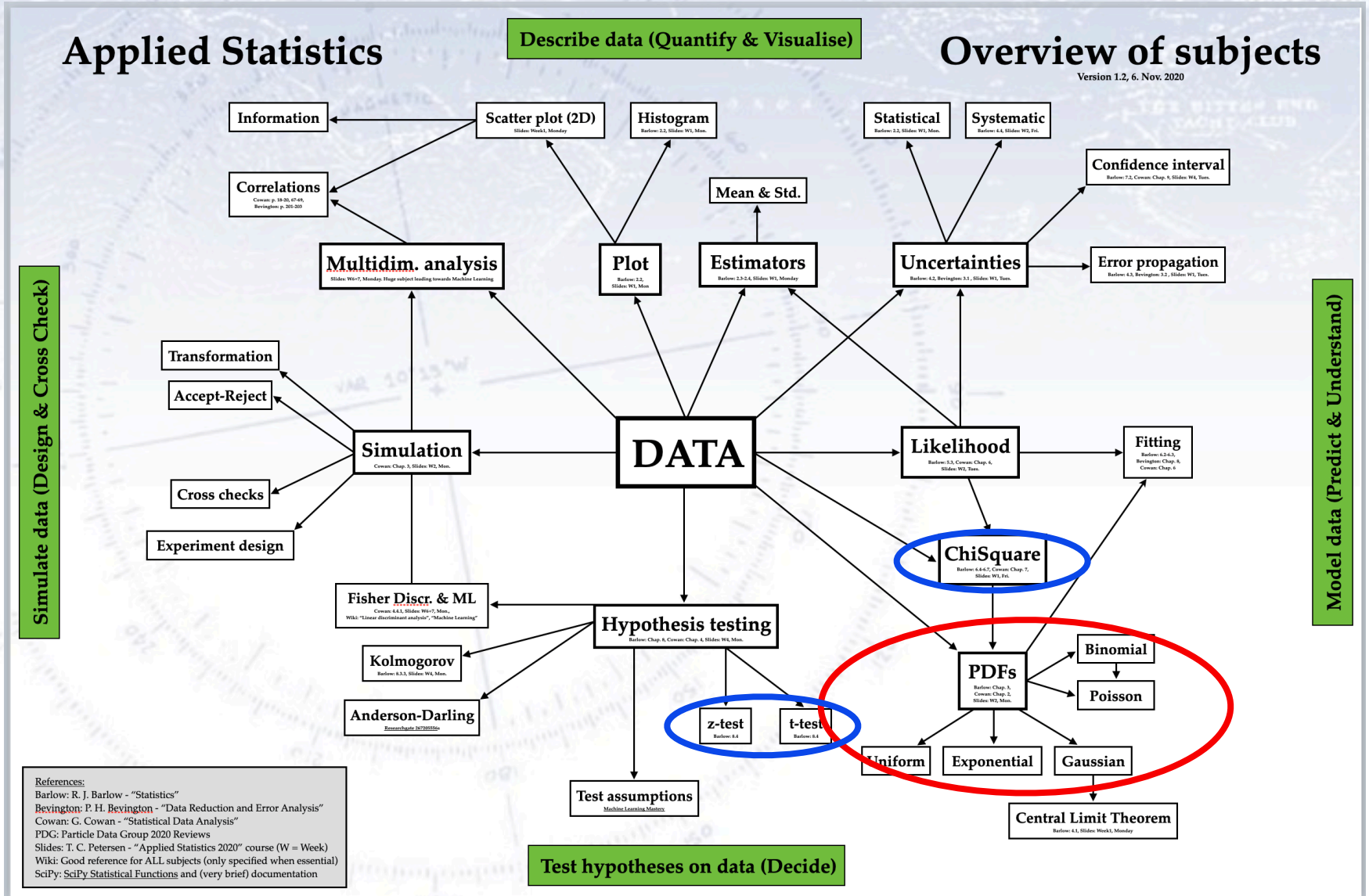


Troels C. Petersen & Mathias L. Heltberg (NBI)



*"Statistics is merely a quantisation of common sense"*

# Probability Density Functions



References:  
 Barlow: R. J. Barlow - "Statistics"  
 Bevington: P. H. Bevington - "Data Reduction and Error Analysis"  
 Cowan: G. Cowan - "Statistical Data Analysis"  
 PDG: Particle Data Group 2020 Reviews  
 Slides: T. C. Petersen - "Applied Statistics 2020" course (W = Week)  
 Wiki: Good reference for ALL subjects (only specified when essential)  
 SciPy: SciPy Statistical Functions and (very brief) documentation

# Probability Density Functions

A Probability Density Function (PDF)  $f(x)$  describes the probability of an outcome  $x$ :

*probability to observe  $x$  in the interval  $[x, x+dx] = f(x) dx$*

PDFs are required to be normalised:

$$\int_S f(x) dx = 1$$

The expectation value (aka. mean) and the variance (i.e. standard deviation squared) are then defined as follows:

$$\mu = \int_{-\infty}^{\infty} x f(x) dx$$

$$\sigma^2 = \int_{-\infty}^{\infty} (x - \mu)^2 f(x) dx$$

# Probability Density Functions

Just a word on the probability lingo:

In the literature it is often we use large letters for a random variable  $X$ . This means an *outcome* for an event! If I roll a die, we say that  $X$  takes on values in  $\{1,2,3,4,5,6\}$ .

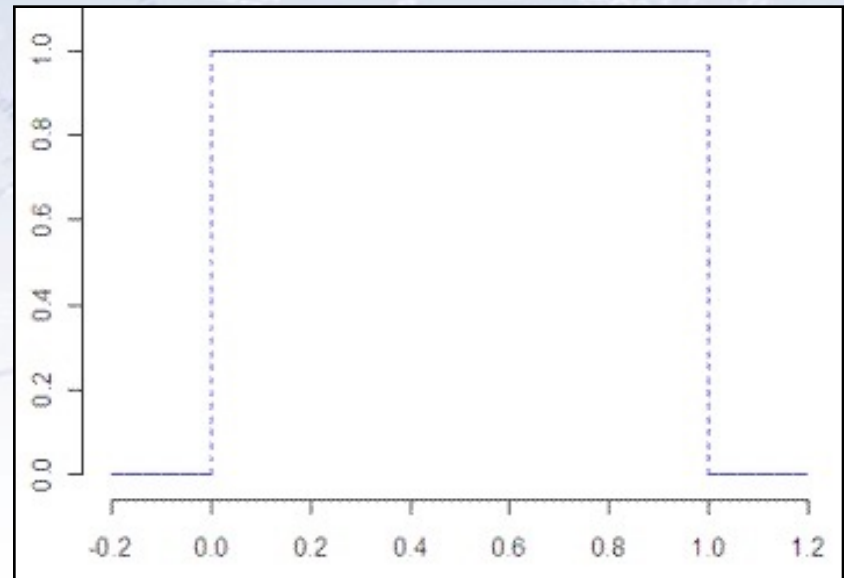
Now the small letters  $x$ , is a normal variable that is a real number. So we could write:  $P(X < x)$ , which translated means that we calculate the probability that in one event, we obtain a variable with the value smaller than the real value  $x$ .

# Probability Density Functions

Example:

Consider a uniform distribution:

$$f(x) = \begin{cases} 1 & x \in [0, 1] \\ 0 & \textit{else} \end{cases}$$



Calculating the mean and width:

$$\mu = \int_{-\infty}^{\infty} x f(x) dx = \int_0^1 x dx = \left[ \frac{1}{2} x^2 \right]_0^1 = \frac{1}{2}$$

$$\sigma^2 = \int_{-\infty}^{\infty} (x - \mu)^2 f(x) dx = \int_0^1 \left(x - \frac{1}{2}\right)^2 dx =$$

$$\left[ \frac{1}{3} x^3 - \frac{1}{2} x^2 + \frac{1}{4} x \right]_0^1 = \frac{1}{3} - \frac{1}{2} + \frac{1}{4} = \frac{1}{12}$$

# Probability Density Functions

The number of PDFs is infinite, and nearly so is the list of known ones:

## Discrete distributions [\[ edit source | edit beta \]](#)

### With finite support [\[ edit source | edit beta \]](#)

- The Bernoulli distribution, which takes value 1 with probability  $p$ .
- The Rademacher distribution, which takes value  $\pm 1$  with equal probability.
- The binomial distribution, which describes the number of successes in a fixed number of independent trials.
- The beta-binomial distribution, which describes the distribution of the number of successes in a fixed number of trials when the probability of success is itself a random variable.
- The degenerate distribution at  $x_0$ , where  $X$  is certain to take the value  $x_0$ .
- The discrete uniform distribution, where all elements of a finite set are equally likely.
- The hypergeometric distribution, which describes the number of successes in a fixed number of trials without replacement.
- The Poisson binomial distribution, which describes the number of successes in a fixed number of trials with varying probabilities.
- Fisher's noncentral hypergeometric distribution
- Wallenius' noncentral hypergeometric distribution
- Benford's law, which describes the frequency of the digits in a set of numbers.

### With infinite support [\[ edit source | edit beta \]](#)

- The beta negative binomial distribution
- The Boltzmann distribution, a discrete distribution in statistical mechanics. Special cases include:
  - The Gibbs distribution
  - The Maxwell-Boltzmann distribution
- The Borel distribution
- The extended negative binomial distribution
- The extended hypergeometric distribution
- The generalized log-series distribution
- The generalized normal distribution
- The geometric distribution, a discrete distribution with infinite support.
- The hypergeometric distribution
- The logarithmic (series) distribution
- The negative binomial distribution or Pascal distribution
- The parabolic fractal distribution
- The Poisson distribution, which describes a very large number of independent trials with a small probability of success. Special cases include:
  - The Conway-Maxwell-Poisson distribution, a two-parameter generalization of the Poisson distribution.
  - The Polya-Eggenberger distribution
- The Skellam distribution, the distribution of the difference of two independent Poisson random variables.
- The skew elliptical distribution
- The skew normal distribution
- The Yule-Simon distribution
- The zeta distribution has uses in applied statistics
- Zipf's law or the Zipf distribution. A discrete power-law distribution.
- The Zipf-Mandelbrot law is a discrete power-law distribution.

## Continuous distributions [\[ edit source | edit beta \]](#)

### Supported on a bounded interval [\[ edit source | edit beta \]](#)

- The Arcsine distribution on  $[a, b]$ , which is a special case of the beta distribution.
- The Beta distribution on  $[0, 1]$ , of which the uniform distribution is a special case.
- The Lognormal distribution on  $(0, \infty)$ .
- The Dirac delta function although not strictly a function, but the notation treats it as if it were a continuous function.
- The continuous uniform distribution on  $[a, b]$ , when  $a < b$ .
  - The rectangular distribution is a uniform distribution on  $[a, b]$ .
- The Irwin-Hall distribution is the distribution of the sum of  $n$  independent uniform random variables.
- The Kent distribution on the three-dimensional sphere.
- The Kumaraswamy distribution is as versatile as the beta distribution.
- The logarithmic distribution (continuous)
- The PERT distribution is a special case of the beta distribution.
- The raised cosine distribution on  $[\mu - s, \mu + s]$
- The reciprocal distribution
- The triangular distribution on  $[a, b]$ , a special case of the beta distribution.
- The truncated normal distribution on  $[a, b]$ .
- The U-quadratic distribution on  $[a, b]$ .
- The von Mises distribution on the circle.
- The von Mises-Fisher distribution on the  $N$ -dimensional sphere.
- The Wigner semicircle distribution is important in quantum mechanics.

### Supported on semi-infinite intervals, usually $[0, \infty)$

- The Beta prime distribution
- The Birnbaum-Saunders distribution, also known as the Rayleigh distribution
- The chi distribution
  - The noncentral chi distribution
- The chi-squared distribution, which is the sum of the squares of  $k$  independent standard normal random variables.
  - The inverse-chi-squared distribution
  - The noncentral chi-squared distribution
  - The Scaled-inverse-chi-squared distribution
- The Dagum distribution
- The exponential distribution, which describes the time between events in a Poisson process.
- The F-distribution, which is the distribution of the ratio of two chi-squared variates which are not independent.
- The noncentral F-distribution
- Fisher's z-distribution
- The folded normal distribution
- The Fréchet distribution
- The Gamma distribution, which describes the time between events in a Poisson process.
  - The Erlang distribution, which is a special case of the gamma distribution.
  - The inverse-gamma distribution
- The generalized Pareto distribution
- The Gamma/Gompertz distribution
- The Gompertz distribution
- The half-normal distribution

- Hotelling's T-squared distribution
- The inverse Gaussian distribution, also known as the Wald distribution
- The Lévy distribution
- The log-Cauchy distribution
- The log-gamma distribution
- The log-Laplace distribution
- The log-logistic distribution
- The log-normal distribution, describing variability in many natural phenomena
- The Mittag-Leffler distribution
- The Nakagami distribution
- The Pareto distribution, or "power law" distribution
- The Pearson Type III distribution
- The phased bi-exponential distribution is common in pharmacokinetics
- The phased bi-Weibull distribution
- The Rayleigh distribution
- The Rayleigh mixture distribution
- The Rice distribution
- The shifted Gompertz distribution
- The type-2 Gumbel distribution
- The Weibull distribution or Rosin-Rammler distribution, used in grinding, milling and crushing operations.

### Supported on the whole real line [\[ edit source | edit beta \]](#)

- The Behrens-Fisher distribution, which arises in the analysis of variance
- The Cauchy distribution, an example of a heavy-tailed distribution
- The resonance energy distribution, impact and fracture
- Chernoff's distribution
- The Exponentially modified Gaussian distribution
- The Fisher-Tippett, extreme value, or log-normal distribution
  - The Gumbel distribution, a special case of the Fisher-Tippett distribution
- Fisher's z-distribution
- The generalized logistic distribution
- The generalized normal distribution
- The geometric stable distribution
- The Holtmark distribution, an example of a heavy-tailed distribution
- The hyperbolic distribution
- The hyperbolic secant distribution
- The Johnson SU distribution
- The Landau distribution
- The Laplace distribution
- The Lévy skew alpha-stable distribution or Lévy distribution, Lévy distribution and normal distribution
- The Linnik distribution
- The logistic distribution
- The map-Airy distribution
- The normal distribution, also called the Gaussian distribution, independent, identically distributed variables
- The Normal-exponential-gamma distribution
- The Pearson Type IV distribution (see Pearson distribution)
- The skew normal distribution

- Student's t-distribution, useful for estimating the mean of a normal distribution with unknown variance.
  - The noncentral t-distribution
- The type-1 Gumbel distribution
- The Voigt distribution, or Voigt profile, is the convolution of a Gaussian and a Lorentzian distribution.
- The Gaussian minus exponential distribution is used in queueing theory.

### With variable support [\[ edit source | edit beta \]](#)

- The generalized extreme value distribution has a shape parameter
- The generalized Pareto distribution has a shape parameter
- The Tukey lambda distribution is either supported on a bounded interval or on the whole real line
- The Wakeby distribution

### Mixed discrete/continuous distributions [\[ edit source | edit beta \]](#)

- The rectified Gaussian distribution replaces the negative part of a Gaussian distribution with a discrete distribution.

### Joint distributions [\[ edit source | edit beta \]](#)

For any set of independent random variables the joint distribution is the product of the individual distributions.

### Two or more random variables on the same space

- The Dirichlet distribution, a generalization of the multinomial distribution
- The Ewens's sampling formula is a probability distribution on permutations
- The Balding-Nichols model
- The multinomial distribution, a generalization of the binomial distribution
- The multivariate normal distribution, a generalization of the normal distribution
- The negative multinomial distribution, a generalization of the negative binomial distribution
- The generalized multivariate log-gamma distribution

### Matrix-valued distributions [\[ edit source | edit beta \]](#)

- The Wishart distribution
- The inverse-Wishart distribution
- The matrix normal distribution
- The matrix t-distribution

### Non-numeric distributions [\[ edit source | edit beta \]](#)

- The categorical distribution
- newton distribution

### Miscellaneous distributions [\[ edit source | edit beta \]](#)

- The Cantor distribution
- The generalized logistic distribution family
- The Pearson distribution family
- The phase-type distribution

And surely more!

# Probability Density Functions

The number of PDFs is infinite, and nearly so is the list of known ones:

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- The discrete uniform distribution, where all elements of a finite set are equally likely.
- The hypergeometric distribution, which describes the number of successes in a fixed number of trials, where the probability of success is a random variable.
- The Poisson binomial distribution, which describes the number of successes in a fixed number of trials, where the probability of success is a random variable.
- Fisher's noncentral hypergeometric distribution
- Wallenius' noncentral hypergeometric distribution

## Continuous distributions [ edit source | edit beta ]

### Supported on a bounded interval [ edit source | edit beta ]

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- The type-I Gumbel distribution
- The Voigt distribution, or Voigt profile, is the convolution of a Gaussian and a Lorentzian distribution
- The Gaussian minus exponential distribution is used in queueing theory

### With variable support [ edit source | edit beta ]

- The generalized extreme value distribution has three types
- The generalized Pareto distribution has a support that is a function of the parameter
- The Tukey lambda distribution is either supported on a bounded interval or on the real line
- The Wakeby distribution

### Mixed discrete/continuous distributions [ edit source | edit beta ]

- The rectified Gaussian distribution replaces the negative part of a Gaussian distribution with a discrete distribution

### Joint distributions [ edit source | edit beta ]

For any set of independent random variables the joint distribution is the product of the individual distributions.

<https://docs.scipy.org/doc/scipy/reference/stats.html>

- The Gibbs distribution
- The Maxwell-Boltzmann distribution
- The Borel distribution
- The extended negative binomial distribution
- The extended hypergeometric distribution
- The generalized log-series distribution
- The generalized normal distribution
- The geometric distribution, a discrete distribution with a constant hazard rate
- The hypergeometric distribution
- The logarithmic (series) distribution
- The negative binomial distribution or Pascal distribution
- The parabolic fractal distribution
- The Poisson distribution, which describes a very large number of discrete events, the hyper-Poisson, the general Poisson distribution
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And surely more!

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- The Tukey lambda distribution is either suppor
- The Wakeby distribution

*"Essentially, all models are wrong, but some are useful"*

[George E. P. Box, British Statistician, 1919-2013]

- The chi-squared distribution, which is the sum of t
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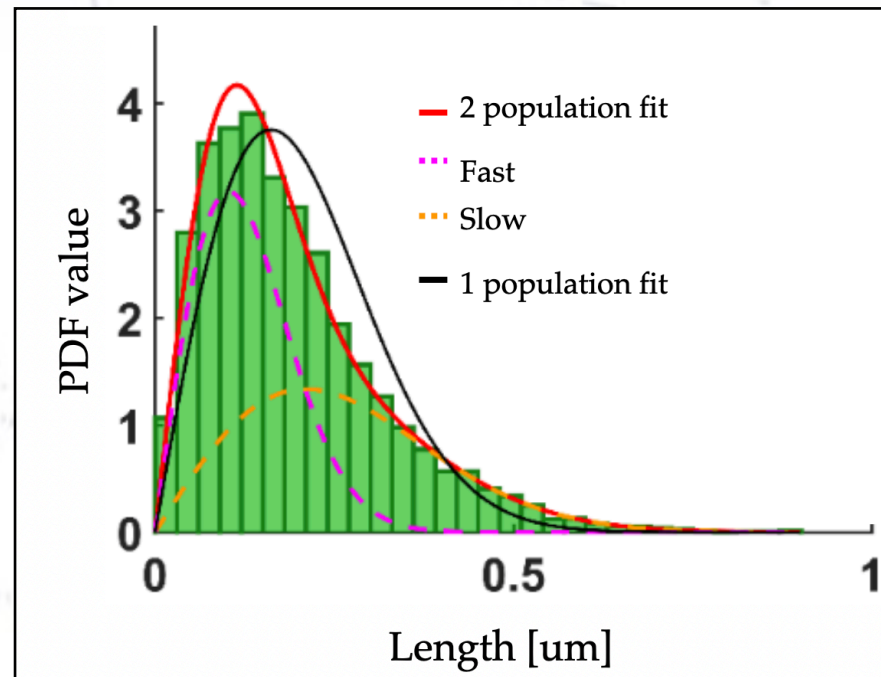
And surely more!



# Why PDF's

We basically want to extract information about the system we are studying based on the data. Why not just estimate a mean and a variance and call it a day?

PDFs makes us able to ask what the *probability* of a certain event given the underlying model - and this allows for new discoveries!



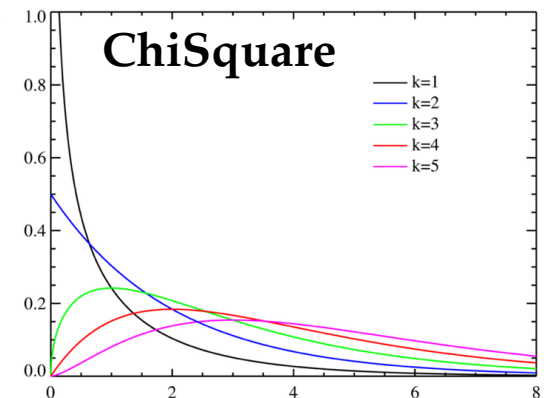
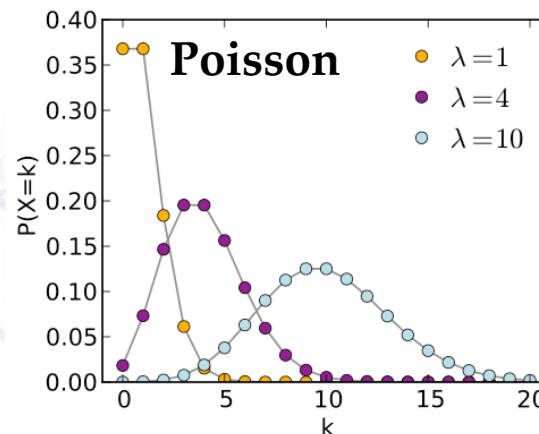
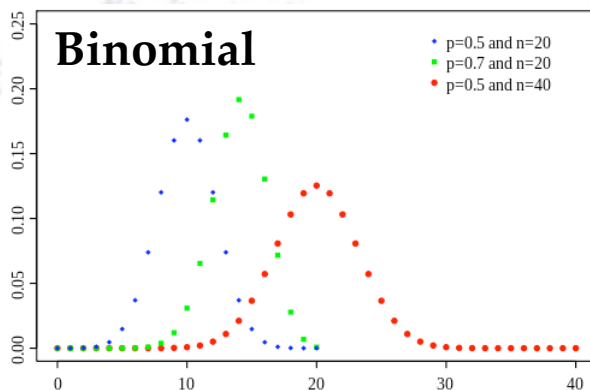
# Probability Density Functions

An almost complete list of those we will deal with in this course is:

- **Gaussian** (aka. Normal)
- **Poisson**
- **Binomial** (and also Multinomial)
- Students t-distribution
- Uniform
- ChiSquare
- Exponential
- Error function (integral of Gaussian)

See Barlow chap.3  
and Cowan chap.2

You should already know most of these, and the rest will be explained.



# Binomial, Poisson, Gaussian

$$f(n; N, p) = \frac{N!}{n!(N-n)!} p^n (1-p)^{N-n}$$

Given **N** trials each with **p** chance of **success**, how many **successes n** should you expect in total?

This distribution is... **Binomial:**

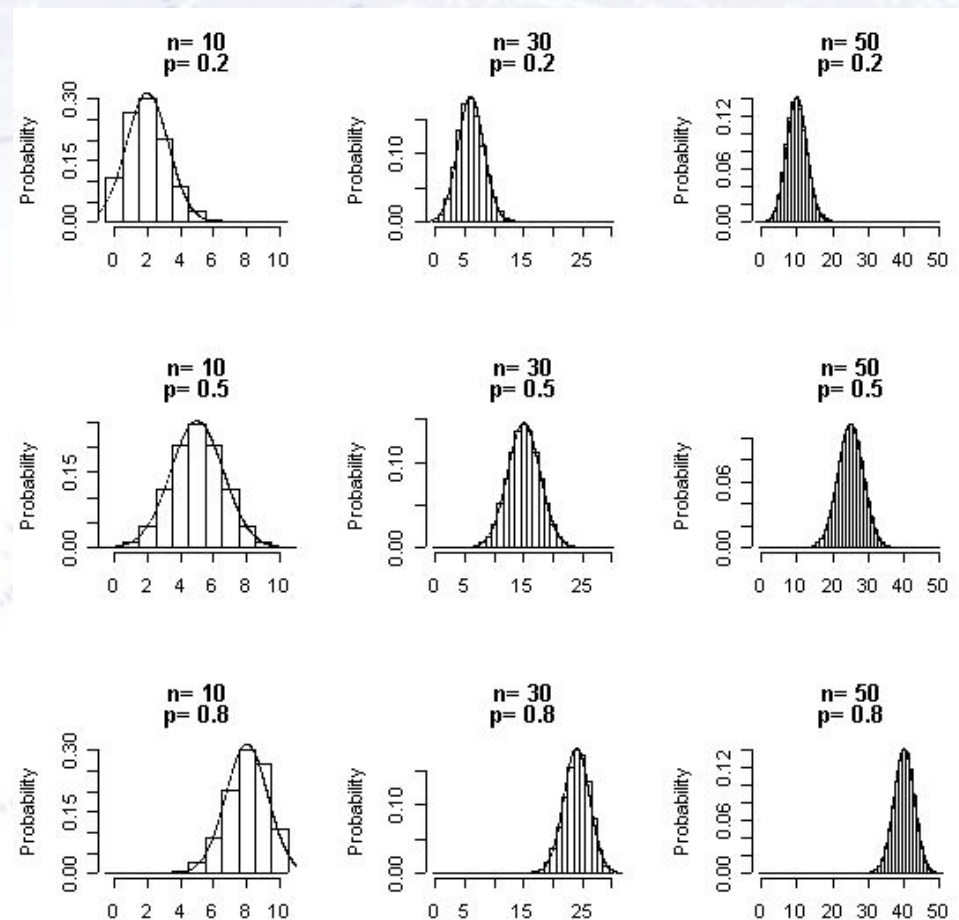
$$f(n; N, p) = \frac{N!}{n!(N-n)!} p^n (1-p)^{N-n}$$

Mean =  $Np$

Variance =  $Np(1-p)$

This means, that the error on a fraction  $f = n/N$  is:

$$\sigma(f) = \sqrt{\frac{f(1-f)}{N}}$$



# Binomial, Poisson, Gaussian

You count 100 cars, and see 15 red cars. What is your estimate of the fraction (i.e. probability) of red cars and its uncertainty?

- a)  $0.150 \pm 0.050$
- b)  $0.150 \pm 0.026$
- c)  $0.150 \pm 0.036$
- d)  $0.125 \pm 0.030$
- e)  $0.150 \pm 0.081$

From previous page: 
$$\sigma(f) = \sqrt{\frac{f(1-f)}{N}}$$

A friend tells you, that 8% of the cars on Blegdamsvej are red. What is the chance of that? Could he be right?

# Binomial, Poisson, Gaussian

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- c)  $0.150 \pm 0.036$
- d)  $0.125 \pm 0.030$
- e)  $0.150 \pm 0.081$

$$(0.150 - 0.080) / 0.036 = 1.9 \sigma$$



From previous page: 
$$\sigma(f) = \sqrt{\frac{f(1-f)}{N}}$$

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# Binomial, Poisson, Gaussian

$$f(n; N, p) = \frac{N!}{n!(N-n)!} p^n (1-p)^{N-n}$$

The binomial distribution was first introduced by the famous mathematician/physicist Jacob Bernoulli in 1713 (posthumously).

The binomial distribution basically consists of two elements: The binomial coefficient and the probabilities of  $n$  such events.

Even though a system has many outcomes, it is typically possible to refer to either “success” of “failure”.

*Assume the probability to have COVID19 is 1%. In a sample of 50 people the chance to have 1 or more infected is:  $1-p(0) = 1-0.99^{50} = 0.60$*

$$(x + y)^4 = x^4 + 4x^3y + 6x^2y^2 + 4xy^3 + y^4.$$

0:									1
1:								1	1
2:							1	2	1
3:						1	3	3	1
4:					1	4	6	4	1
5:				1	5	10	10	5	1
6:			1	6	15	20	15	6	1
7:	1	7	21	35	35	21	7	1	
8:	1	8	28	56	70	56	28	8	1

# Binomial, Poisson, Gaussian

## Requirements to be Binomial:

- Fixed number of trials,  $N$
- Independent trials.
- Only two outcomes (success / failure).
- Constant probability of success / failure.

If number of possible outcomes is more than two  $\Rightarrow$  **Multinomial distribution.**

## Examples of Binomial experiments:

- Tossing a coin 20 times counting number of tails.
- Asking 200 people if they watch sports on TV.
- Rolling a die to see if a 6 appear (Multinomial for all outcomes!).
- Asking 100 die-hards from Ehedslisten, if they would vote for Konservative at the next election!

## Examples which aren't Binomial experiments:

- Rolling a die until a 6 appears (not fixed number of trials).
- Drawing 5 cards for a poker hand (no replacement  $\Rightarrow$  not independent)

# Binomial, Poisson, Gaussian

If  $N \rightarrow \infty$  and  $p \rightarrow 0$ , but  $Np \rightarrow \lambda$  then a Binomial approaches a Poisson: (see Barlow 3.3.1)

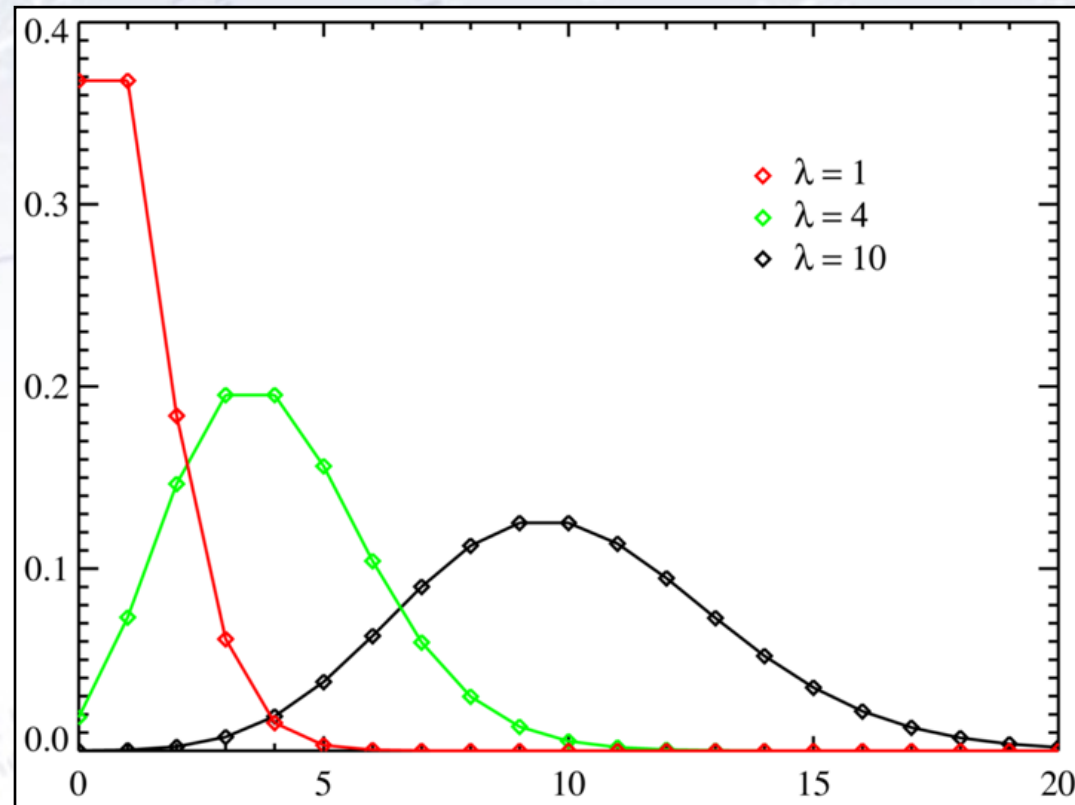
$$f(n, \lambda) = \frac{\lambda^n}{n!} e^{-\lambda}$$

In reality, the approximation is already quite good at e.g.  $N=50$  and  $p=0.1$ .

The Poisson distribution only has one parameter, namely  $\lambda$ .

Mean =  $\lambda$

Variance =  $\lambda$



So the error on a number is...

*...the square root of that number!*



# Binomial, Poisson, Gaussian

The error on a  
(Poisson) number...  
is the square root  
of that number!!!

# Binomial, Poisson, Gaussian

The error on a  
(Poisson) number.

A very useful case of this is the error to assign a bin in a histogram,  
if there is reasonable statistics ( $N_i > 5-20$ ) in each bin.

is the square root  
of that number!!!

The error on a  
(Poisson) number...  
is the square root  
of that number!!!

Note: The sum of two Poissons with  $\lambda_a$  and  $\lambda_b$  is a new Poisson with  $\lambda = \lambda_a + \lambda_b$ .  
(See Barlow pages 33-34 for proof)

# Binomial, Poisson, Gaussian

Examples of the Poisson distribution:

There are 122 deaths by horse kicks over 10 different regiments, over 20 years. What is the predicted number of deaths in a specific year?

Here we use exactly the Poisson distribution. First we estimate the mean value:

$$\mu = \frac{122}{20 * 10} = 0.61$$

This means that the probability that 0 will die is given by:

$$P(0) = e^{-0.61} \frac{0.61^0}{0!} = 0.54$$



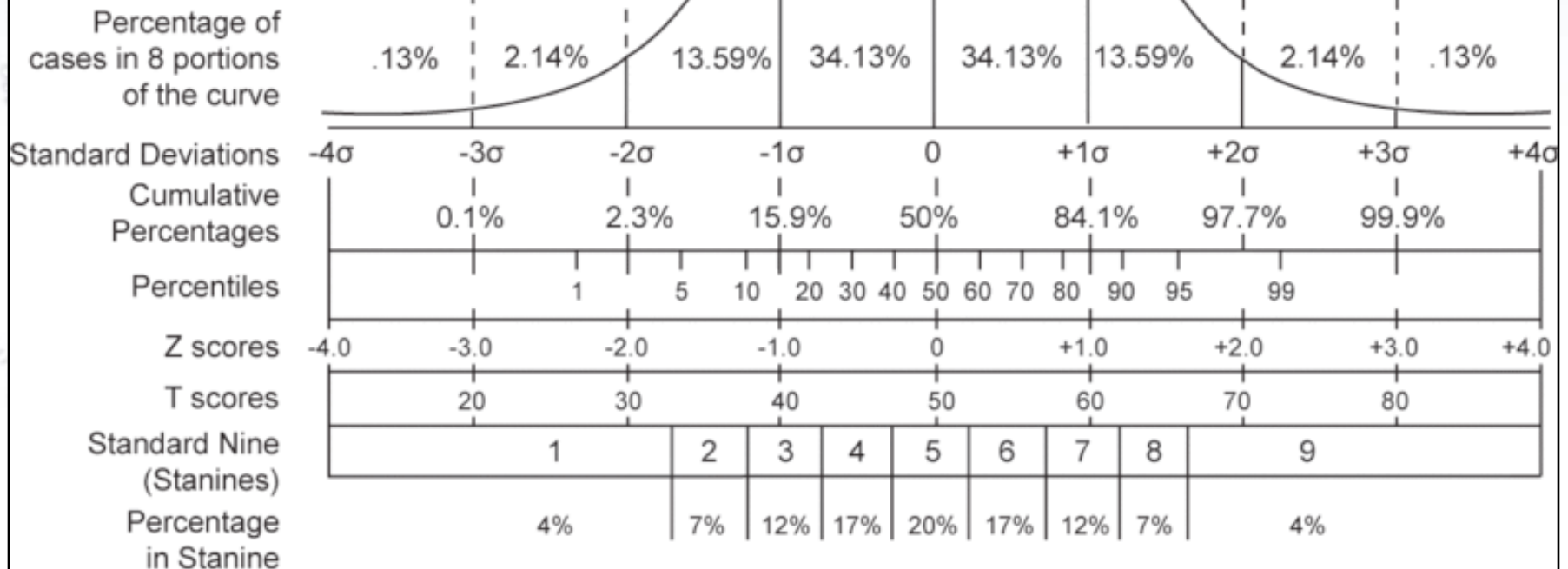
# Binomial, Poisson, Gaussian

If  $\lambda \rightarrow \infty$ , the Poisson becomes a Gaussian...

...and  $\lambda > 20$  is enough!

For proof, see  
Barlow p.40

*Normal,  
Bell-shaped Curve*



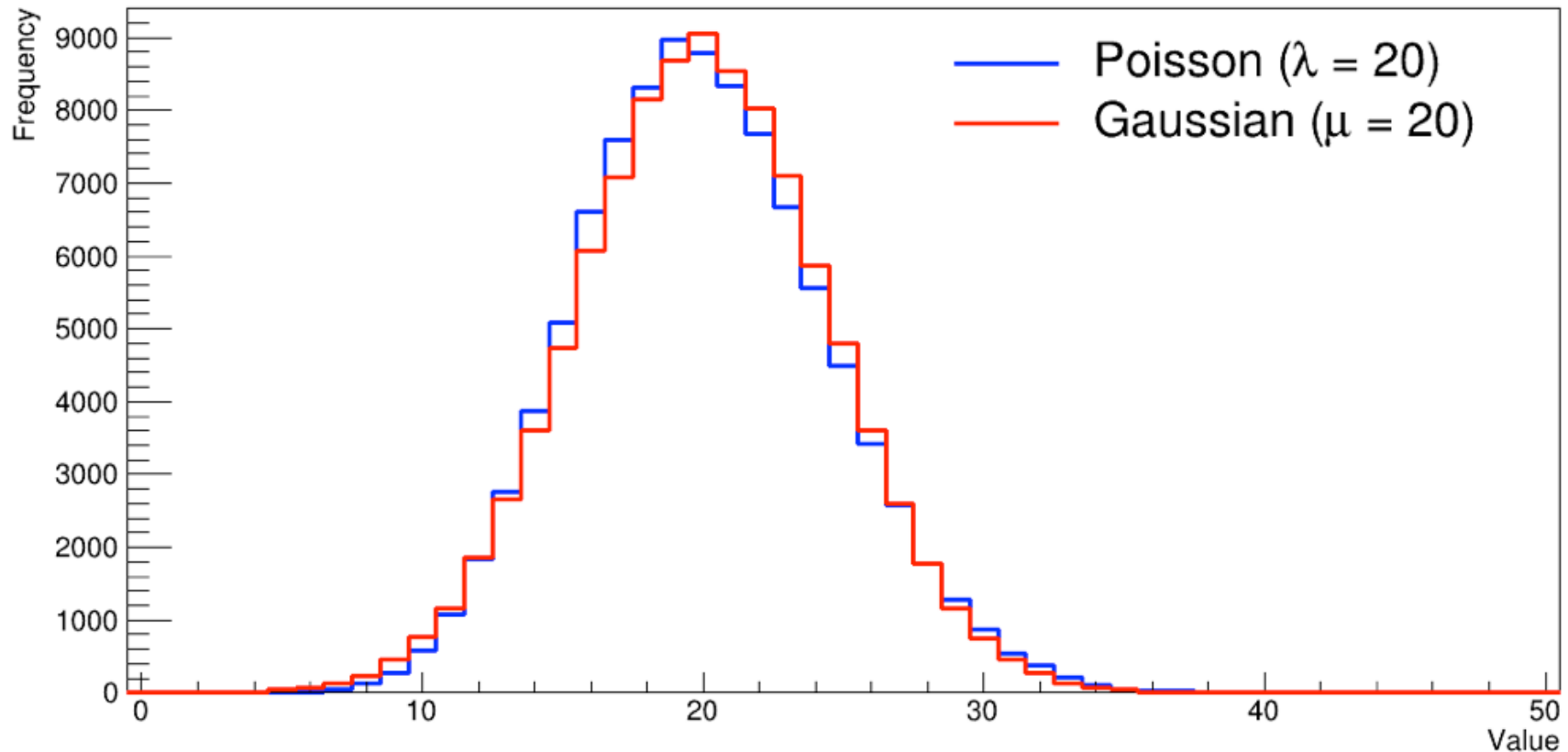
All fields encounter the Gaussian, and for this reason, its scale has many names!

# Binomial, Poisson, Gaussian

If  $\lambda \rightarrow \infty$ , the Poisson becomes a Gaussian...

...and  $\lambda > 20$  is enough!

Poisson and Gaussian distribution comparison

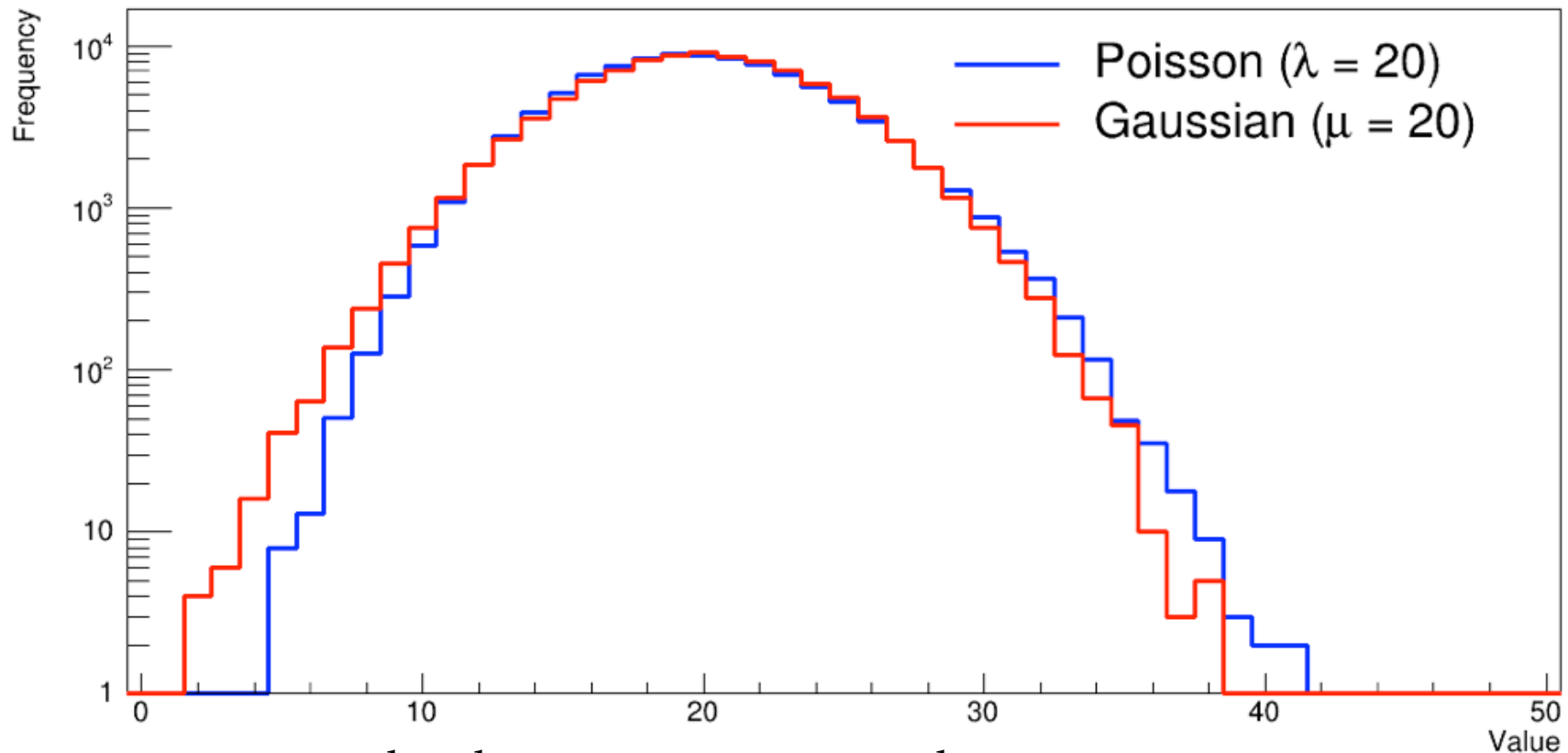


# Binomial, Poisson, Gaussian

If  $\lambda \rightarrow \infty$ , the Poisson becomes a Gaussian...

...and  $\lambda > 20$  is enough!

Poisson and Gaussian distribution comparison

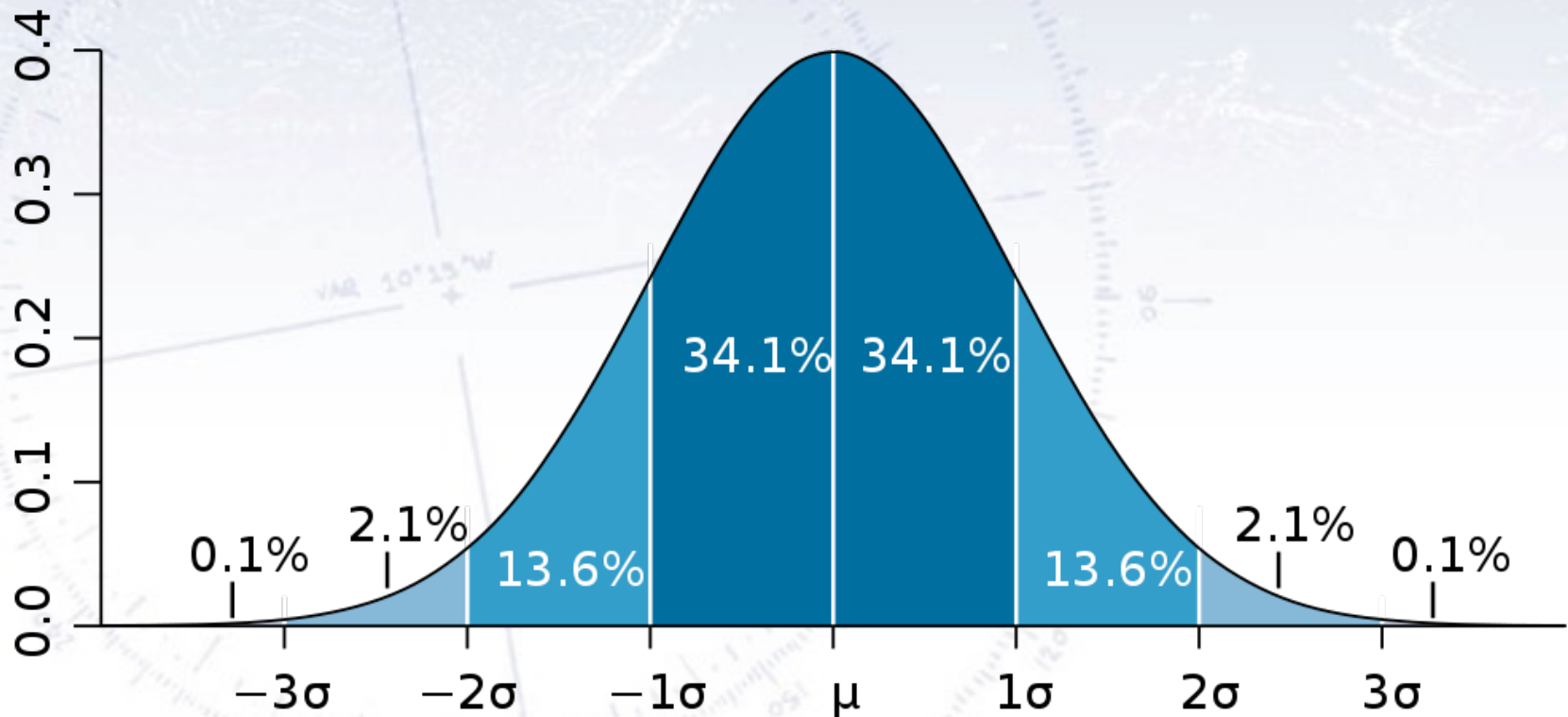


However, note that the TAILS are not quite the same!!!

This is the very reason for the difference between Chi2 and (binned) likelihood!

# Binomial, Poisson, Gaussian

*“If the Greeks had known it, they would have deified it.”*



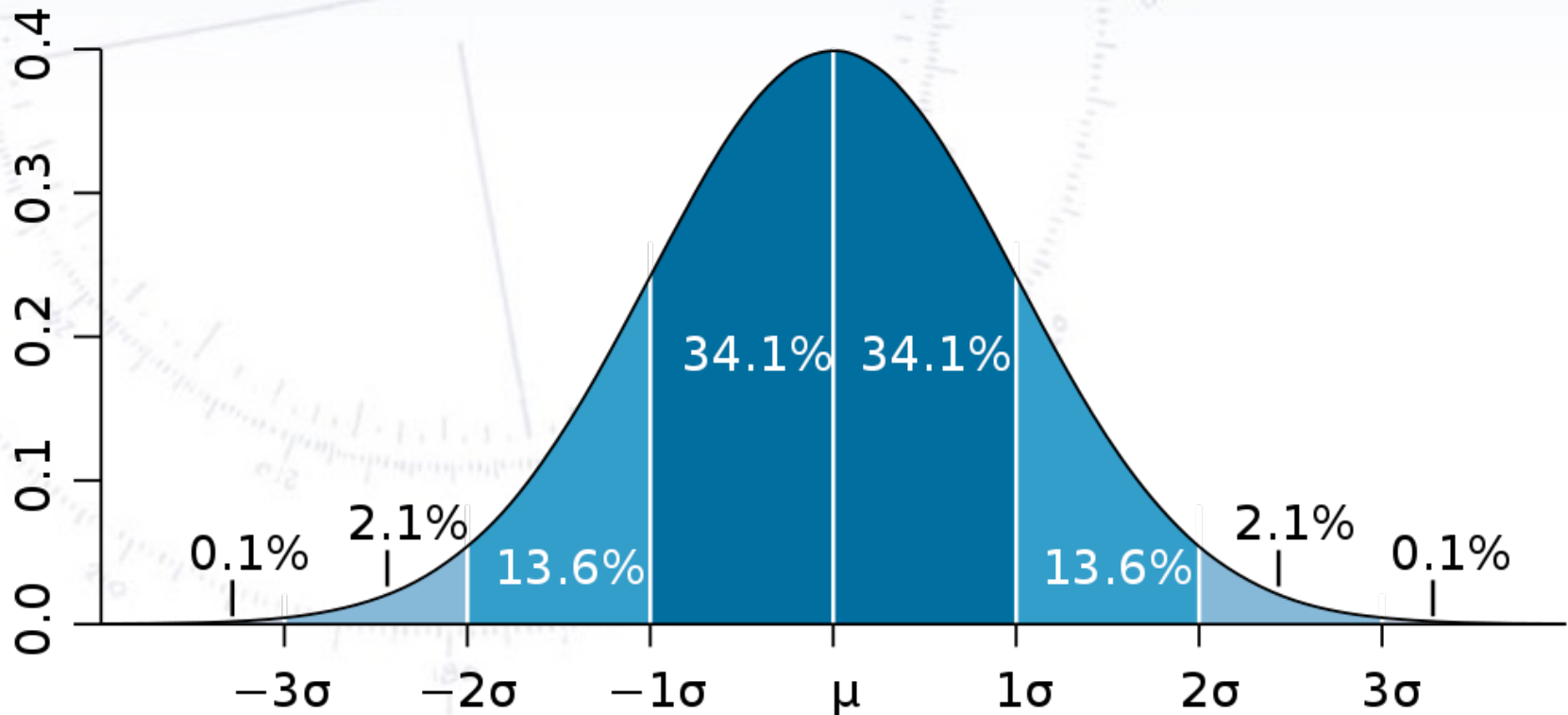
*“If the Greeks had known it, they would have deified it. It reigns with serenity and in complete self-effacement amidst the wildest confusion. **The more huge the mob and the greater the apparent anarchy, the more perfect is its sway.** It is the supreme Law of Unreason. Whenever a large sample of chaotic elements are taken in hand and marshalled in the order of their magnitude, an unsuspected and most beautiful form of regularity proves to be latent all along.” [Karl Pearson]*



# Binomial, Poisson, Gaussian

The Gaussian defines the way we consider uncertainties.

Range	Inside	Outside
$\pm 1\sigma$	<b>68 %</b>	32 %
$\pm 2\sigma$	<b>95 %</b>	5 %
$\pm 3\sigma$	<b>99.7 %</b>	0.3 %
$\pm 5\sigma$	99.99995 %	0.00005 %



# Student's t-distribution

Assume we are measuring a small sample, i.e. 5 measurements.

Now we don't even know the uncertainty on the measurements, but we assume that they are normally distributed. We can rewrite our variable of interest:

$$t = \frac{x - \mu}{\hat{\sigma}^2} = \frac{y}{\sqrt{\chi^2/n}}$$

This distribution we have seen before:

$$f(x) = \begin{cases} \frac{x^{k/2-1} e^{-x/2}}{2^{k/2} \Gamma(k/2)} & \text{for } x \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

When variance is unknown, estimating it from sample gives additional error:

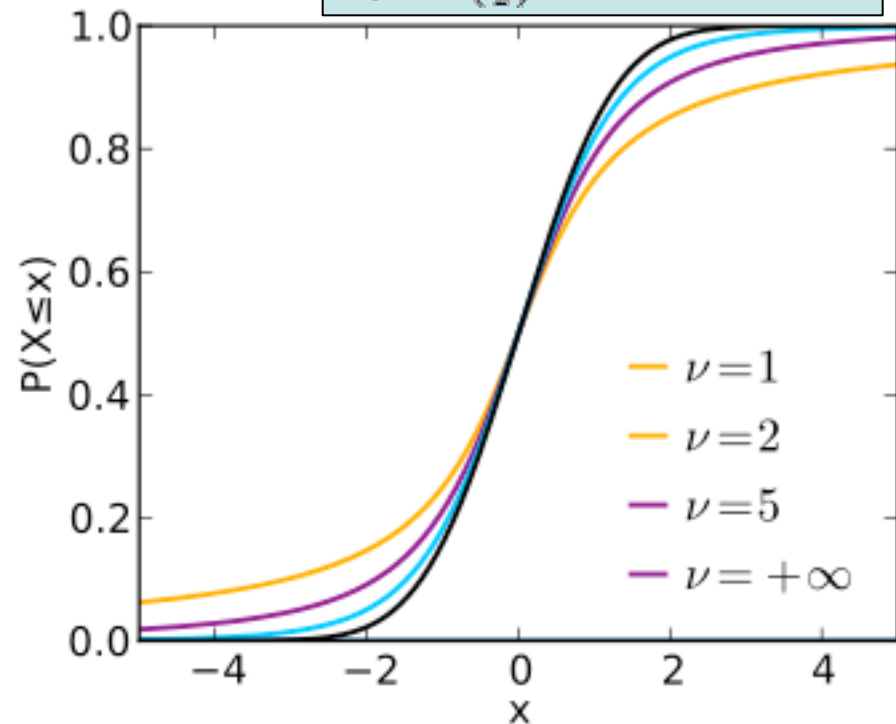
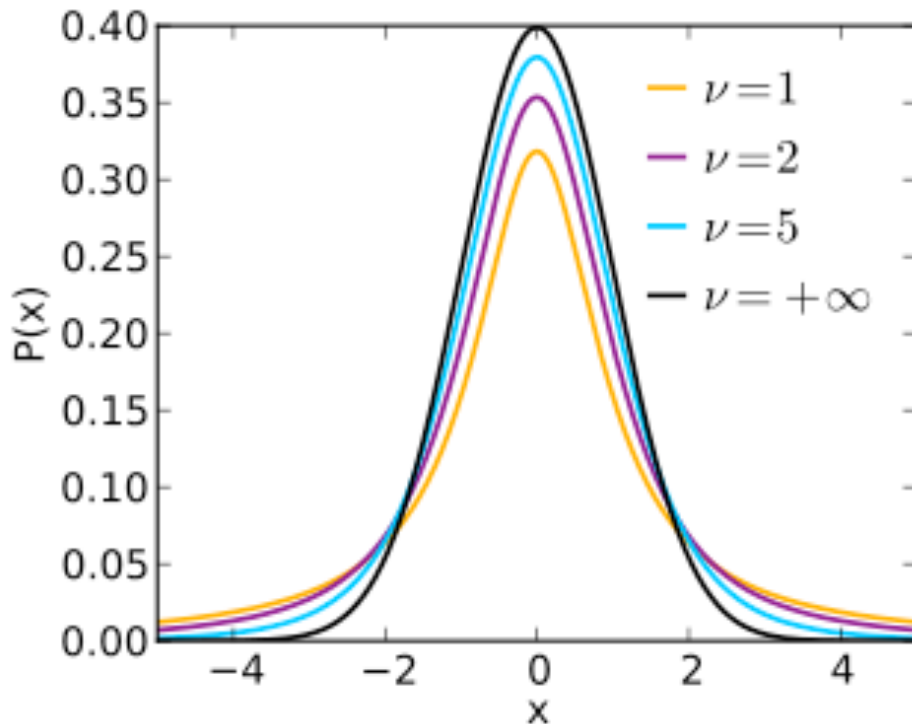
**Gaussian:**  $z = \frac{x - \mu}{\sigma}$

**Student's:**  $t = \frac{x - \mu}{\hat{\sigma}}$

# Student's t-distribution

Discovered by William Gosset (who signed "student"), student's t-distribution takes into account **lacking knowledge of the variance**.

$$\frac{\Gamma\left(\frac{\nu+1}{2}\right)}{\sqrt{\nu\pi}\Gamma\left(\frac{\nu}{2}\right)} \left(1 + \frac{x^2}{\nu}\right)^{-\frac{\nu+1}{2}}$$



When variance is unknown, estimating it from sample gives additional error:

**Gaussian:**

$$z = \frac{x - \mu}{\sigma}$$

**Student's:**

$$t = \frac{x - \mu}{\hat{\sigma}}$$

# Exponential distribution

One particularly important PDF is the exponential distribution.

This takes the shape:

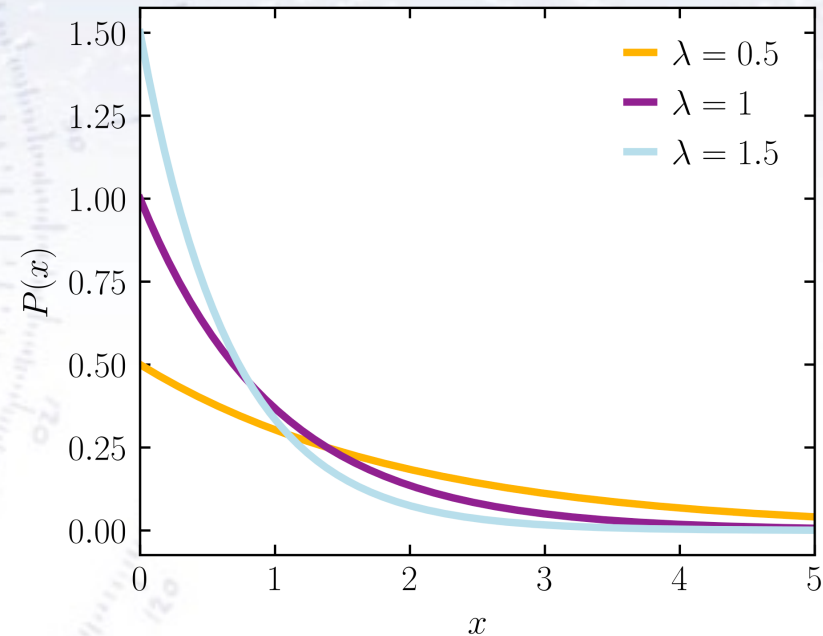
$$f(x) = \lambda e^{-\lambda x}$$

With this we can also calculate the mean value:

$$\begin{aligned}\mu &= \int_0^{\infty} x \lambda e^{-\lambda x} dx \\ &= \lambda \left( \left[ -\frac{1}{\lambda} x e^{-\lambda x} \right]_0^{\infty} + \int_0^{\infty} \frac{1}{\lambda} e^{-\lambda x} dx \right) \\ &= \frac{\lambda}{\lambda^2} = \frac{1}{\lambda}\end{aligned}$$

And also the variance by performing similar integration:

$$\begin{aligned}\sigma^2 &= \int_0^{\infty} (x - \mu)^2 \lambda e^{-\lambda x} dx \\ &= \frac{1}{\lambda^2}\end{aligned}$$



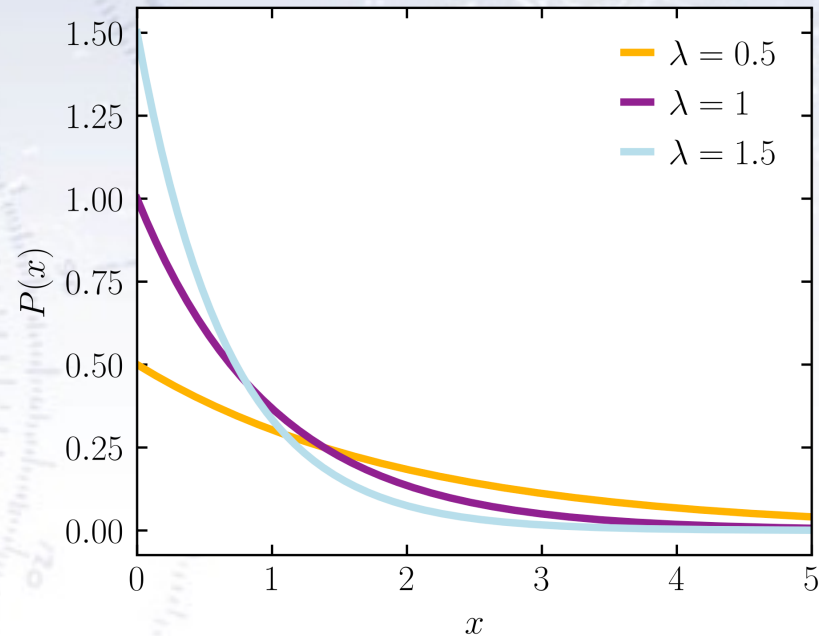
# Exponential distribution

Why is the exponential distribution so important?

There are several good examples, but the one we will show here is the following:

*If a process occurs with a constant rate, the distribution of time before the event happens will be exponentially distributed*

This is really the case for many systems. Of course the most prominent example is the decay of atoms.



# Exponential distribution

Assume that an atom decays with rate  $\lambda$ .

The probability that the atom will decay in a short time interval  $dt$ , must be:

$$p_{decay} = \lambda dt \quad p_{not} = (1 - \lambda)dt$$

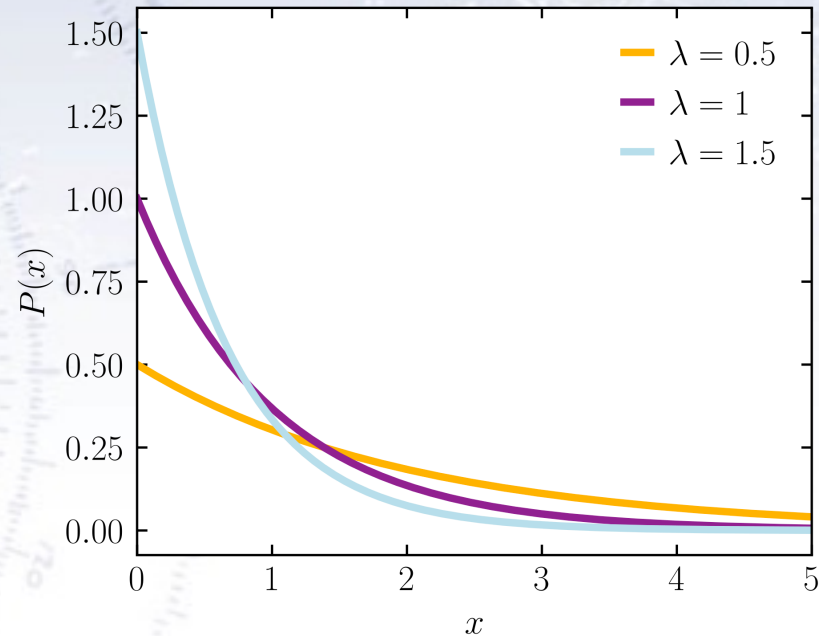
Now we can define a time that is the sum of a lot of small time intervals:  $\tau = n \cdot dt$

$$p_{not}(\tau) = \left(1 - \frac{\tau}{n}\lambda\right)^n$$

And finally, the probability that an event occurs after exactly some time tau must be:

$$p(t_{first} = \tau) = \left(1 - \frac{\tau}{n}\lambda\right)^n \lambda dt = \lambda e^{-\lambda\tau} dt$$

Where we have used the definition of the exponential distribution



# Rayleigh distribution

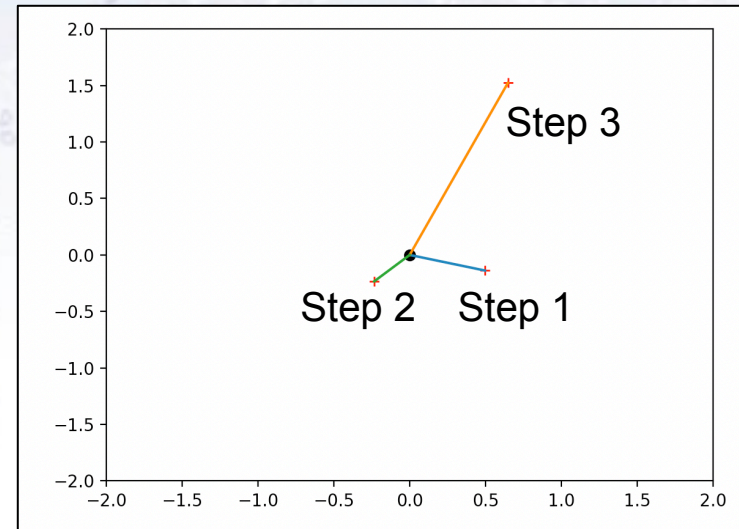
Let's assume that a particle moves in two dimensions. It diffuses so in both dimensions, it will take the step with distribution (for simplicity assuming  $\text{std}=1$ ):

$$p(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}x^2}$$

This means that the probability that the particle will be at exactly position  $x^*$  and  $y^*$  will be:

$$p(x, y) = \frac{1}{2\pi} e^{-\frac{1}{2}(x^2+y^2)}$$

This looks like the radius, but in order to compute to total probability of a radius, we must factor in the possibility of obtaining a particular radius.



# Rayleigh distribution

To count the number of ways to obtain the radius  $r$ , is exactly the perimeter of a circle with radius  $r$ , i.e.  $2\pi r$ .

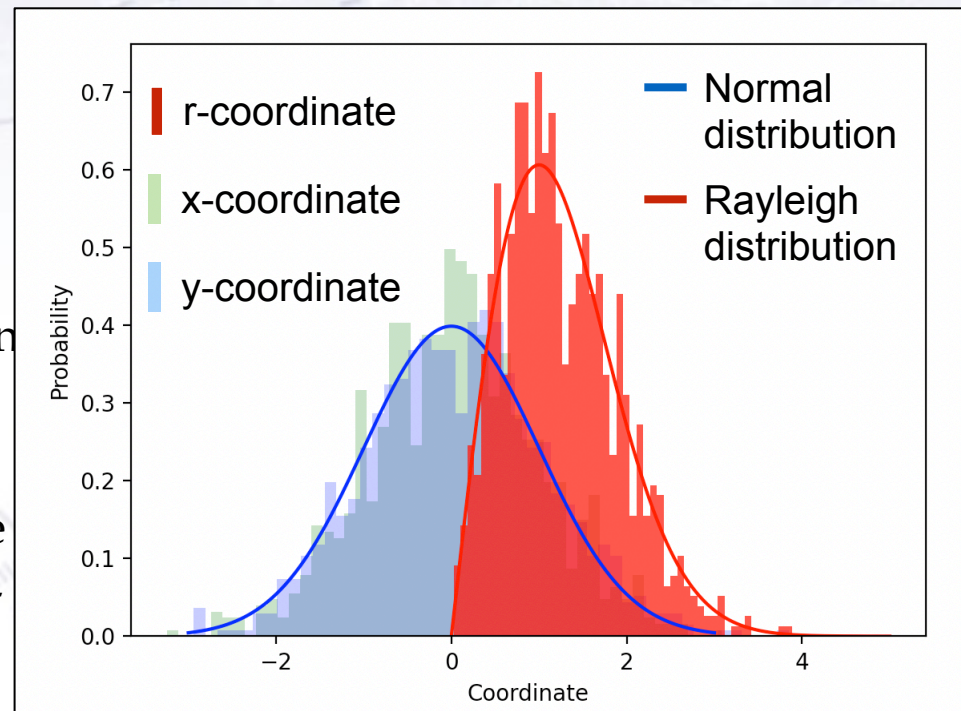
Multiplying with this we get:

$$p(r) = r e^{-\frac{1}{2}r^2}$$

This is exactly the Rayleigh distribution for  $\text{std}=1$ .

If we simulate the 1000 of the steps, we see that we such a distribution in the  $r$ -coordinate.

Note that the most probable point is  $x=y=0$ , but that the probability of  $r=0$  is zero.







# Some particular elements of PDF

# Cumulative distributions functions

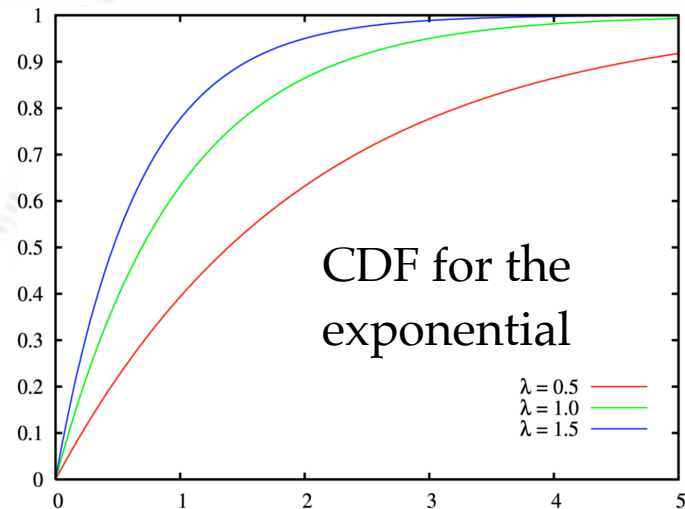
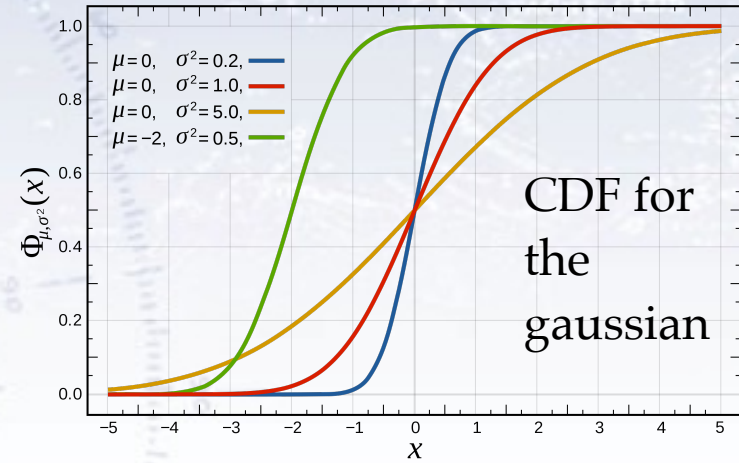
Completely basic to every PDF is the cumulative distribution function, the CDF.

The CDF is defined by:

$$F_X(x) = \int_{-\infty}^x f_X(t) dt.$$

In words, this means that it is the probability of getting  $x$ , or something below that value.

The CDF is used in many ways, and we will meet it again soon, when we discuss hypothesis testing and statistical tests.



# Convolution of probabilities

Suppose we draw two random numbers from a probability distribution  $f(x)$ . How can we calculate the probability of their sum?

$$\begin{aligned} f(z) &= \int \int f(x_1) \cdot f(x_2) \delta(z - ax_1 - ax_2) dx_1 dx_2 \quad \text{we substitute } s = ax_1 \text{ so } \frac{ds}{dx_1} = a \\ &= \int \int f\left(\frac{s}{a}\right) \cdot f(x_2) \delta(z - s - ax_2) \frac{1}{a} ds dx_2 \quad \text{we integrate using the } \delta \text{ function} \\ &= \frac{1}{a} \int f\left(\frac{z}{a} - x_2\right) \cdot f(x_2) dx_2 \end{aligned}$$

For the gaussian for instance, we will get, that this is a new gaussian distribution.

# Characteristic functions

Typically when studying statistics, one stumble upon the term characteristic function.

Every PDF has a characteristic function that is simply the Fourier transform of the PDF itself:

$$G_x(t) = \int_{-\infty}^{\infty} f(x)e^{itx} dx = \mathbb{E}(e^{ixt})$$

The characteristic function has some properties that makes it neat to use, for instance that it can generate all moments for the PDF itself (note that the first moment is the mean, the second is the variance etc.).

The gaussian has a characteristic function given by:

$$\begin{aligned} G_z(t) &= \int e^{itz} \frac{1}{\sqrt{2\pi}} e^{-\frac{z^2}{2}} dz \text{ noting that } (z - it)^2 = z^2 - t^2 - itz \\ &= \int \frac{1}{\sqrt{2\pi}} e^{-\frac{(z-it)^2}{2}} e^{-\frac{t^2}{2}} dz \text{ substituting } u = z - it \\ &= \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} \int e^{-\frac{u^2}{2}} dz \text{ noting the integral is } \sqrt{2\pi} \text{ (for the gaussian to be normalized)} \\ &= e^{-\frac{t^2}{2}} \end{aligned}$$

# Sum up of the lecture

All PDFs are normalized functions, that describe the probability of getting a value from a function.

The most fundamental are the binomial, the Poisson and the Gaussian.

Remember that the error on a (Poisson) number is **the square root** of that number!

Remember that the Gaussian distribution defines the uncertainties, that we report on experiments.