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Power-law distributions in empirical data

Article summary

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What follows is a summary of the article "Powerlaw distributions in empirical data" by Aaron Clauset, Cosma Rohilla Shalizi and M.E.J. Newman (ref. [1]). The article presents tools to analyze datasets w.r.t. power-laws. Power-laws occur in diverse scientific fields and are made difficult to characterize due to large tailfluctuations. It is therefore of scientific interest to develop methods for analyzing data hypothesized to follow such a distribution.

After introducing discrete and continuous power-laws, the article describes the maximum likelihood estimators for relevant parameters for both continuous and discrete distributions, and subsequently goes through goodnessof-fit test. Finally, the methods introduced are applied to 24 real-world datasets. This summary follows a similar structure emphasizing the methodology.

Power-law distributions. A quantity x obeys a power-law if it is drawn from a distribution proportional to $x^{-\alpha}$. The parameter α is known as the *scaling parameter*. A given quantity commonly obeys the power law only in some subinterval of $(0, \infty)$. Lower and upper bounds x_{\min} and x_{\max} for the power law may be introduced. The article [1] only considers distributions unbounded from above. For the doubly bounded discrete case, see e.g. ref. [2]. The normalized continuous distribution has probability density function (PDF)

$$p(x) = \frac{\alpha - 1}{x_{\min}} \left(\frac{x}{x_{\min}}\right)^{-\alpha}, \qquad (1)$$

whereas normalized discrete distribution has probability mass function $(PMF)^1$

$$p(x) = \frac{x^{-\alpha}}{\zeta(\alpha, x_{\min})} \,. \tag{2}$$

 $\zeta(\alpha, x_{\min})$ is the generalized or Hurwitz zeta-function $\zeta(\alpha, x_{\min}) = \sum_{n=0}^{\infty} (n + x_{\min})^{-\alpha}.$

Note also the definitions of the complementary cumulative distribution function (CDF) for the continuous case, $P(x) = \int_x^{\infty} p(x')dx' = (x/x_{\min})^{-\alpha+1}$, and for the discrete case, $P(x) = \sum_{y=x}^{\infty} p(y) = \zeta(\alpha, x)/\zeta(\alpha, x_{\min})$. **Parameter estimation.** The article [1] discusses the estimation of distribution parameters α and x_{\min} . Following article notation, estimators are denoted by "hatted" symbols, e.g. $\hat{\alpha}$ is the maximum likelihood estimator (MLE) for α .

Since a power-law becomes linear in a log-log plot, a common approach is to perform a linear least squaresfit to binned data on a log-log plot. This method is demonstrated to be inaccurate regardless of binning convention, as is also displayed in Figure 1.

Continuous distribution α MLE. For observations $\{x_i\}_{i \in \mathbb{N}}$, the MLE for the scaling parameter is given by

$$\hat{\alpha} = 1 + n \left(\sum_{i=1}^{n} \ln \frac{x_i}{x_{\min}} \right)^{-1} \tag{3}$$

with corresponding standard error $\sigma = (\hat{\alpha} - 1)/\sqrt{n} + O(1/n)$. *n* is the number of observations.

Discrete distribution α **MLE.** Generalized to arbitrary integer x_{\min} , the MLE $\hat{\alpha}$ for the discrete case is found by maximizing the likelihood

$$\mathcal{L}(\alpha) = -n \ln \zeta(\alpha, x_{\min}) - \alpha \sum_{i=1}^{n} \ln x_i \qquad (4a)$$

as a function of α , or equivalently solving the equation

$$\frac{\zeta'(\hat{\alpha}, x_{\min})}{\zeta(\hat{\alpha}, x_{\min})} = -\frac{1}{n} \sum_{i=1}^{n} \ln x_i.$$
 (4b)

The standard error on this $\hat{\alpha}$ may be estimated as

$$\sigma = \frac{1}{\sqrt{n}} \left(\frac{\zeta''(\hat{\alpha}, x_{\min})}{\zeta(\hat{\alpha}, x_{\min})} - \left(\frac{\zeta'(\hat{\alpha}, x_{\min})}{\zeta(\hat{\alpha}, x_{\min})} \right)^2 \right)^{-1/2}$$
(4c)

Estimating the lower bound x_{\min} . The article also discusses the estimation of the lower bound. The estimate of α is highly dependent on accurate estimation of x_{\min} , as is displayed in Figure 2—underestimating x_{\min} will include non-power-law data whereas overestimating it will discard valid power-law data, increasing sensitivity to statistical fluctuation. Two estimators

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¹This summary tries to match the notation of the article. Thus depending on context, x represents either a discrete or a continuous variable, p(x) represents a PDF or a PMF, etc.



Figure 1: Figure 3.2 from article [1]. Comparison of different parameter estimation methods for α with data drawn from (a) discrete and (b) continuous distributions, namely: the discrete MLE (3), the continuous MLE (4b), a linear least squares fit to constant-width bins of PDF, and a linear least squares fit to the CDF rank-frequency plot. Note how poorly all shown estimators, with the exception of the relevant MLE, perform.

are presented and tested on a particular sampled distribution. The second one is found to perform better, although both are described as reasonable.

The first estimator relies on an approximation known as a *Bayesian information criterion* (BIC) and mentioned to be valid for only discrete distributions. To estimate x_{\min} , one models the distribution as a set of independent probabilities for the discrete events below x_{\min} in combination with the expected power-law above, and then maximizes the marginal likelihood for x_{\min} .

The alternate estimator (KS), valid for both discrete and continuous data, maximizes the similarity between the best-fit power-law and the empirical distribution. Similarity between CDFs of the data S(x) and the fit P(x) is here described by the Kolmogorov-Smirnov (KS) test statistic

$$D = \max_{x \ge x_{\min}} |S(x) - P(x)|, \tag{5}$$

but any test statistic can in principle be used. Minimizing D as a function of x_{\min} yields an estimate for x_{\min} . Alternate test statistics are proposed, in particular a modified KS test statistic, re-weighted to distribute sensitivity uniformly across the entire data range.

Goodness-of-fit tests and model comparison. A Monte Carlo procedure for performing goodness-of-fit tests on fitted datasets is described, Using parameters obtained through the methods described in the previous sections, a number of synthetic datasets are sampled from a distribution with the same parameter values. The KS statistic is then calculated for the synthetic



Figure 2: Figure 3.3 from article [1]. For a sampled true distribution ($\alpha = 2.5$ and $x_{\min} = 100$) with power-law behavior beyond x_{\min} , this shows how the estimate of α depends on the chosen cut-off (the lowest value of any fitted point) x_{\min} . The α -estimate appears relatively forgiving when overestimating x_{\min} , however also appears to quickly deteriorate with underestimation.

datasets and the p-value for the original dataset is then given as the fraction of synthetic datasets that perform worse than the original data in the KS test. Note that in this case, a larger p-value indicates a "better" fit to the data. Datasets with $p \leq 0.1$ are rejected.

For comparing plausibility different models for a given dataset, the article proposes comparison based on the likelihood ratio between the two models. This method may be used to reject a model in comparison with another and a p-value for the statistical significance of the rejection is computed based on ref. [3].

Application to real-world data. Finally, the methods just described are applied to 24 real-world datasets from a diverse series of fields, estimating scaling parameters and comparing different heavy-tailed distributions. One key observation is that the distinction between a log-normal and a power-law distribution is very difficult. For some datasets, scaling parameter estimates incompatible with previously published estimates are found, suggesting reevaluation of any resultant conclusions.

References.

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