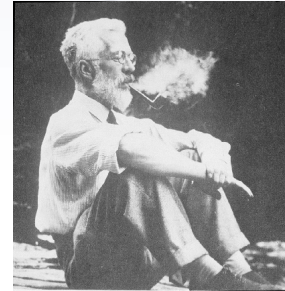
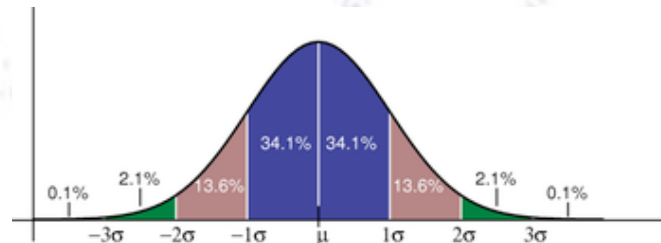


# Applied Statistics

## Probability Density Functions (PDFs)



IA PLACZ  
Troels C. Petersen



*"Statistics is merely a quantisation of common sense"*

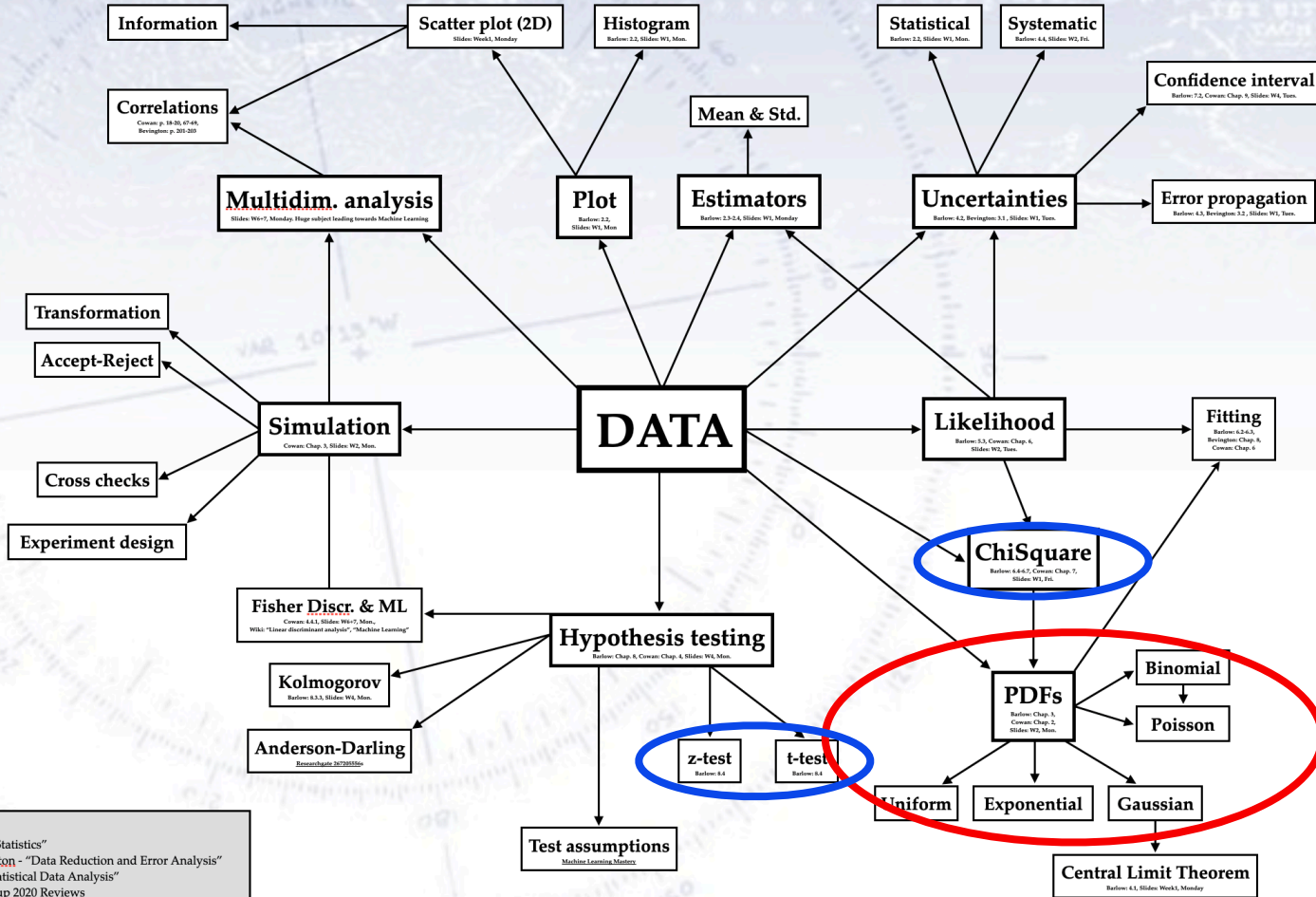
# Probability Density Functions

## Applied Statistics

## Describe data (Quantify & Visualise)

## Overview of subjects

Version 1.2, 6. Nov. 2020



Simulate data (Design & Cross Check)

Model data (Predict & Understand)

References:  
 Barlow: R. J. Barlow - "Statistics"  
 Bevington: P. H. Bevington - "Data Reduction and Error Analysis"  
 Cowan: G. Cowan - "Statistical Data Analysis"  
 PDG: Particle Data Group 2020 Reviews  
 Slides: T. C. Petersen - "Applied Statistics 2020" course (W = Week)  
 Wiki: Good reference for ALL subjects (only specified when essential)  
 SciPy: SciPy Statistical Functions and (very brief) documentation

## Test hypotheses on data (Decide)

# Probability Density Functions

A Probability Density Function (PDF)  $f(x)$  describes the probability of an outcome  $x$ :

*probability to observe  $x$  in the interval  $[x, x+dx] = f(x) dx$*

PDFs are required to be normalised:

$$\int_S f(x) dx = 1$$

The expectation value (aka. mean) and the variance (i.e. standard deviation squared) are then defined as follows:

$$\mu = \int_{-\infty}^{\infty} x f(x) dx$$

$$\sigma^2 = \int_{-\infty}^{\infty} (x - \mu)^2 f(x) dx$$

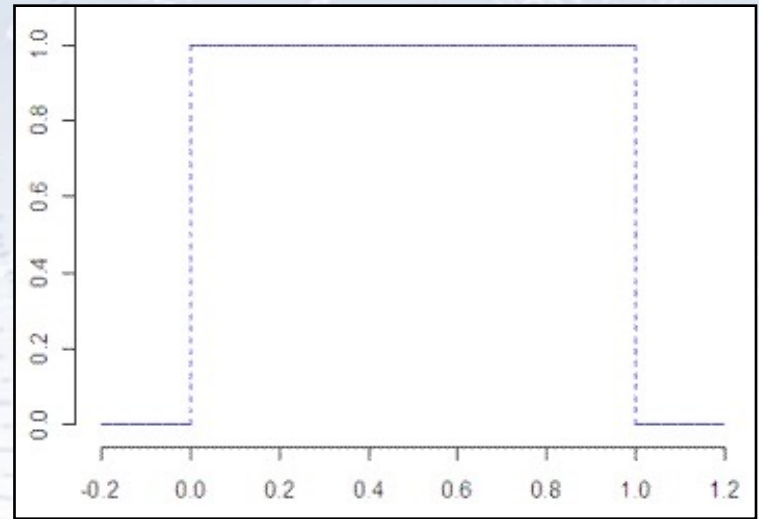
# Probability Density Functions

Example:

Consider a uniform distribution:

$$f(x) = \begin{cases} 1 & x \in [0, 1] \\ 0 & \textit{else} \end{cases}$$

Calculating the mean and variance:



$$\mu = \int_{-\infty}^{\infty} x f(x) dx = \int_0^1 x dx = \left[ \frac{1}{2} x^2 \right]_0^1 = \frac{1}{2}$$

$$\begin{aligned} \sigma^2 &= \int_{-\infty}^{\infty} (x - \mu)^2 f(x) dx = \int_0^1 \left(x - \frac{1}{2}\right)^2 dx = \\ &\left[ \frac{1}{3} x^3 - \frac{1}{2} x^2 + \frac{1}{4} x \right]_0^1 = \frac{1}{3} - \frac{1}{2} + \frac{1}{4} = \frac{1}{12} \end{aligned}$$

# Cumulative distributions functions

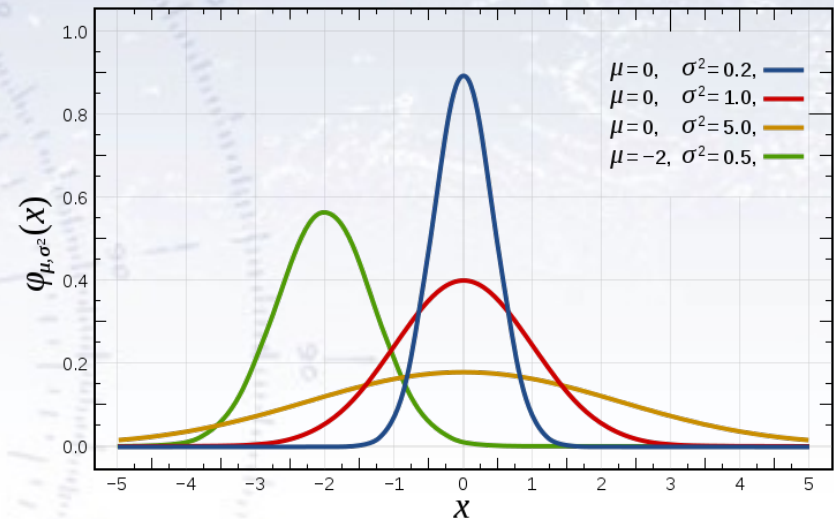
Completely basic to every PDF is the **cumulative distribution function, CDF**, defined as:

$$F_X(x) = \int_{-\infty}^x f_X(t) dt.$$

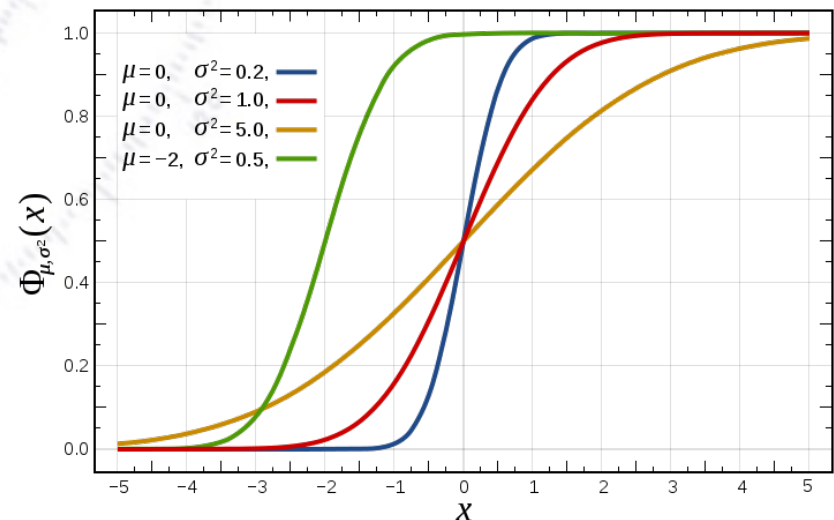
In words, this means that it is the probability of getting  $x$ , or something below that value.

The CDF is used in many ways, and we will meet it again soon, when we discuss hypothesis testing.

## Gaussian PDF



## Gaussian CDF



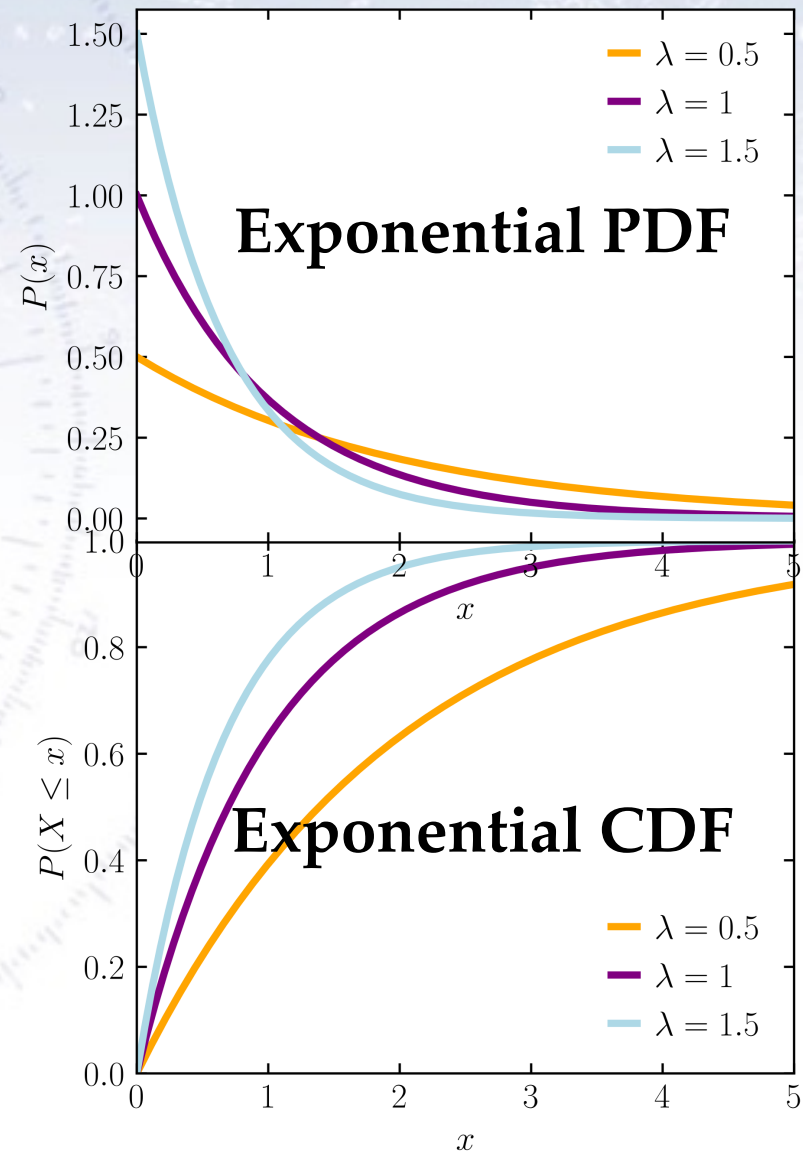
# Cumulative distributions functions

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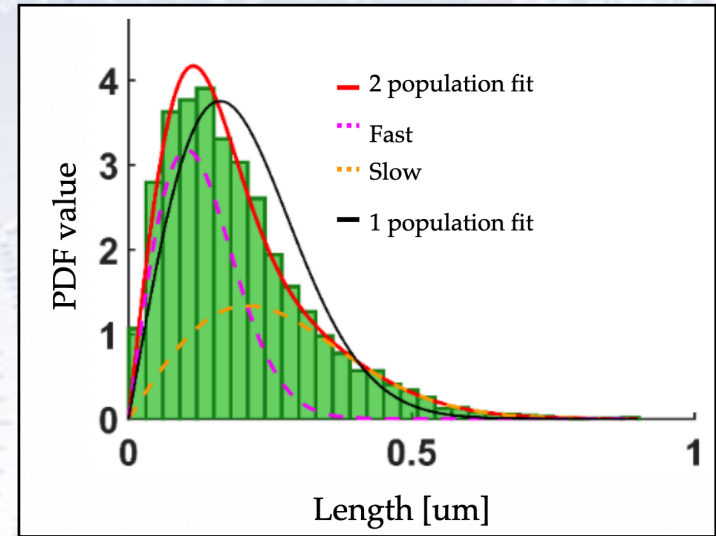
The CDF is used in many ways, and we will meet it again soon, when we discuss hypothesis testing.



# Why PDFs

Could we not just use mean and variance and call it a day?

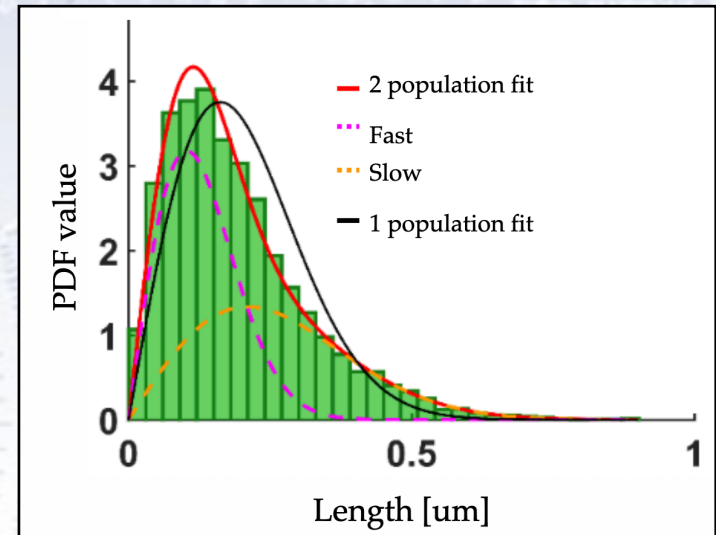
Well, PDFs makes us able to ask what the *probability* of a certain event given the underlying model (i.e. PDF), and this allows for new discoveries!



# Why PDFs

Could we not just use mean and variance and call it a day?

Well, PDFs makes us able to ask what the *probability* of a certain event given the underlying model (i.e. PDF), and this allows for new discoveries!



On notation:

In the literature it is often we use large letters for a random variable  $X$ . This means an *outcome* for an event! If I roll a die, we say that  $X$  takes on values in  $\{1,2,3,4,5,6\}$ , which is a *discrete* case.

Small letters are typically real numbers. So we could write:  $P(X < c)$ , which translated means that we calculate the probability  $P$  that in one event  $X$ , we obtain a value of  $X$  smaller than the real value  $c$ .



# Probability Density Functions

The number of PDFs is infinite, and nearly so is the list of known ones:

## Discrete distributions [\[ edit source | edit beta \]](#)

### With finite support [\[ edit source | edit beta \]](#)

- The Bernoulli distribution, which takes value 1 with probability  $p$ .
- The Rademacher distribution, which takes value  $\pm 1$  with equal probability.
- The binomial distribution, which describes the number of successes in a fixed number of independent trials.
- The beta-binomial distribution, which describes the distribution of the number of successes in a fixed number of trials when the probability of success is itself a random variable.
- The degenerate distribution at  $x_0$ , where  $X$  is certain to take the value  $x_0$ .
- The discrete uniform distribution, where all elements of a finite set are equally likely.
- The hypergeometric distribution, which describes the number of successes in a fixed number of trials without replacement.
- The Poisson binomial distribution, which describes the number of successes in a fixed number of trials with varying probabilities.
- Fisher's noncentral hypergeometric distribution
- Wallenius' noncentral hypergeometric distribution
- Benford's law, which describes the frequency of digits in many real-world datasets.

### With infinite support [\[ edit source | edit beta \]](#)

- The beta negative binomial distribution
- The Boltzmann distribution, a discrete distribution in statistical mechanics. Special cases include:
  - The Gibbs distribution
  - The Maxwell-Boltzmann distribution
- The Borel distribution
- The extended negative binomial distribution
- The extended hypergeometric distribution
- The generalized log-series distribution
- The generalized normal distribution
- The geometric distribution, a discrete distribution with infinite support.
- The hypergeometric distribution
- The logarithmic (series) distribution
- The negative binomial distribution or Pascal distribution
- The parabolic fractal distribution
- The Poisson distribution, which describes a very large number of independent trials with a small probability of success. Special cases include:
  - The Conway-Maxwell-Poisson distribution, a two-parameter generalization of the Poisson distribution.
  - The Polya-Eggenberger distribution
- The Skellam distribution, the distribution of the difference of two independent Poisson variables.
- The skew elliptical distribution
- The skew normal distribution
- The Yule-Simon distribution
- The zeta distribution has uses in applied statistics
- Zipf's law or the Zipf distribution. A discrete power-law distribution.
- The Zipf-Mandelbrot law is a discrete power-law distribution.

## Continuous distributions [\[ edit source | edit beta \]](#)

### Supported on a bounded interval [\[ edit source | edit beta \]](#)

- The Arcsine distribution on  $[a, b]$ , which is a special case of the beta distribution.
- The Beta distribution on  $[0, 1]$ , of which the uniform distribution is a special case.
- The Logitnormal distribution on  $(0, 1)$ .
- The Dirac delta function although not strictly a function, but the notation treats it as if it were a continuous function.
- The continuous uniform distribution on  $[a, b]$ , when  $a < b$ .
  - The rectangular distribution is a uniform distribution on  $[a, b]$ .
- The Irwin-Hall distribution is the distribution of the sum of  $n$  independent uniform random variables.
- The Kent distribution on the three-dimensional sphere.
- The Kumaraswamy distribution is as versatile as the beta distribution.
- The logarithmic distribution (continuous)
- The PERT distribution is a special case of the beta distribution.
- The raised cosine distribution on  $[\mu - s, \mu + s]$
- The reciprocal distribution
- The triangular distribution on  $[a, b]$ , a special case of the beta distribution.
- The truncated normal distribution on  $[a, b]$ .
- The U-quadratic distribution on  $[a, b]$ .
- The von Mises distribution on the circle.
- The von Mises-Fisher distribution on the  $N$ -dimensional sphere.
- The Wigner semicircle distribution is important in quantum mechanics.

### Supported on semi-infinite intervals, usually $[0, \infty)$

- The Beta prime distribution
- The Birnbaum-Saunders distribution, also known as the Rayleigh distribution
- The chi distribution
  - The noncentral chi distribution
- The chi-squared distribution, which is the sum of the squares of  $k$  independent standard normal variables.
  - The inverse-chi-squared distribution
  - The noncentral chi-squared distribution
  - The Scaled-inverse-chi-squared distribution
- The Dagum distribution
- The exponential distribution, which describes the time between events in a Poisson process.
- The F-distribution, which is the distribution of the ratio of two chi-squared variates which are not independent.
- The noncentral F-distribution
- Fisher's z-distribution
- The folded normal distribution
- The Fréchet distribution
- The Gamma distribution, which describes the time between events in a Poisson process.
  - The Erlang distribution, which is a special case of the gamma distribution.
  - The inverse-gamma distribution
- The generalized Pareto distribution
- The Gamma/Gompertz distribution
- The Gompertz distribution
- The half-normal distribution

- Hotelling's T-squared distribution
- The inverse Gaussian distribution, also known as the Wald distribution
- The Lévy distribution
- The log-Cauchy distribution
- The log-gamma distribution
- The log-Laplace distribution
- The log-logistic distribution
- The log-normal distribution, describing variability in many natural phenomena
- The Mittag-Leffler distribution
- The Nakagami distribution
- The Pareto distribution, or "power law" distribution
- The Pearson Type III distribution
- The phased bi-exponential distribution is common in reliability engineering
- The phased bi-Weibull distribution
- The Rayleigh distribution
- The Rayleigh mixture distribution
- The Rice distribution
- The shifted Gompertz distribution
- The type-2 Gumbel distribution
- The Weibull distribution or Rosin-Rammler distribution, used in grinding, milling and crushing operations.

### Supported on the whole real line [\[ edit source | edit beta \]](#)

- The Behrens-Fisher distribution, which arises in the analysis of variance
- The Cauchy distribution, an example of a heavy-tailed distribution
- The resonance energy distribution, impact and fracture
- Chernoff's distribution
- The Exponentially modified Gaussian distribution
- The Fisher-Tippett, extreme value, or log-normal distribution
  - The Gumbel distribution, a special case of the Fisher-Tippett distribution
- Fisher's z-distribution
- The generalized logistic distribution
- The generalized normal distribution
- The geometric stable distribution
- The Holtmark distribution, an example of a heavy-tailed distribution
- The hyperbolic distribution
- The hyperbolic secant distribution
- The Johnson SU distribution
- The Landau distribution
- The Laplace distribution
- The Lévy skew alpha-stable distribution or stable distribution, Lévy distribution and normal distribution
- The Linnik distribution
- The logistic distribution
- The map-Airy distribution
- The normal distribution, also called the Gaussian distribution, is the most common distribution
- The Normal-exponential-gamma distribution
- The Pearson Type IV distribution (see Pearson distribution family)
- The skew normal distribution

- Student's t-distribution, useful for estimating the mean of a normal distribution with unknown variance.
  - The noncentral t-distribution
- The type-1 Gumbel distribution
- The Voigt distribution, or Voigt profile, is the convolution of a Gaussian and a Lorentzian distribution
- The Gaussian minus exponential distribution is used in reliability engineering

### With variable support [\[ edit source | edit beta \]](#)

- The generalized extreme value distribution has a shape parameter
- The generalized Pareto distribution has a shape parameter
- The Tukey lambda distribution is either supported on a bounded interval or on the whole real line
- The Wakeby distribution

### Mixed discrete/continuous distributions [\[ edit source | edit beta \]](#)

- The rectified Gaussian distribution replaces the negative part of a Gaussian distribution with a discrete distribution

### Joint distributions [\[ edit source | edit beta \]](#)

For any set of independent random variables the joint distribution is the product of the individual distributions.

### Two or more random variables on the same space

- The Dirichlet distribution, a generalization of the multinomial distribution
- The Ewens's sampling formula is a probability distribution on permutations
- The Balding-Nichols model
- The multinomial distribution, a generalization of the binomial distribution
- The multivariate normal distribution, a generalization of the normal distribution
- The negative multinomial distribution, a generalization of the negative binomial distribution
- The generalized multivariate log-gamma distribution

### Matrix-valued distributions [\[ edit source | edit beta \]](#)

- The Wishart distribution
- The inverse-Wishart distribution
- The matrix normal distribution
- The matrix t-distribution

### Non-numeric distributions [\[ edit source | edit beta \]](#)

- The categorical distribution
- newton distribution

### Miscellaneous distributions [\[ edit source | edit beta \]](#)

- The Cantor distribution
- The generalized logistic distribution family
- The Pearson distribution family
- The phase-type distribution

And surely more!

# Probability Density Functions

The number of PDFs is infinite, and nearly so is the list of known ones:

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### With finite support [ edit source | edit beta ]

- The Bernoulli distribution, which takes value 1 with probability  $p$ .
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- The binomial distribution, which describes the number of successes in a fixed number of independent trials.
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- The Arcsine distribution on  $[a, b]$ , which is a special case of the beta distribution.
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  - The type-I Gumbel distribution
- The Voigt distribution, or Voigt profile, is the convolution of a Gaussian and a Lorentzian distribution
- The Gaussian minus exponential distribution is used in queueing theory

### With variable support [ edit source | edit beta ]

- The generalized extreme value distribution has three types: Gumbel, Weibull, and Fréchet
- The generalized Pareto distribution has a support that is unbounded above
- The Tukey lambda distribution is either supported on a bounded interval or on the real line
- The Wakeby distribution

### Mixed discrete/continuous distributions [ edit source | edit beta ]

- The rectified Gaussian distribution replaces the negative part of a Gaussian distribution with a discrete distribution

### Joint distributions [ edit source | edit beta ]

For any set of independent random variables the joint distribution is the product of the individual distributions

<https://docs.scipy.org/doc/scipy/reference/stats.html>

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- The Maxwell-Boltzmann distribution
- The Borel distribution
- The extended negative binomial distribution
- The extended hypergeometric distribution
- The generalized log-series distribution
- The generalized normal distribution
- The geometric distribution, a discrete distribution with a constant hazard rate
- The hypergeometric distribution
- The logarithmic (series) distribution
- The negative binomial distribution or Pascal distribution
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And surely more!

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*"Essentially, all models are wrong, but some are useful"*

[George E. P. Box, British Statistician, 1919-2013]

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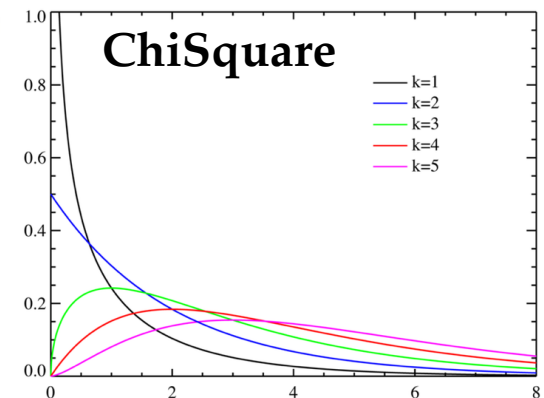
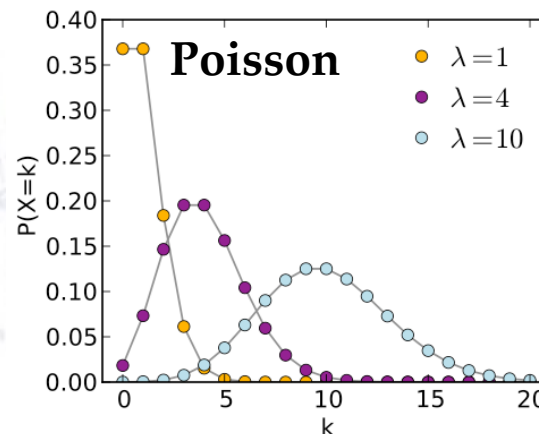
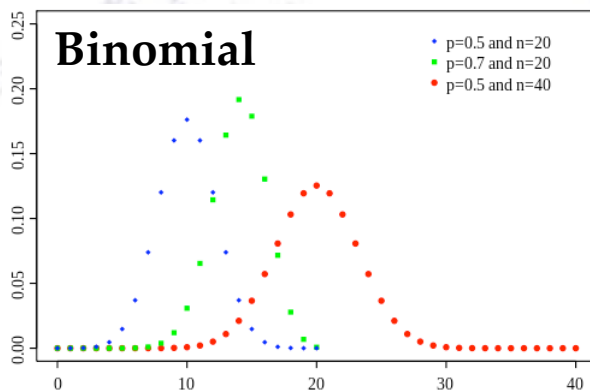
# Probability Density Functions

An almost complete list of those we will deal with in this course is:

- **Gaussian** (aka. Normal)
- **Poisson**
- **Binomial** (and also Multinomial)
- Students t-distribution
- Uniform
- ChiSquare
- Exponential
- Error function (integral of Gaussian)

See Barlow chap.3  
and Cowan chap.2

You should already know most of these, and the rest will be explained.



# Binomial, Poisson, Gaussian

$$f(n; N, p) = \frac{N!}{n!(N-n)!} p^n (1-p)^{N-n}$$

Given **N trials** each with **p chance of success**, how many **successes n** should you expect in total?

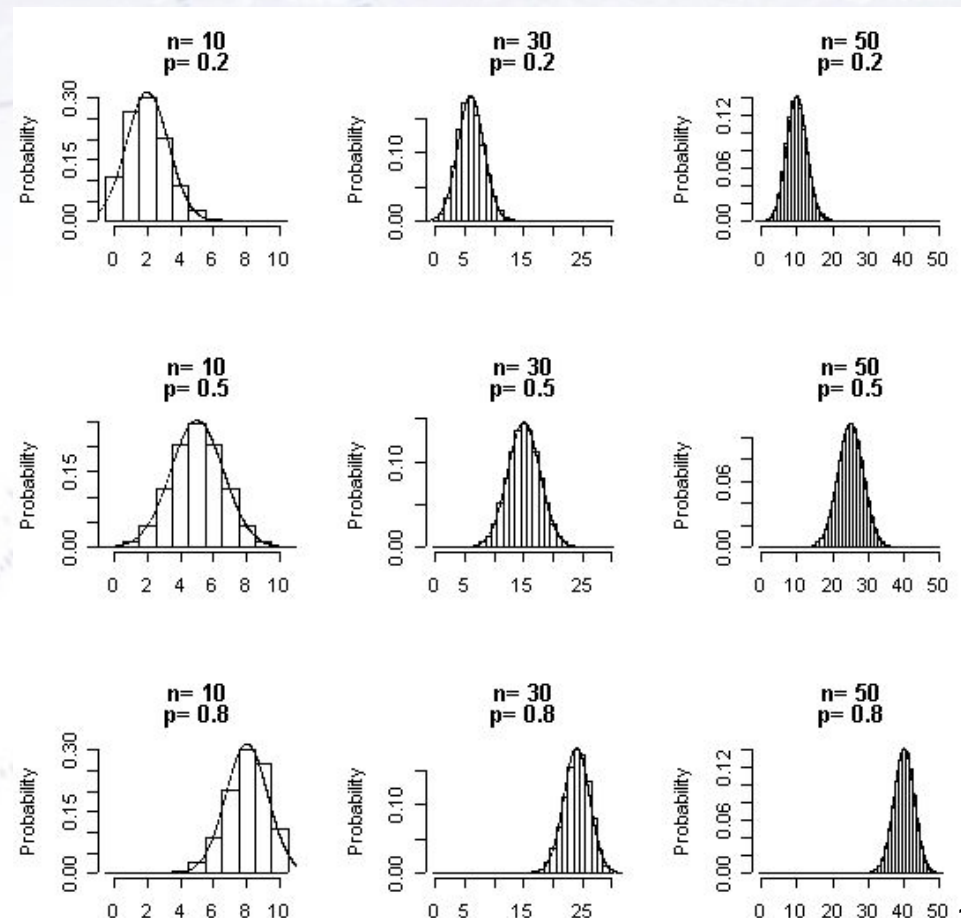
This distribution is... **Binomial**, with

$$\text{Mean} = Np$$

$$\text{Variance} = Np(1-p)$$

This means, that the error on a fraction  $f = n/N$  is:

$$\sigma(f) = \sqrt{\frac{f(1-f)}{N}}$$



# Binomial, Poisson, Gaussian

$$f(n; N, p) = \frac{N!}{n!(N-n)!} p^n (1-p)^{N-n}$$

The binomial distribution was first introduced by Jacob Bernoulli in 1713 (posthumously).

The binomial distribution basically consists of two elements: The binomial coefficient (green) and the probabilities of exactly  $n$  such events (blue).

Even though a system has many outcomes, it is typically possible to refer to either “success” of “failure”.

*Assume the probability to have COVID19 is 1%. In a sample of 50 people the chance to have 1 or more infected is:  $1-p(0) = 1 - 0.99^{50} = 0.60$*

$$(x + y)^4 = x^4 + 4x^3y + 6x^2y^2 + 4xy^3 + y^4.$$

0:										1																
1:										1										1						
2:										1		2		1												
3:										1		3		3		1										
4:										1		4		6		4		1								
5:										1		5		10		10		5		1						
6:										1		6		15		20		15		6		1				
7:										1		7		21		35		35		21		7		1		
8:										1		8		28		56		70		56		28		8		1

# Binomial, Poisson, Gaussian

You count 100 cars, and see 15 red cars. What is your estimate of the fraction (i.e. probability) of red cars and its uncertainty?

- a)  $0.150 \pm 0.050$
- b)  $0.150 \pm 0.026$
- c)  $0.150 \pm 0.036$
- d)  $0.125 \pm 0.030$
- e)  $0.150 \pm 0.081$

From previous page: 
$$\sigma(f) = \sqrt{\frac{f(1-f)}{N}}$$

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**Notice - this was actually a hypothesis test!**

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# Binomial, Poisson, Gaussian

## Requirements to be Binomial:

- Fixed number of trials,  $N$
- Independent trials.
- Only two outcomes (success / failure).
- Constant probability of success / failure.

If number of possible outcomes is more than two  $\Rightarrow$  **Multinomial distribution.**

## Examples of Binomial experiments:

- Tossing a coin 20 times counting number of tails.
- Asking 200 people if they watch sports on TV.
- Rolling a die to see if a 6 appear (Multinomial for all outcomes!).
- Asking 100 die-hards from Ehedslisten, if they would vote for Konservative at the next election!

## Examples which aren't Binomial experiments:

- Rolling a die until a 6 appears (not fixed number of trials).
- Drawing 5 cards for a poker hand (no replacement  $\Rightarrow$  not independent)

# Binomial, Poisson, Gaussian

If  $N \rightarrow \infty$  and  $p \rightarrow 0$ , but  $Np \rightarrow \lambda$  then a Binomial approaches a Poisson: (see Barlow 3.3.1)

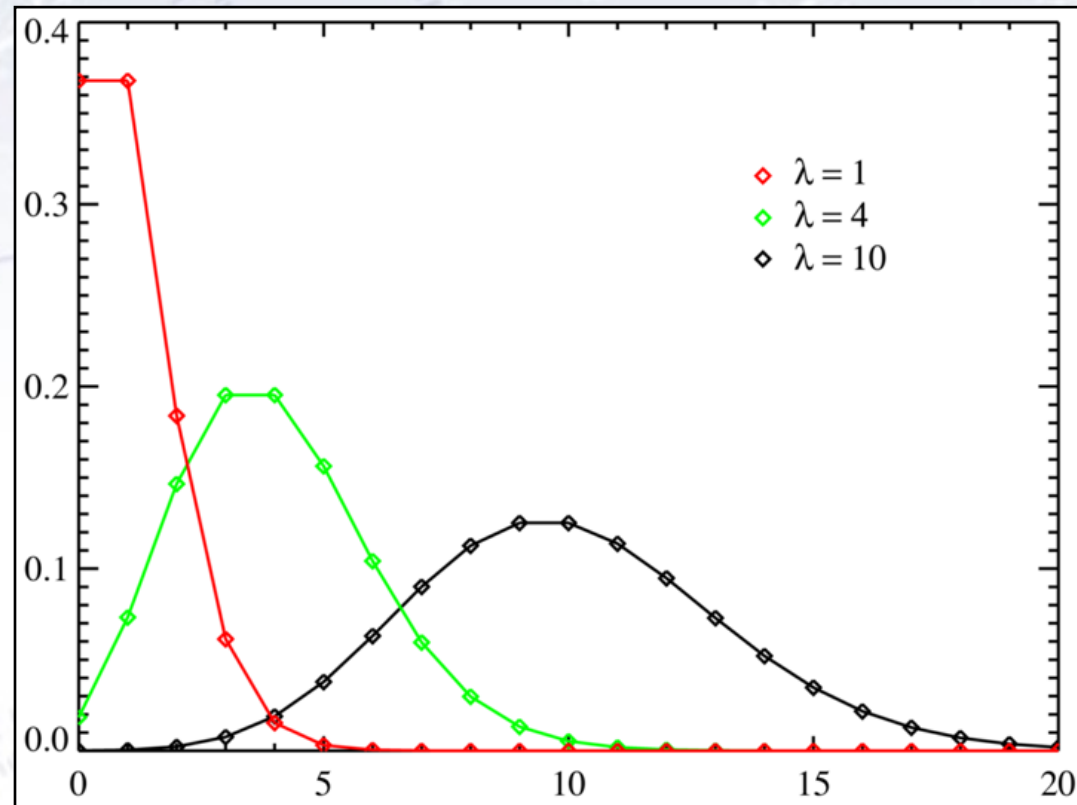
$$f(n, \lambda) = \frac{\lambda^n}{n!} e^{-\lambda}$$

In reality, the approximation is already quite good at e.g.  $N=50$  and  $p=0.1$ .

The Poisson distribution only has one parameter, namely  $\lambda$ .

Mean =  $\lambda$

Variance =  $\lambda$



So the error on a number is...

*...the square root of that number!*

# Binomial, Poisson, Gaussian

The error on a  
(Poisson) number...  
is the square root  
of that number!!!

# Binomial, Poisson, Gaussian

The error on a  
(Poisson) number.

A very useful case of this is the error to assign a bin in a histogram,  
if there is reasonable statistics ( $N_i > 5-20$ ) in each bin.

is the square root  
of that number!!!

The error on a  
(Poisson) number...  
is the square root  
of that number!!!

Note: The sum of two Poissons with  $\lambda_a$  and  $\lambda_b$  is a new Poisson with  $\lambda = \lambda_a + \lambda_b$ .  
(See Barlow pages 33-34 for proof)

# Binomial, Poisson, Gaussian

The Poisson distribution has the advantage that **neither the number of trials  $N$  nor the probability of success  $p$  has to be known** - just their product.

A typical use is when dealing with **rates** in a given interval of time, distance, area, volume, etc.

# Binomial, Poisson, Gaussian

The Poisson distribution has the advantage that **neither the number of trials N nor the probability of success p has to be known** - just their product.

A typical use is when dealing with **rates** in a given interval of time, distance, area, volume, etc.

Example (real from 1898):

There were 122 deaths by horse kicks over 10 different regiments, over 20 years. What is the predicted number of deaths in a specific regiment and year?

First we estimate the mean value:

$$\mu = \frac{122}{20 * 10} = 0.61$$

This means that the probability that 0 will die is given by:

$$P(0) = e^{-0.61} \frac{0.61^0}{0!} = 0.54$$





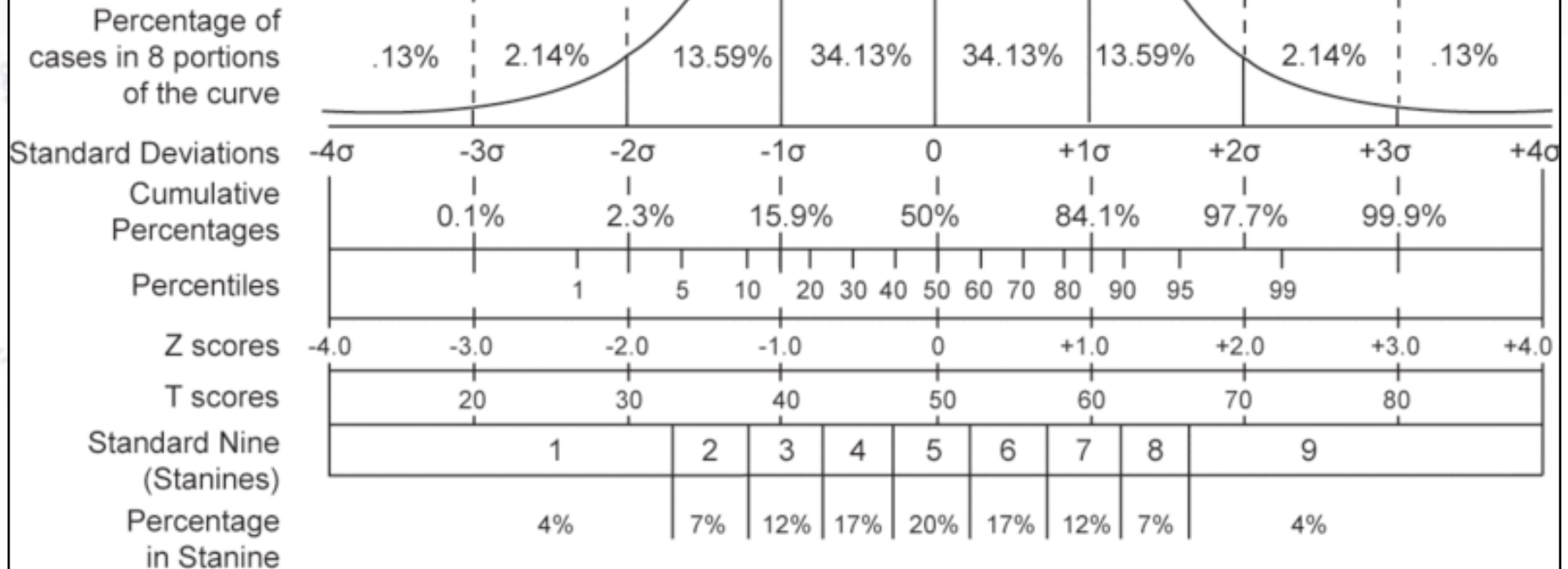
# Binomial, Poisson, Gaussian

If  $\lambda \rightarrow \infty$ , the Poisson becomes a Gaussian...

...and  $\lambda > 20$  is enough!

For proof, see  
Barlow p.40

*Normal,  
Bell-shaped Curve*



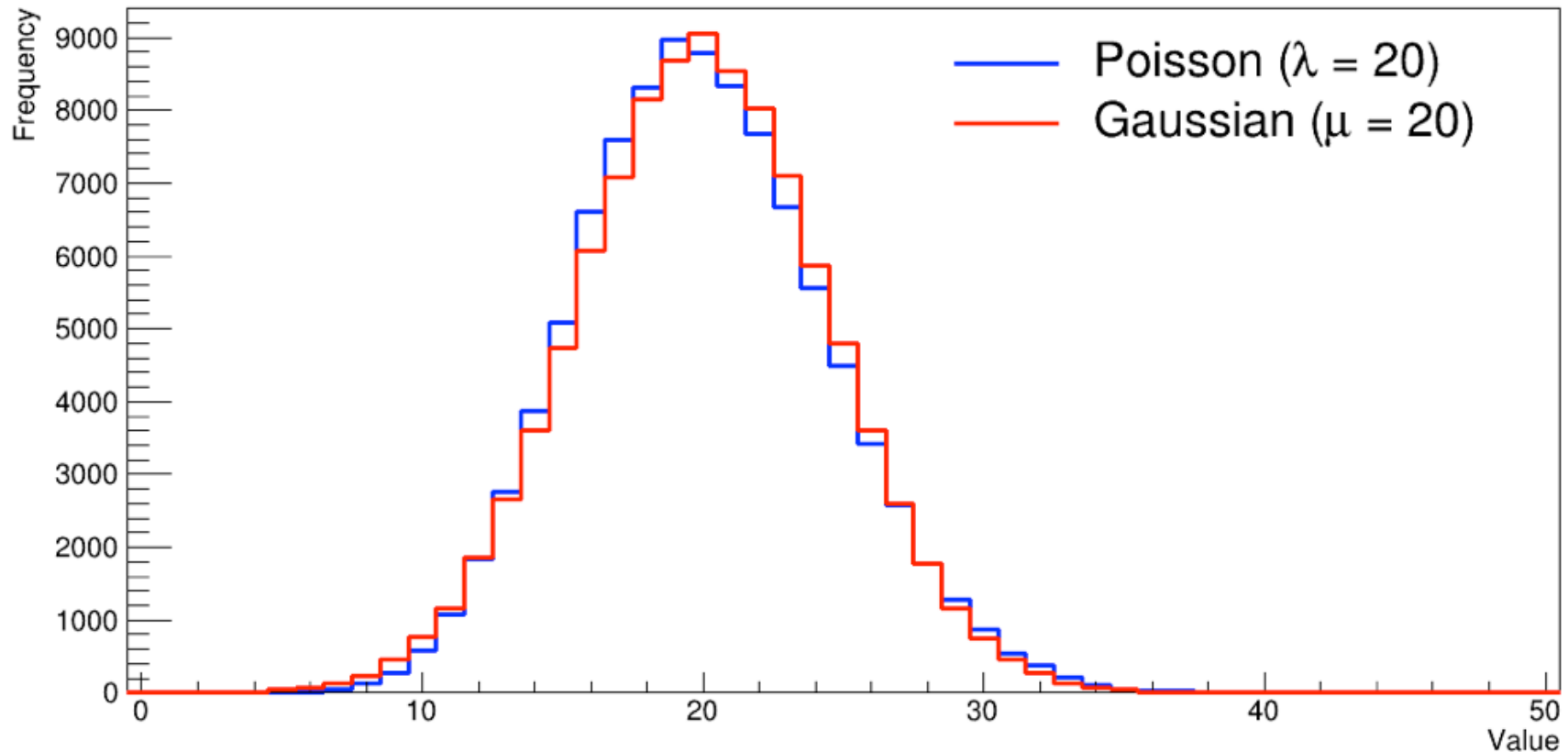
All fields encounter the Gaussian, and for this reason, its scale has many names!

# Binomial, Poisson, Gaussian

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Poisson and Gaussian distribution comparison

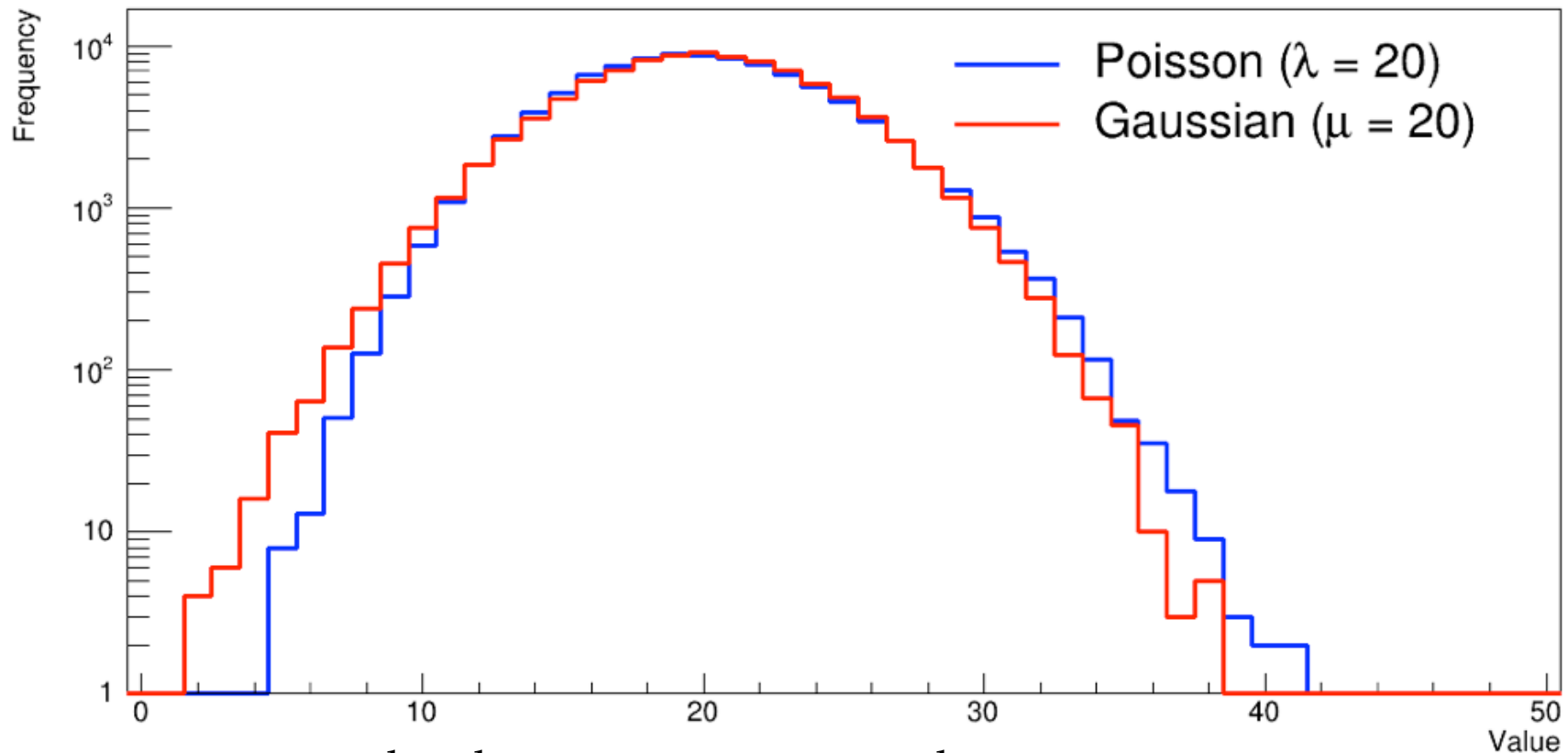


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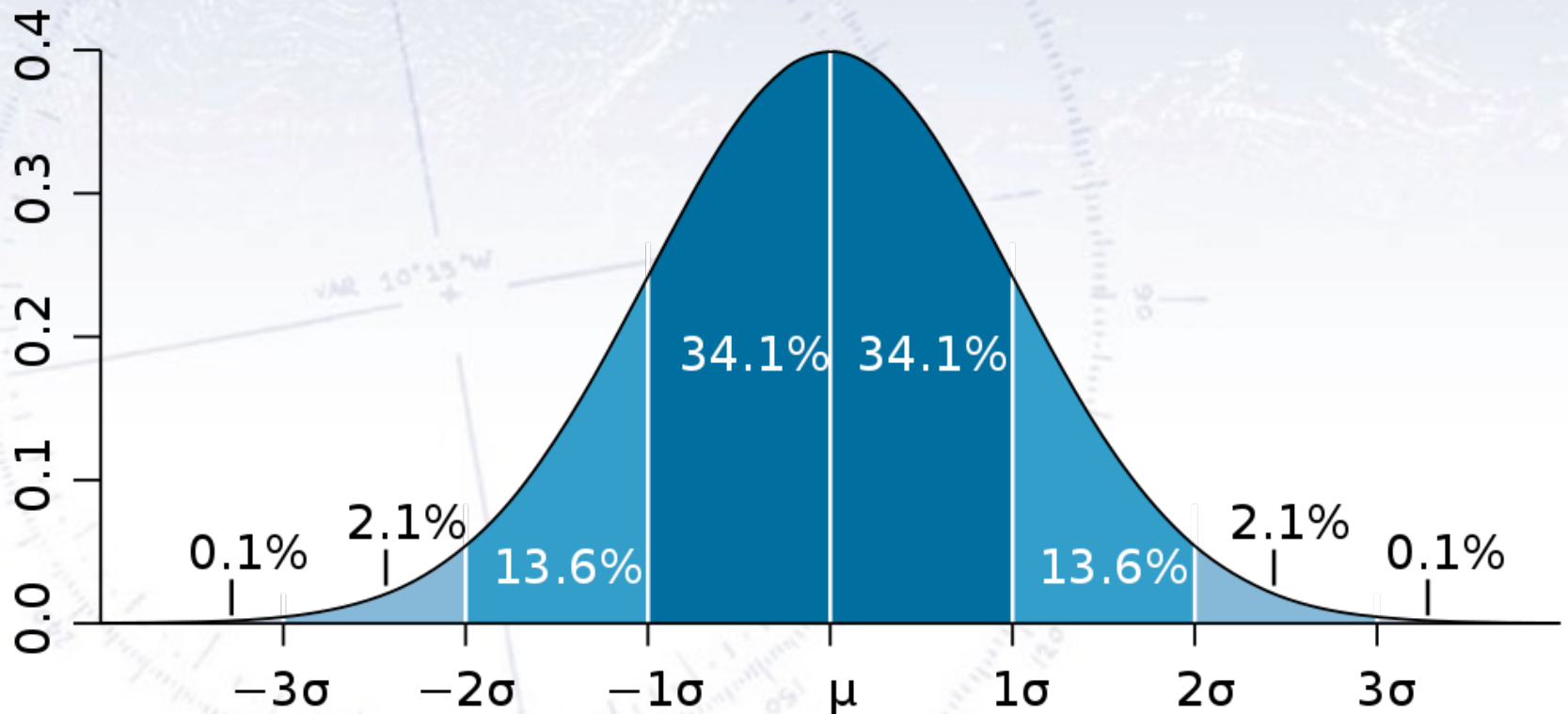


However, note that the TAILS are not quite the same!!!

This is the very reason for the difference between Chi2 and (binned) likelihood!

# Binomial, Poisson, Gaussian

*“If the Greeks had known it, they would have deified it.”*

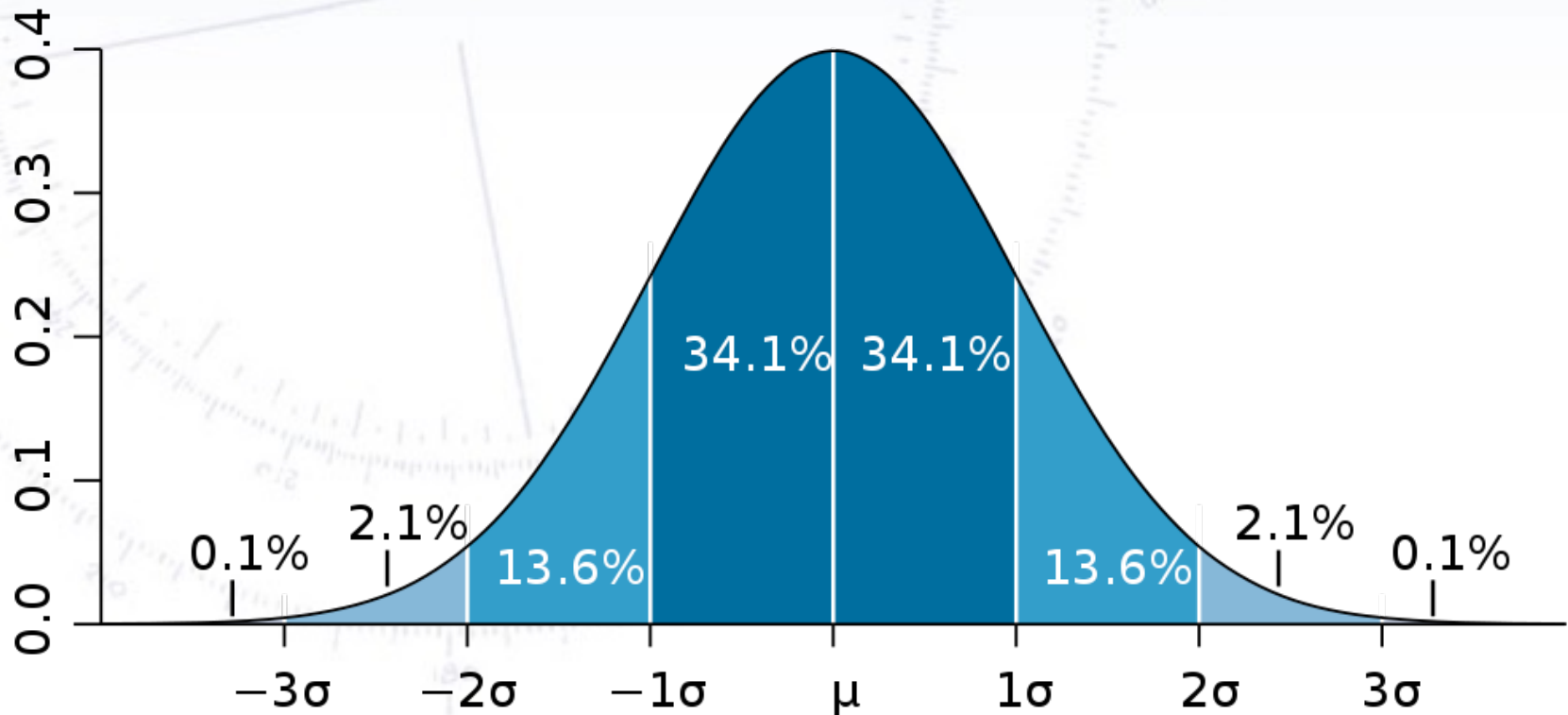


*“If the Greeks had known it, they would have deified it. It reigns with serenity and in complete self-effacement amidst the wildest confusion. **The more huge the mob and the greater the apparent anarchy, the more perfect is its sway.** It is the supreme Law of Unreason. Whenever a large sample of chaotic elements are taken in hand and marshalled in the order of their magnitude, an unsuspected and most beautiful form of regularity proves to be latent all along.” [Karl Pearson]*

# Binomial, Poisson, Gaussian

The Gaussian defines the way we consider uncertainties.

Range	Inside	Outside
$\pm 1\sigma$	<b>68 %</b>	32 %
$\pm 2\sigma$	<b>95 %</b>	5 %
$\pm 3\sigma$	<b>99.7 %</b>	0.3 %
$\pm 5\sigma$	99.99995 %	0.00005 %



# Student's t-distribution

Given only a small (n obs.) sample (still assumed Gaussian), we don't know the mean  $\mu$  and width  $\sigma$  well - we only know estimates of them! This changes the PDF to:

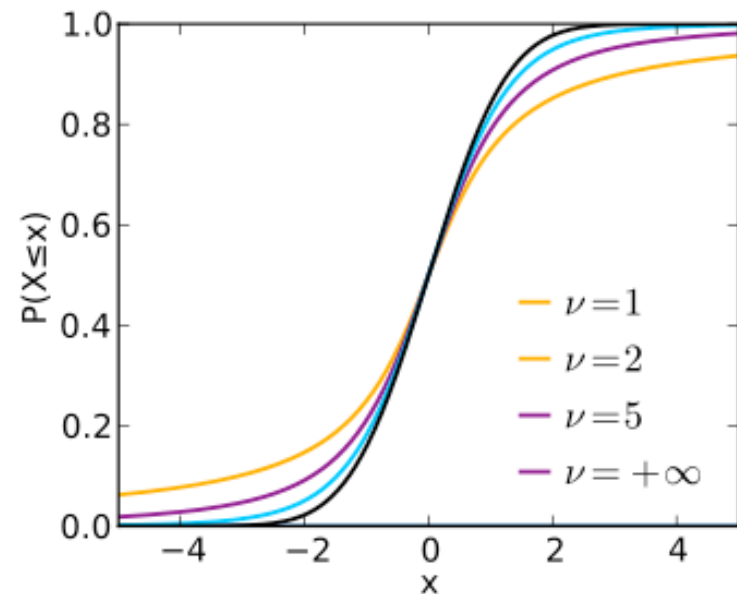
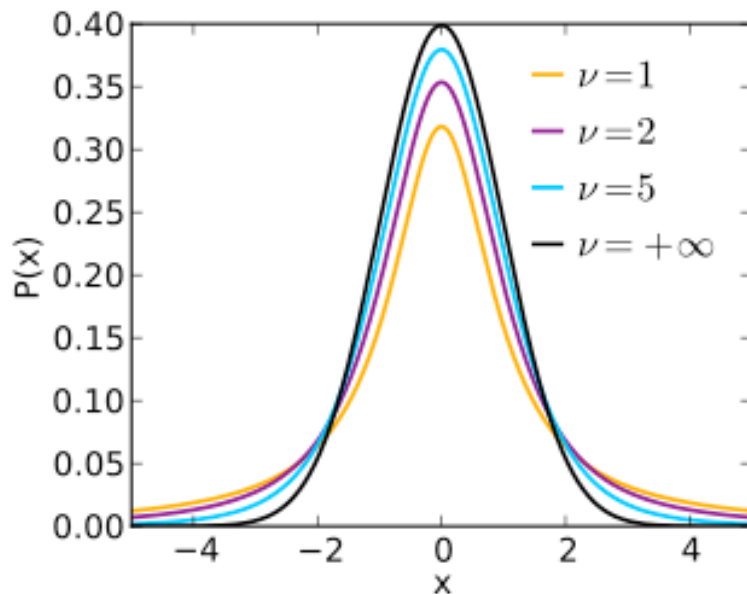
$$p(x | \nu, \hat{\mu}, \hat{\sigma}^2) = \frac{\Gamma(\frac{\nu+1}{2})}{\Gamma(\frac{\nu}{2}) \sqrt{\pi\nu\hat{\sigma}^2}} \left( 1 + \frac{1}{\nu} \left( \frac{x - \hat{\mu}}{\hat{\sigma}} \right)^2 \right)^{-\frac{\nu+1}{2}} \quad \nu = N_{\text{DoF}} = n - 1$$

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“Discovered” by William Gosset, student's t-distribution takes into account the **lacking knowledge of the mean and variance** (as is the case for small samples).

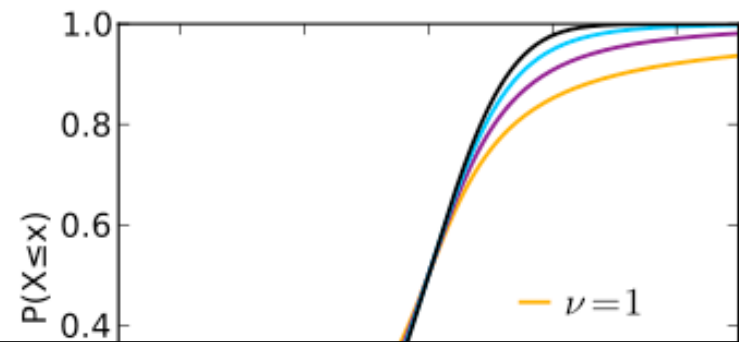
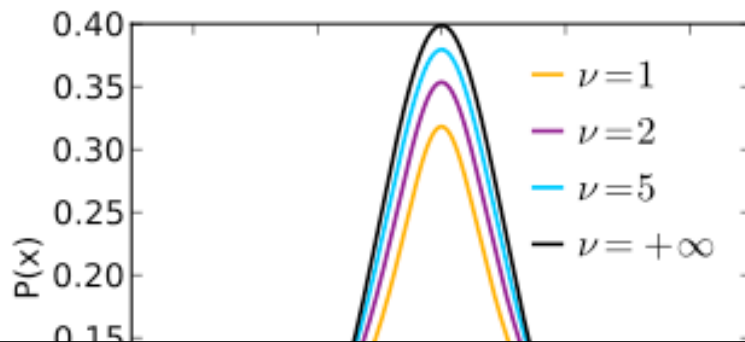


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“Discovered” by William Gosset, student's t-distribution takes into account the **lacking knowledge of the mean and variance** (as is the case for small samples).



When mean and width are poorly known, estimating it from sample gives:

**Gaussian:**  $z = \frac{x - \mu}{\sigma}$

**Student's:**  $t = \frac{x - \hat{\mu}}{\hat{\sigma}}$



# Exponential distribution

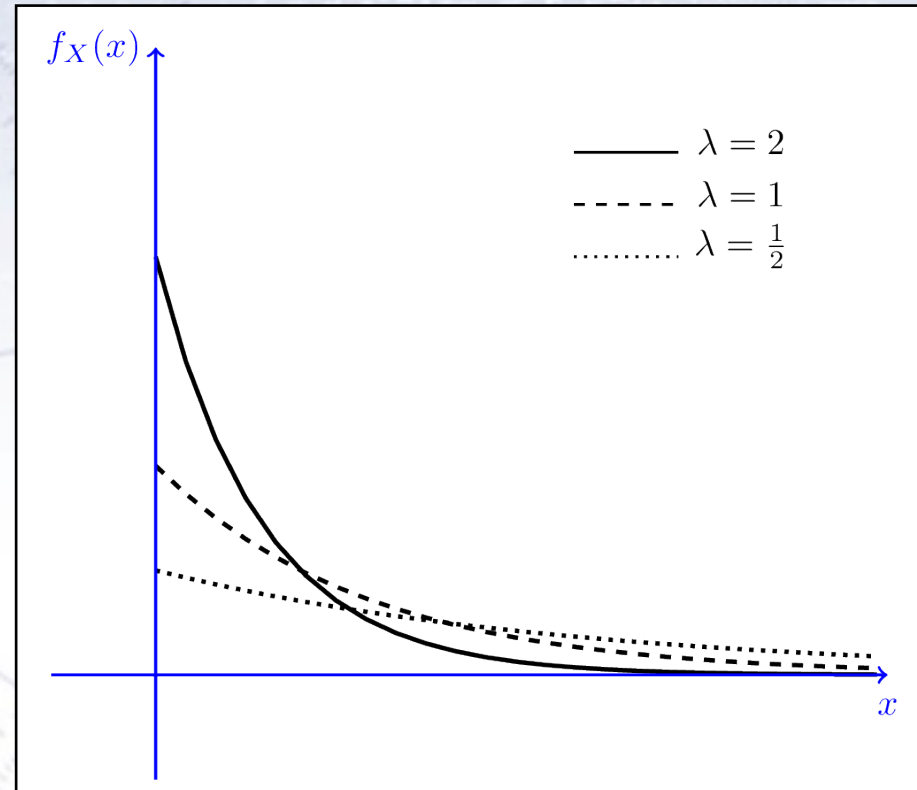
One particularly important PDF is the exponential distribution:

$$f(x) = \lambda e^{-\lambda x}$$

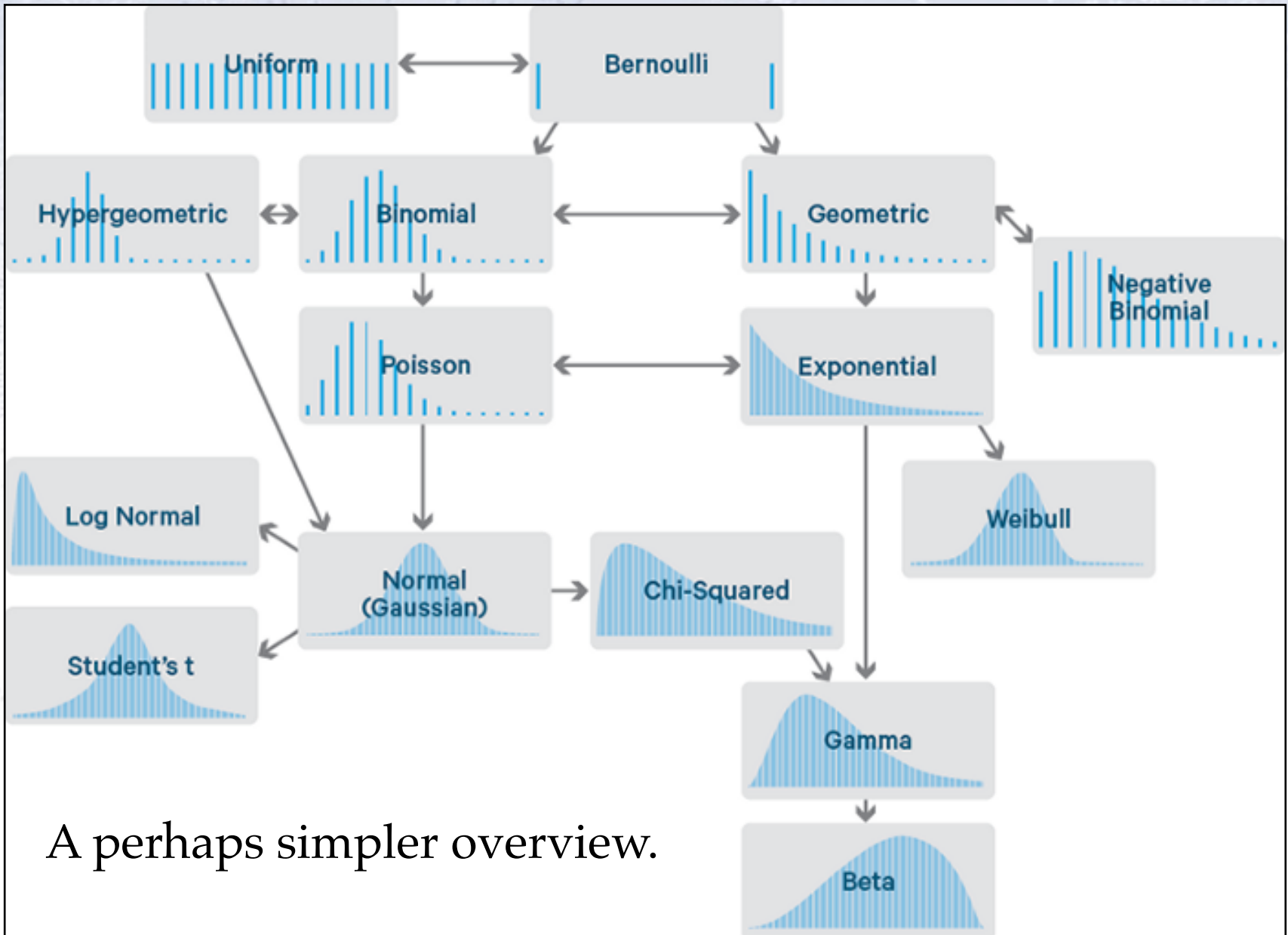
It has mean value  $1/\lambda$  and width  $1/\lambda$ .

Its importance comes from the fact that:  
*If a process occurs with a constant rate, the distribution of time before the event happens will be exponentially distributed*

This is really the case for many systems. Of course the most prominent example is the decay of particles/cells/etc.

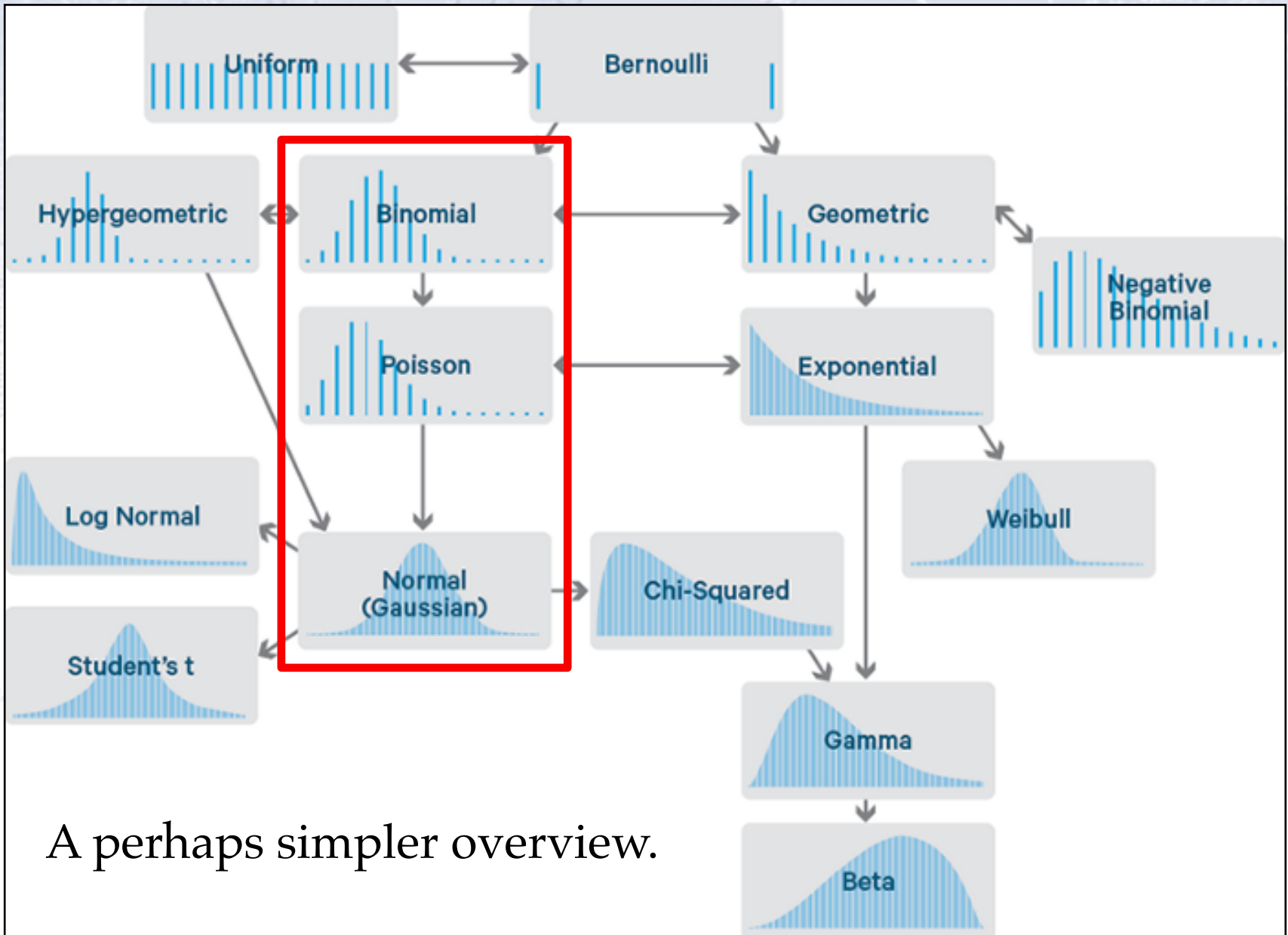


# Distribution Overview



A perhaps simpler overview.

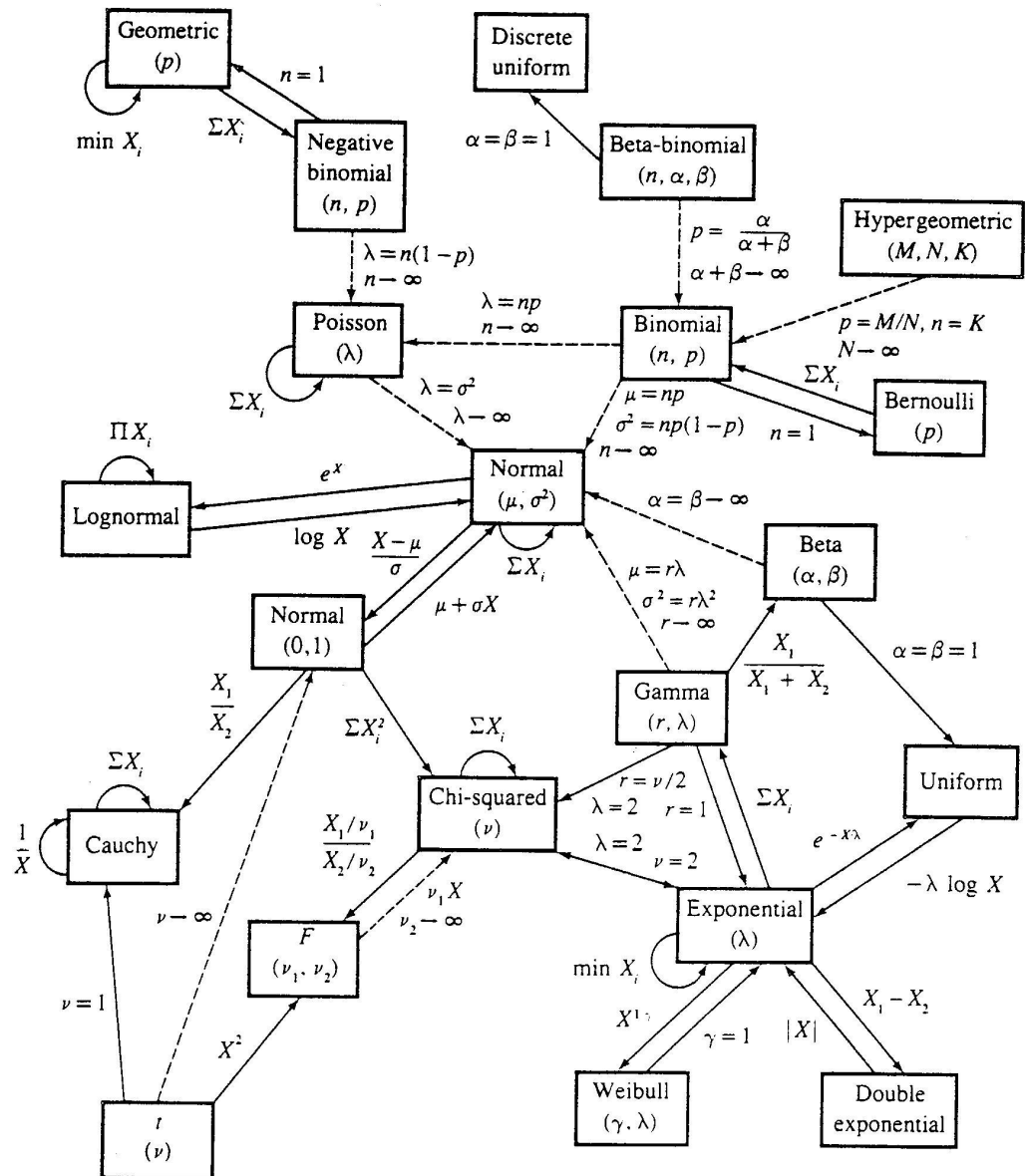
# Distribution Overview



# Distribution Relationship

The different PDFs are related.

As can be seen, essentially all PDFs “converges” towards the Gaussian (normal) distribution.



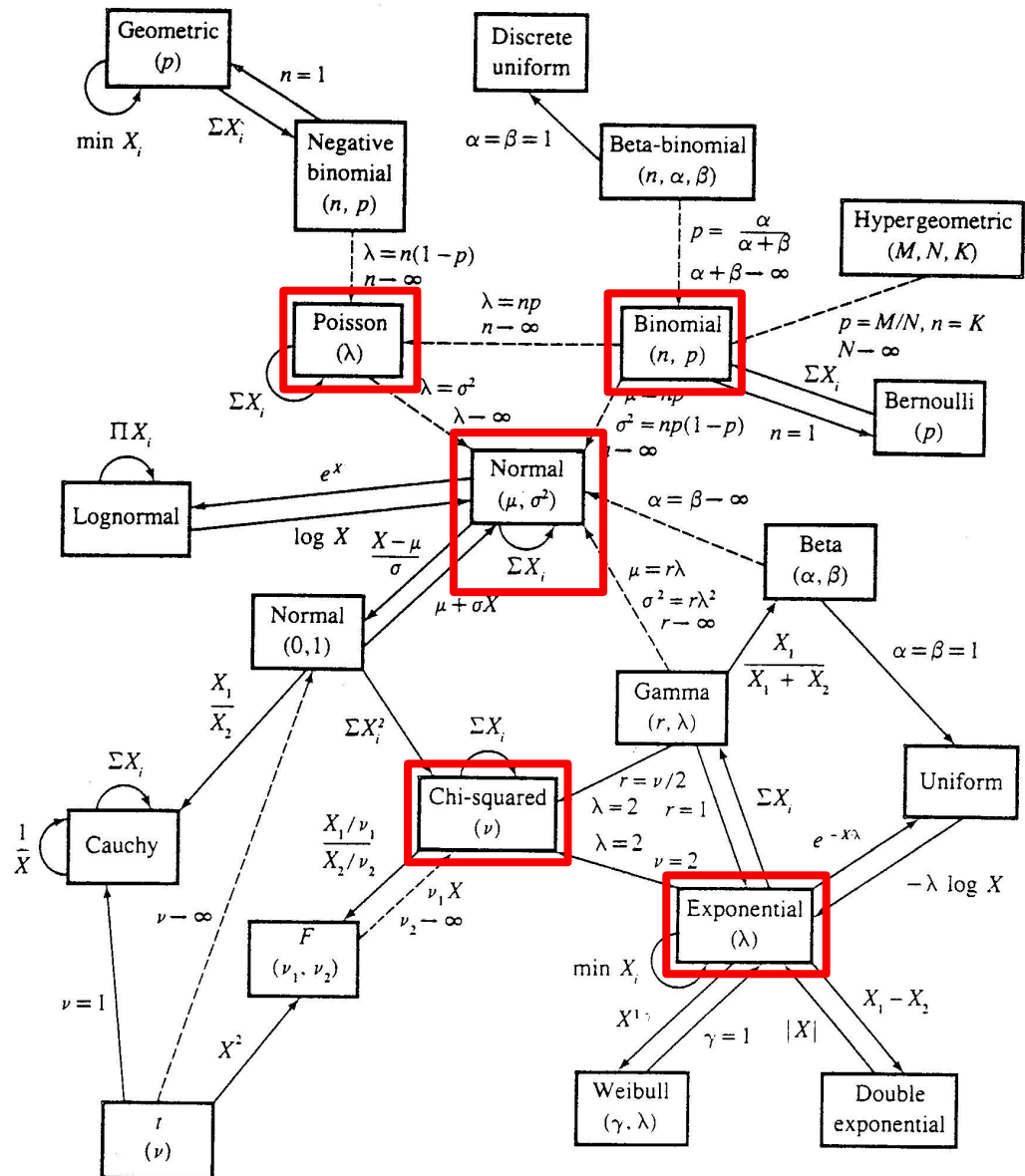
**Relationships among common distributions.** Solid lines represent transformations and special cases, dashed lines represent limits. Adapted from Leemis (1986).

# Distribution Relationship

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Don't worry about knowing them all.... Through a long life in statistics, I have still yet to encounter all of these in use!

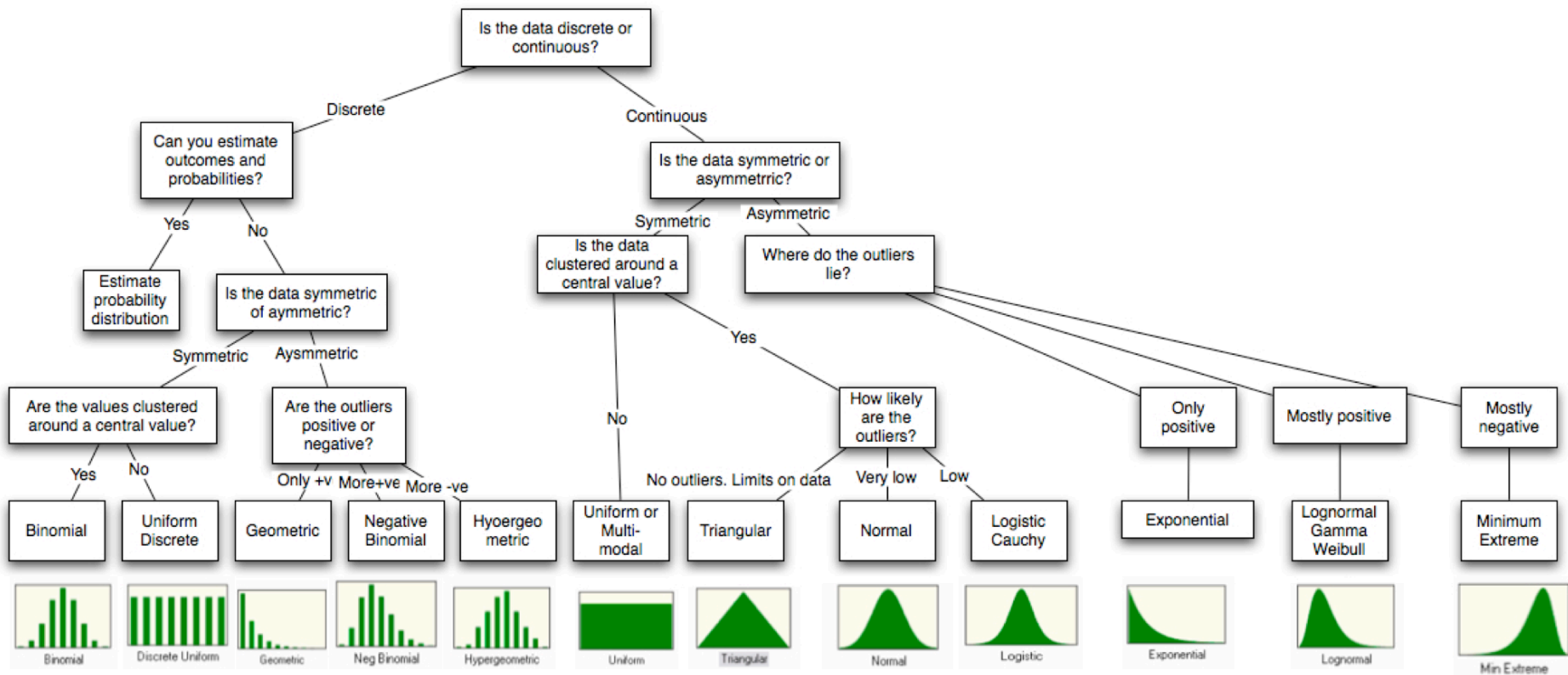


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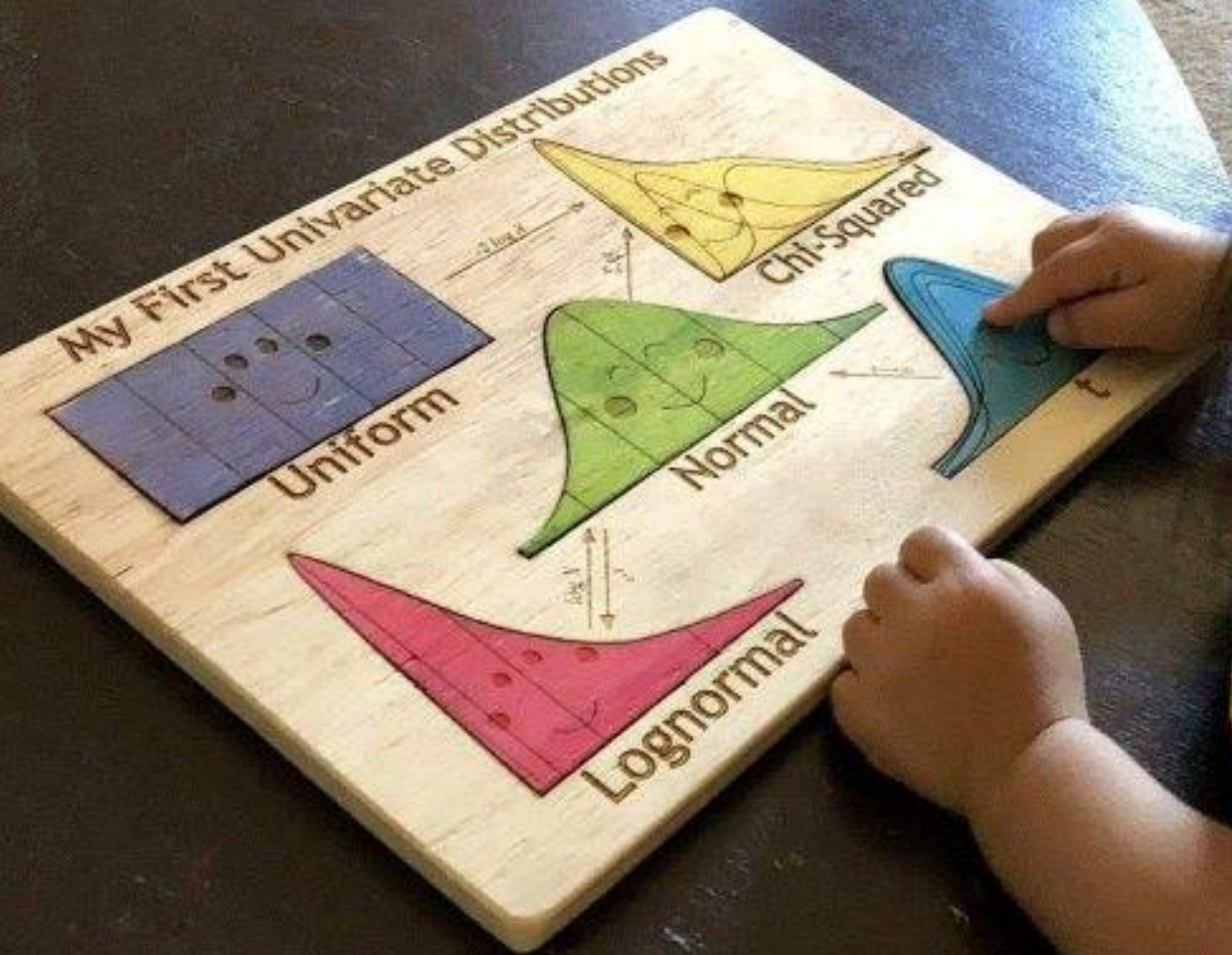
# Distribution Overview

I like the following overview of the most common PDFs, though it is far from perfect. However, it shows what makes the essential differences between PDFs.

## Distributional Choices/Identification



# Distribution Overview



# Summary of lecture

All PDFs are normalized functions, that describe the probability of getting a certain value / outcome from evaluating the PDF function.

Among the most fundamental PDFs are the Binomial, Poisson and Gaussian.

Remember that the error on a (Poisson) number is **the square root** of that number!

Remember that the Gaussian distribution defines the uncertainties, that we report on experiments.