



UNIVERSITY OF
COPENHAGEN



The Good, the Bad and the Noisy

Characterisation of IceCube Neutrino Events Using Graph Neural Networks

Master Thesis Defense in Computational Physics

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June 27th 2022

Supervised by Troels Christian Petersen

Introduction

Theory & Motivation
Machine Learning in IceCube
Current State of Affairs

My Work

Time Regression
Event Cleaning
Upgrade Pulse Cleaning
Regression of Cleaned Pulses

Intermezzo 1: Improvement of Pulse Cleaning
Intermezzo 2: Quality of Cleaned Events

Conclusions & Outlook

Introduction

Theory & Motivation

Neutrinos & the Standard Model

Neutrino Oscillations

Machine Learning in IceCube

Current State of Affairs

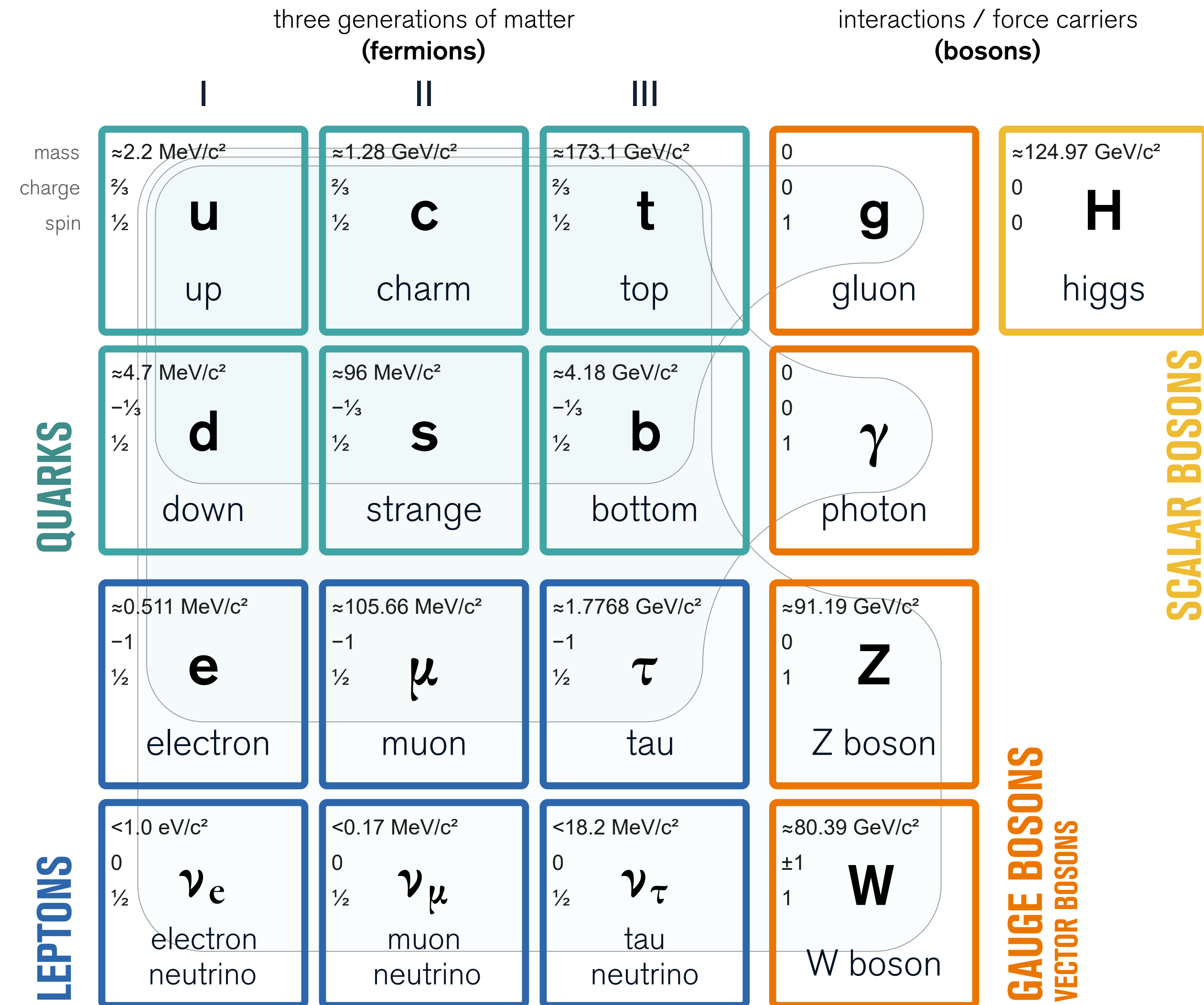
My Work

Conclusions & Outlook

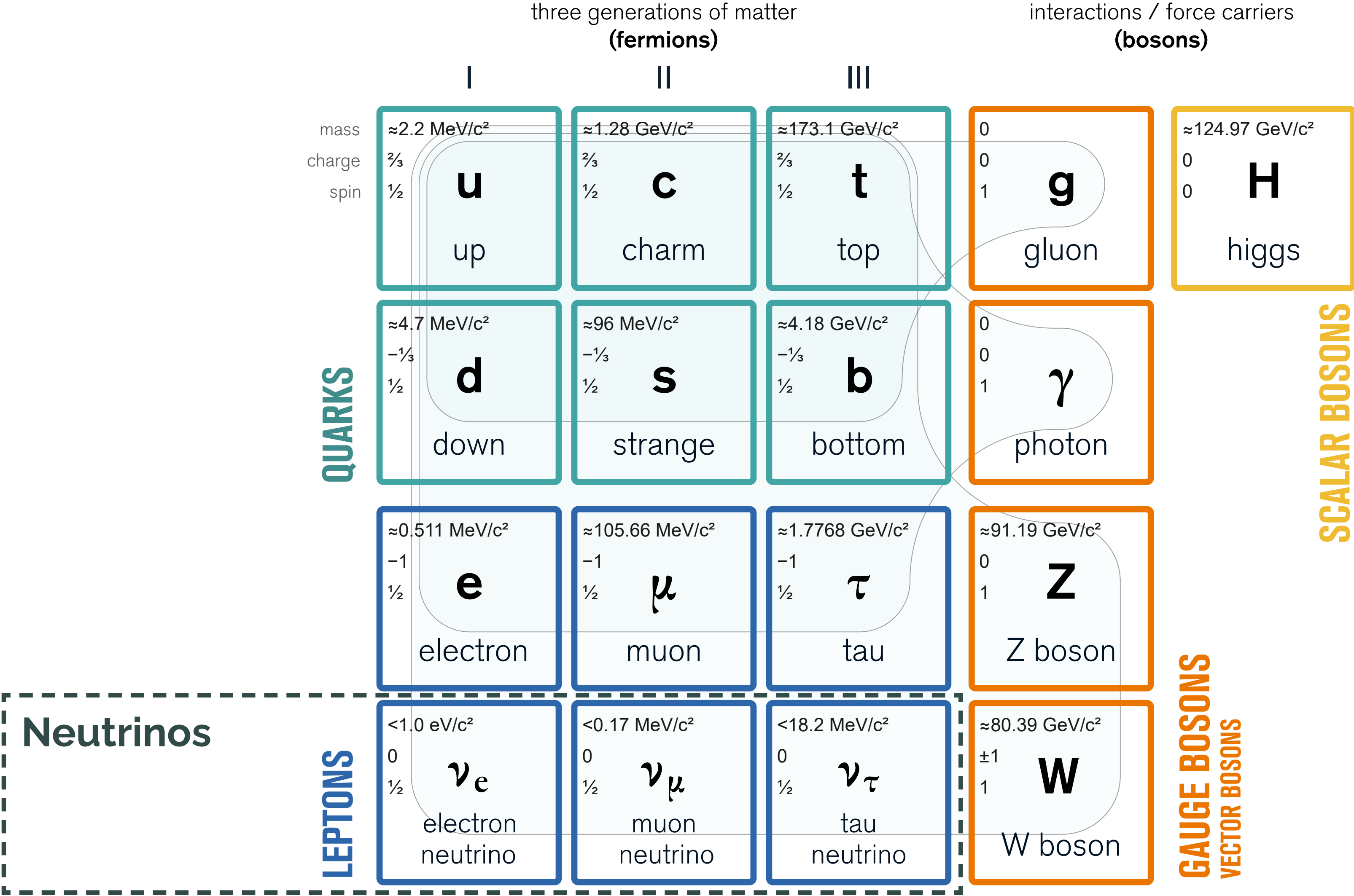
Coherent description of matter and its behavior

Rigorously tested

Incomplete



Neutrinos

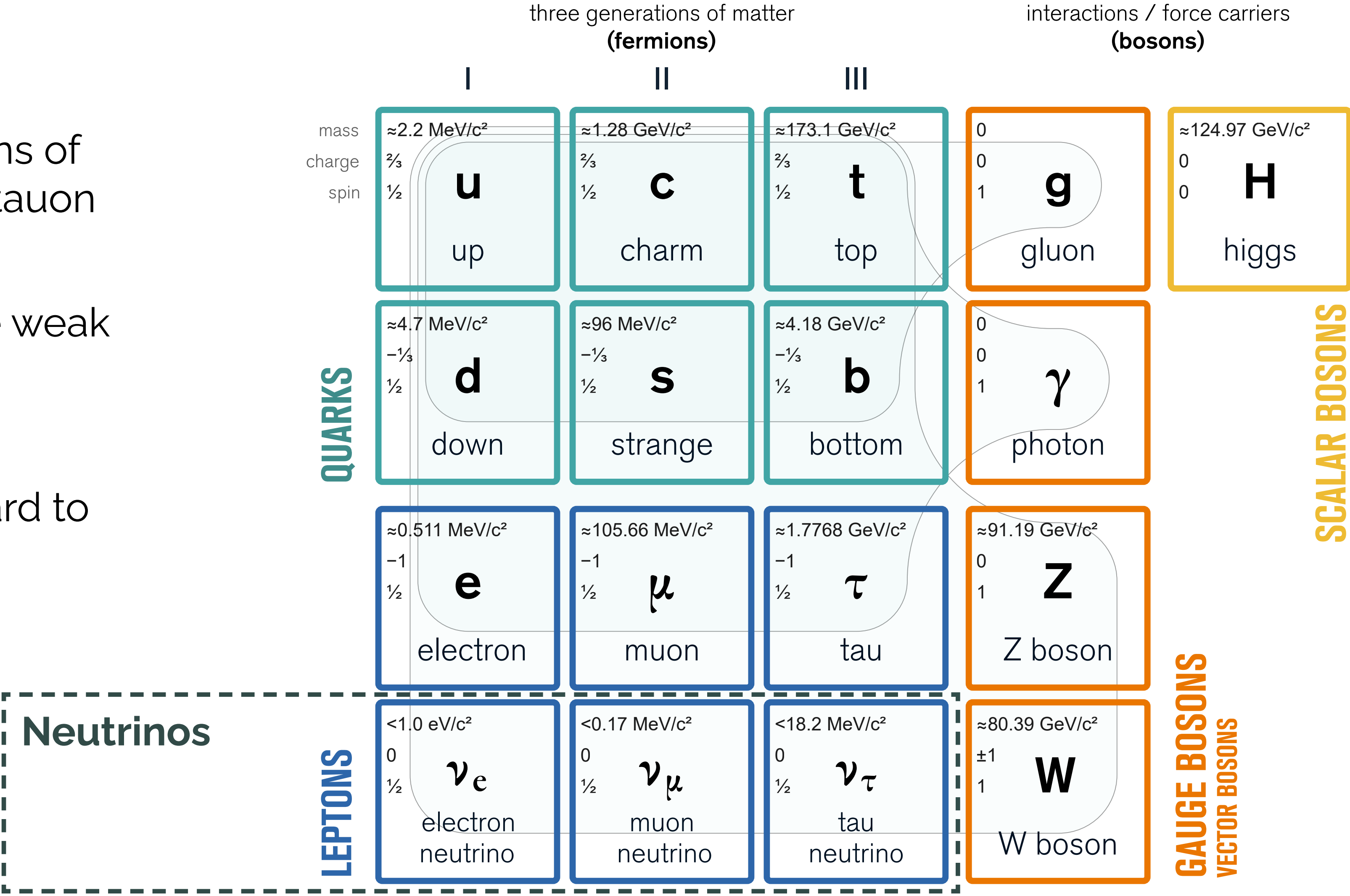




Light and neutral cousins of the eletron, muon and tauon

Interact only trough the weak force (and gravity)

Overly abundant but hard to observe



Unexpected ratios of neutrino
flavours observed in experiments

Probability of observing a given flavour
changes with distance travelled

Neutrino oscillations!

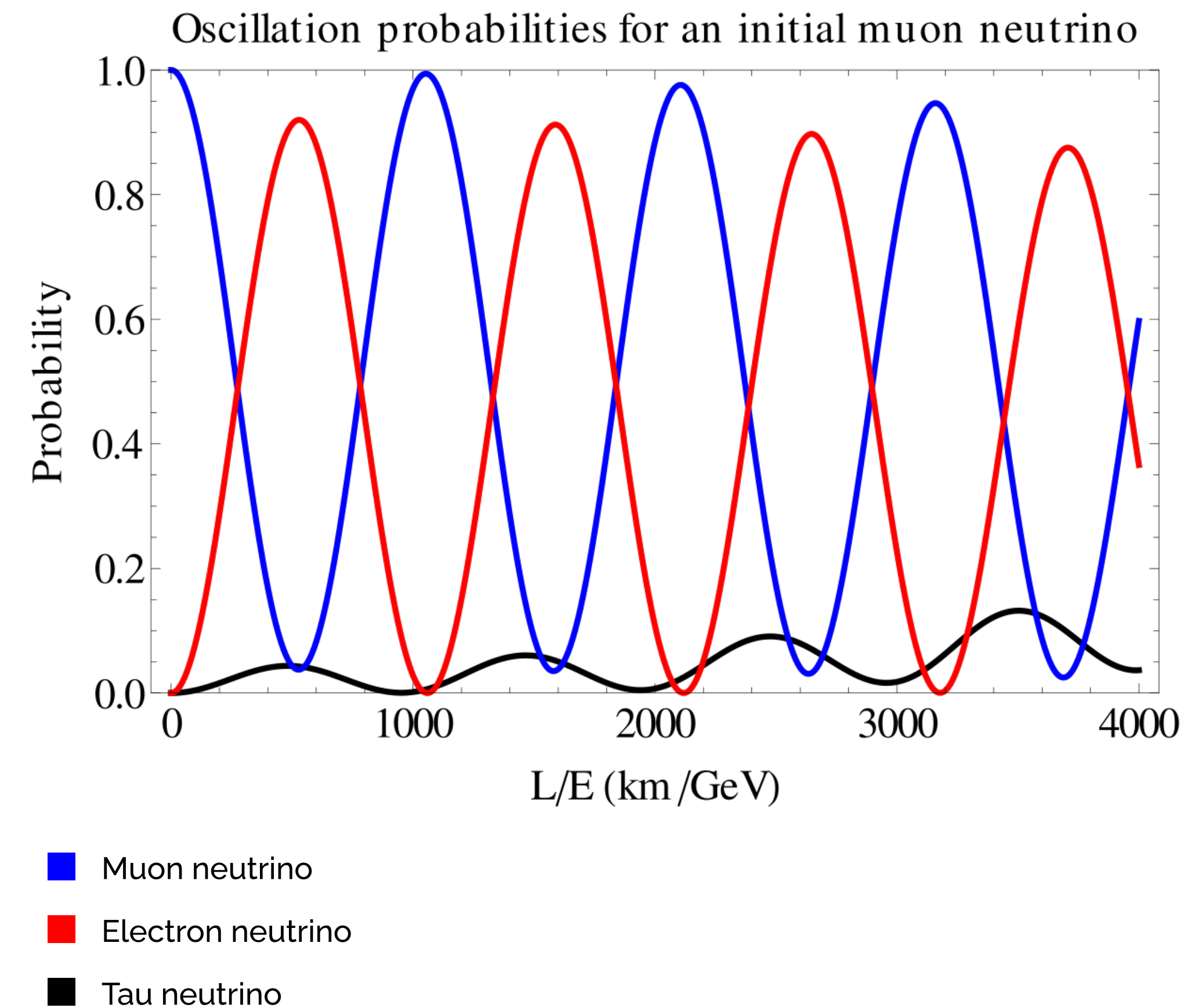


Figure from https://en.wikipedia.org/wiki/Neutrino_oscillation

| Eigenstates of weak interactions: ν_e, ν_μ, ν_τ

| Eigenstates of free propagation: ν_1, ν_2, ν_3

| Unitary transformation between the two eigenbases is described by the PMNS-matrix:

$$|\nu_\alpha\rangle = \sum_{k \in 1,2,3} U_{\alpha k}^* |\nu_k\rangle$$

$$\begin{pmatrix} U_{e1} & U_{e2} & U_{e3} \\ U_{\mu 1} & U_{\mu 2} & U_{\mu 3} \\ U_{\tau 1} & U_{\tau 2} & U_{\tau 3} \end{pmatrix}$$

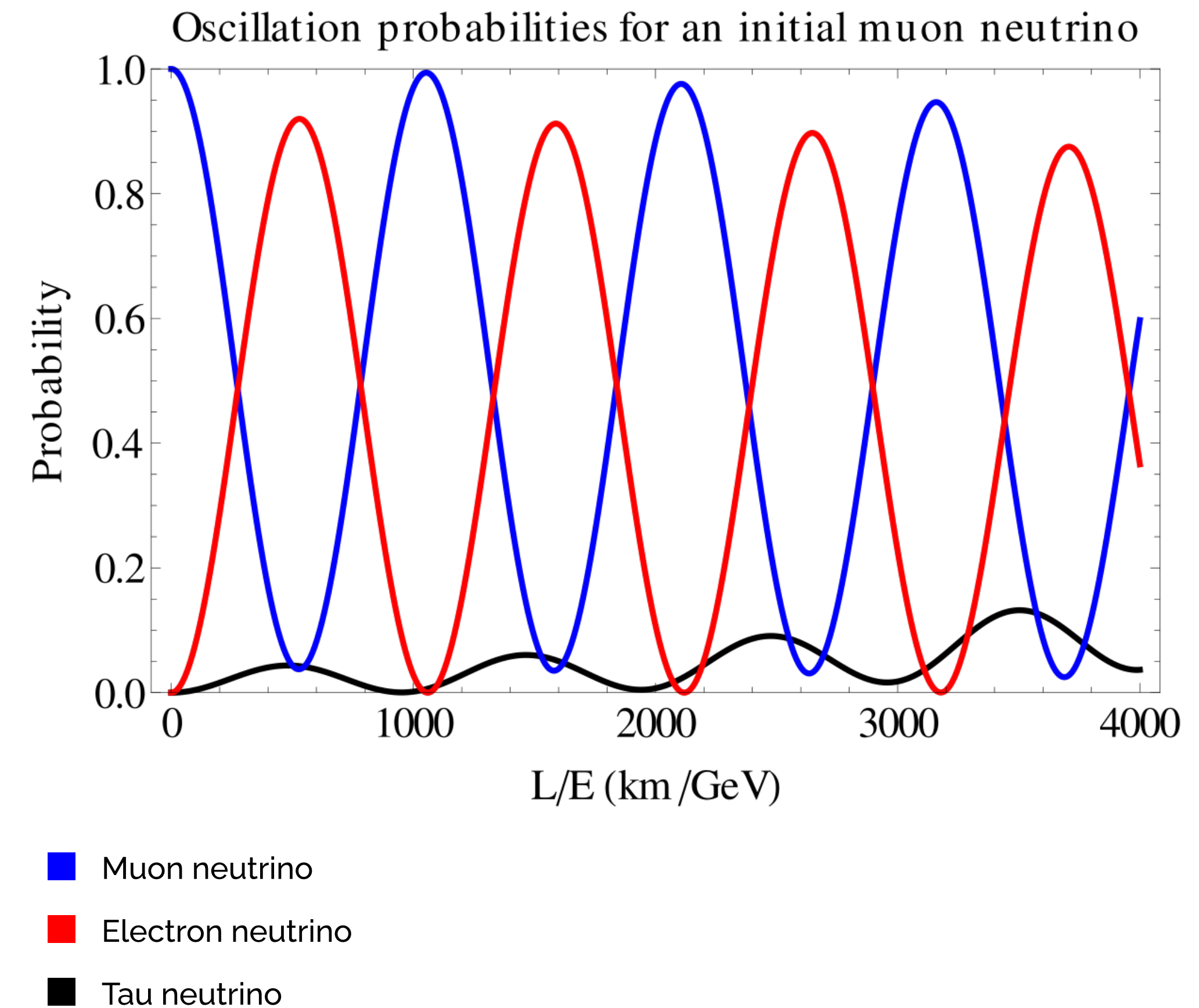


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| Eigenstates of weak interactions: ν_e, ν_μ, ν_τ

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$$|\nu_\alpha\rangle = \sum_{k \in 1,2,3} U_{\alpha k}^* |\nu_k\rangle$$

$$c_{ij} = \cos(\theta_{ij}) \text{ and } s_{ij} = \sin(\theta_{ij})$$

$$\begin{pmatrix} U_{e1} & U_{e2} & U_{e3} \\ U_{\mu 1} & U_{\mu 2} & U_{\mu 3} \\ U_{\tau 1} & U_{\tau 2} & U_{\tau 3} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & c_{23} & s_{23} \\ 0 & -s_{23} & c_{23} \end{pmatrix} \begin{pmatrix} c_{13} & 0 & s_{13}e^{-i\delta_{\text{CP}}} \\ 0 & 1 & 0 \\ -s_{13}e^{i\delta_{\text{CP}}} & 0 & c_{13} \end{pmatrix} \begin{pmatrix} c_{12} & s_{12} & 0 \\ -s_{12} & c_{12} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

| Probability of oscillating from one flavour state to another

$$P(\nu_\alpha \rightarrow \nu_\beta) = \delta_{\alpha\beta} - 2 \sum_{k,l \in 1,2,3} \text{Re} \left(U_{\alpha k}^* U_{\beta k} U_{\alpha l} U_{\beta l}^* \right) \sin^2 \left(\frac{\Delta m_{kl}^2 L}{4E} \right) \\ + \sum_{k,l \in 1,2,3} \text{Im} \left(U_{\alpha k}^* U_{\beta k} U_{\alpha l} U_{\beta l}^* \right) \sin^2 \left(\frac{\Delta m_{lk}^2 L}{2E} \right)$$

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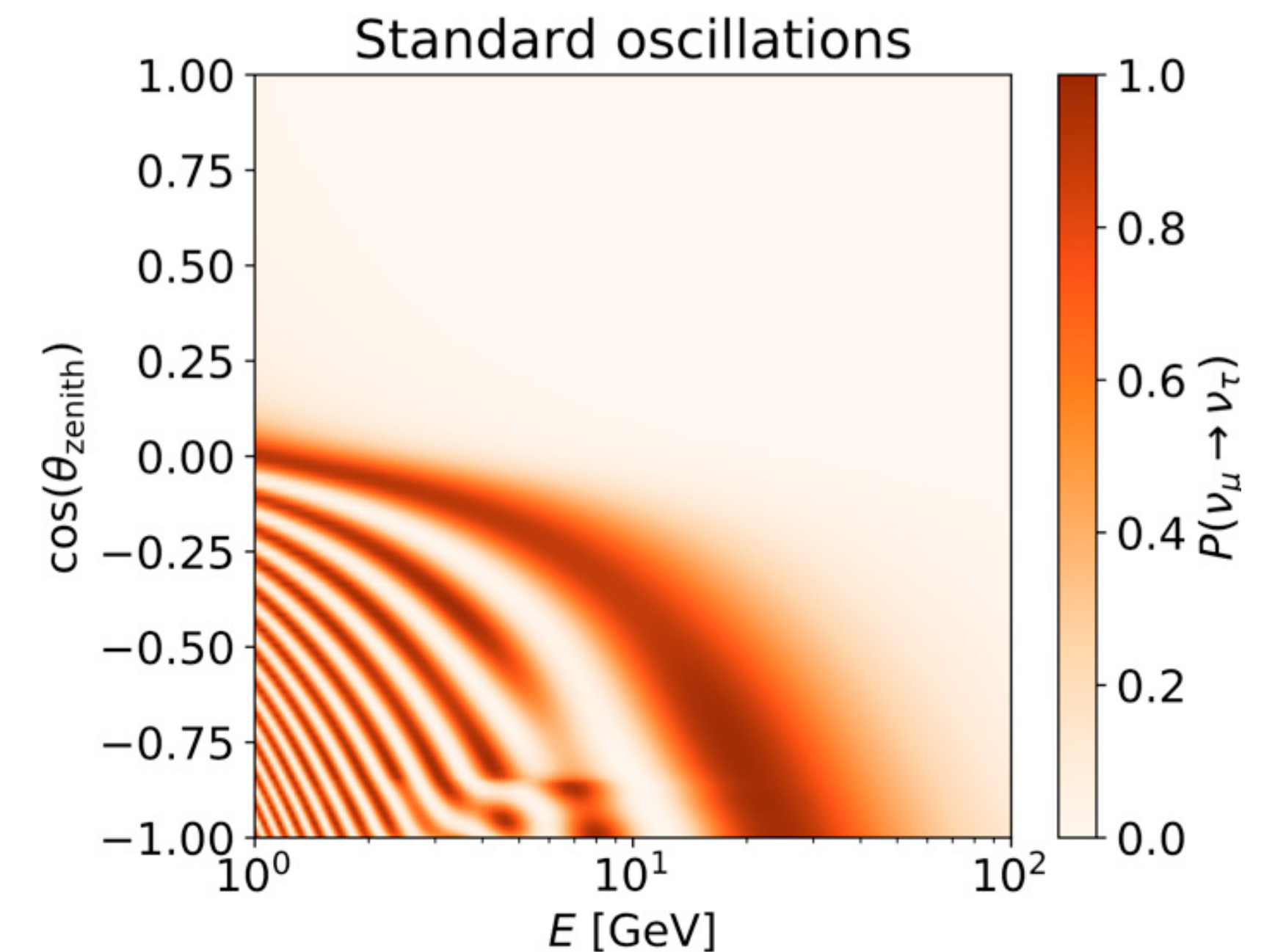
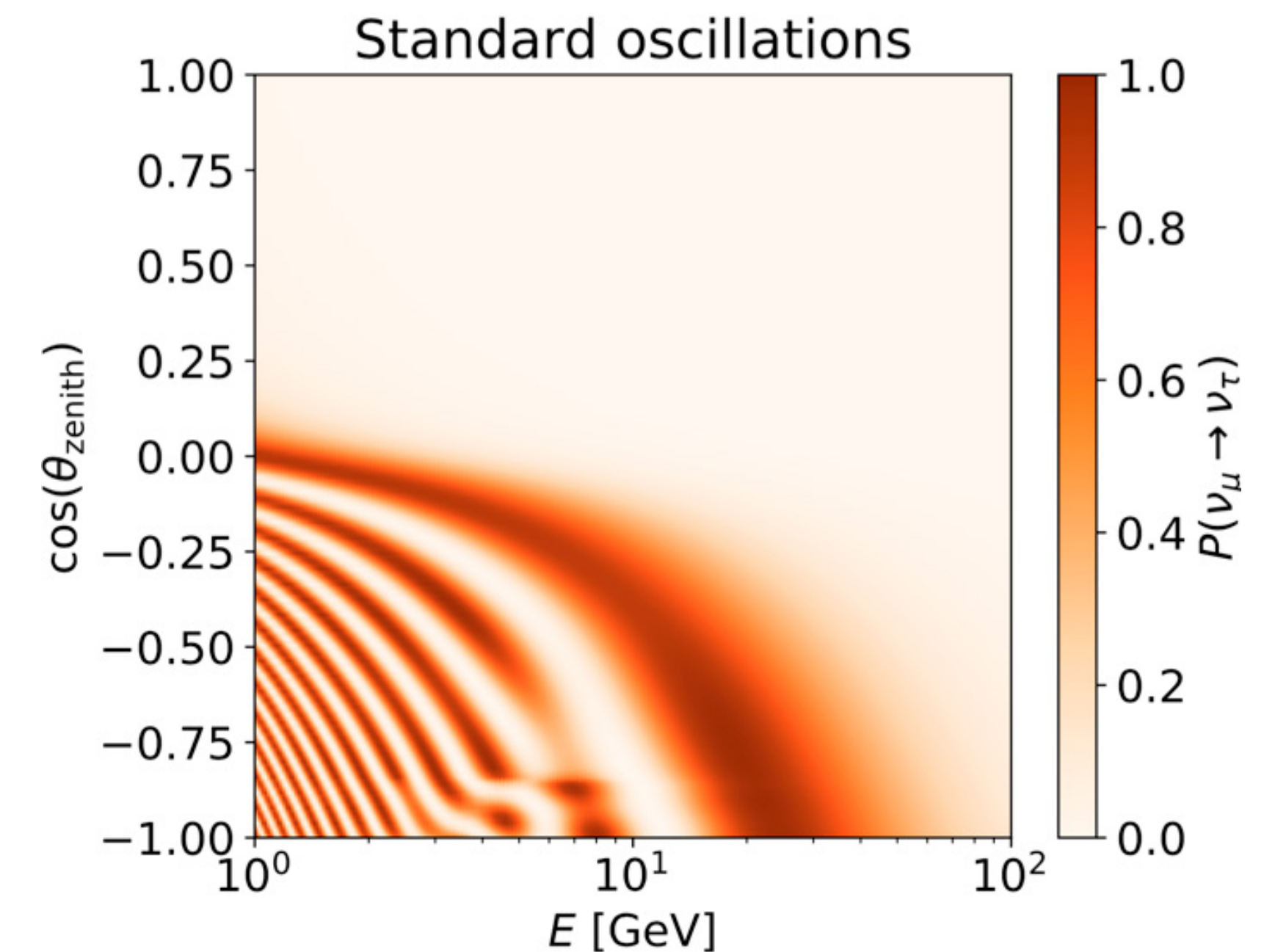


Figure from
<https://nbi.ku.dk/english/research/experimental-particle-physics/icecube/neutrino-oscillation/>

Partial conclusion: Accurate measurement of neutrino energy, direction and flavour composition will enable accurate calculation of PMNS-matrix elements and mass differences.

$$P(\nu_\alpha \rightarrow \nu_\beta) = \delta_{\alpha\beta} - 2 \sum_{k,l \in 1,2,3} \text{Re} \left(U_{\alpha k}^* U_{\beta k} U_{\alpha l} U_{\beta l}^* \right) \sin^2 \left(\frac{\Delta m_{kl}^2 L}{4E} \right) + \sum_{k,l \in 1,2,3} \text{Im} \left(U_{\alpha k}^* U_{\beta k} U_{\alpha l} U_{\beta l}^* \right) \sin^2 \left(\frac{\Delta m_{lk}^2 L}{2E} \right)$$



Introduction

Theory and motivation

Machine Learning in IceCube

IceCube

Events & Event Signatures

Machine Learning

Graphs & GNNs

GraphNeT & DynEdge

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The IceCube Neutrino Observatory

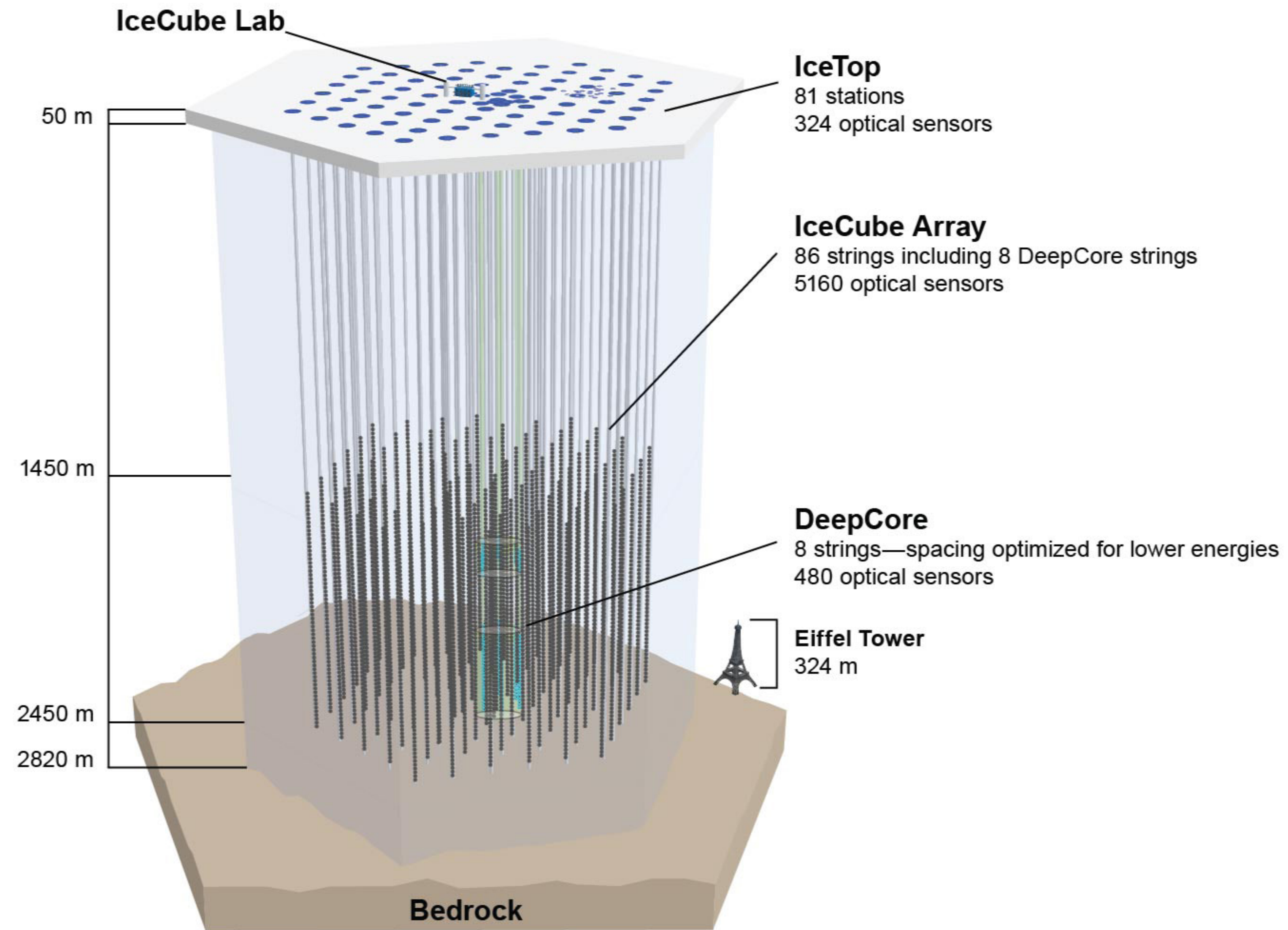
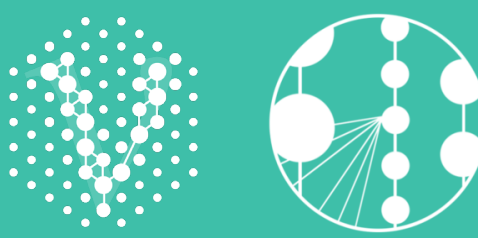
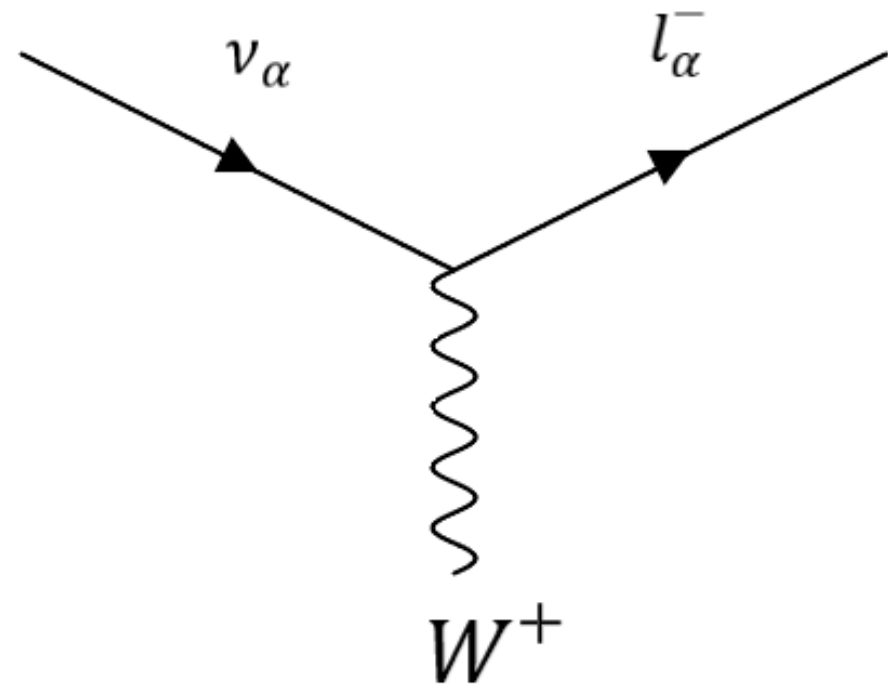
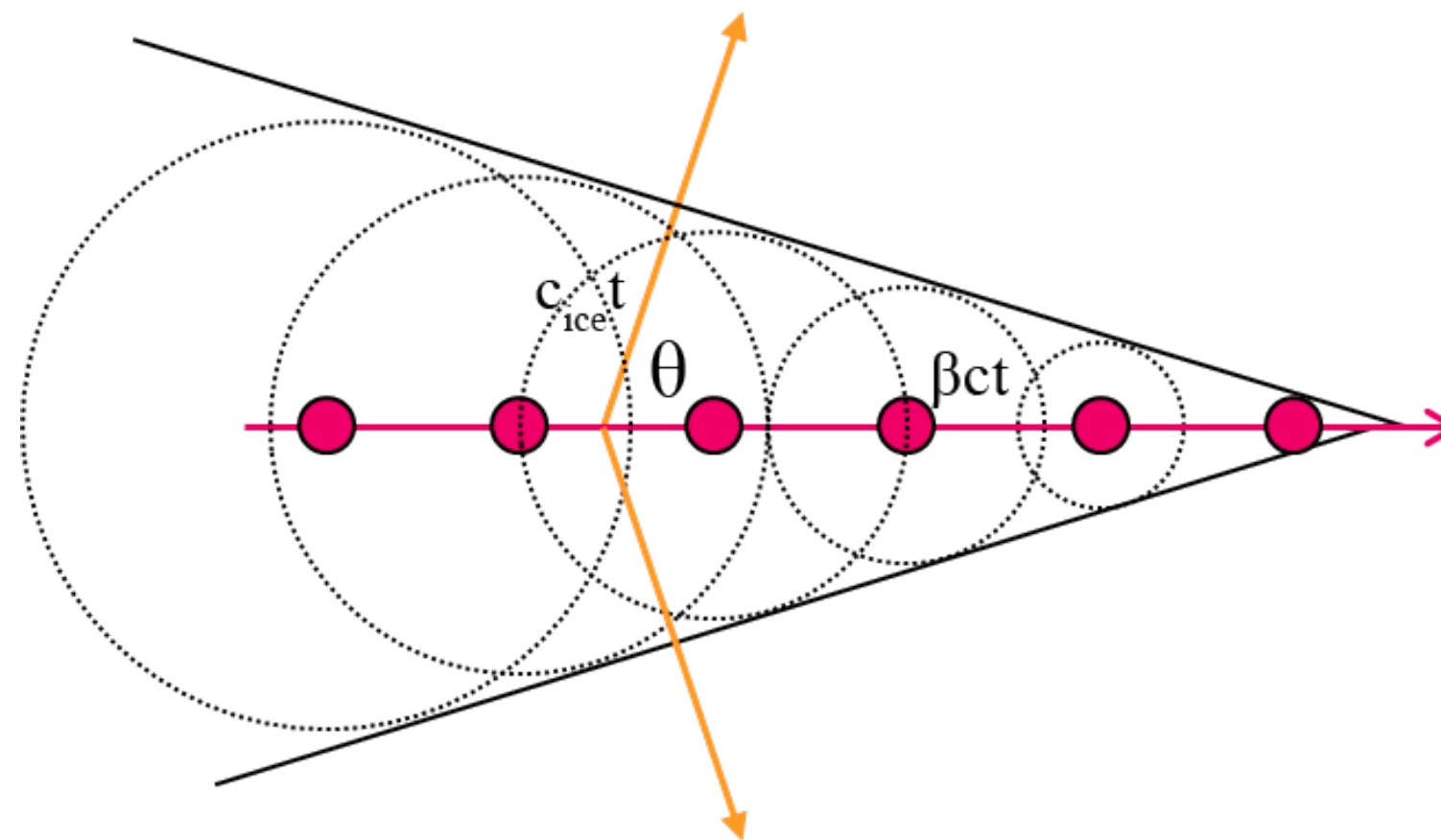


Figure from <https://nbi.ku.dk/english/news/news19/upgrade-of-a-research-icecube/>

Neutrino interaction



Cherenkov Radiation



DOMs



Figure from
<http://large.stanford.edu/courses/2014/ph241/alaedian2/>

Figure from
https://commons.wikimedia.org/wiki/File:ICECUBE_dom_taklamp.jpg

- | Different neutrino interactions lead to different event signatures
- | Muons have sufficient mass and lifetime to leave a distinct track

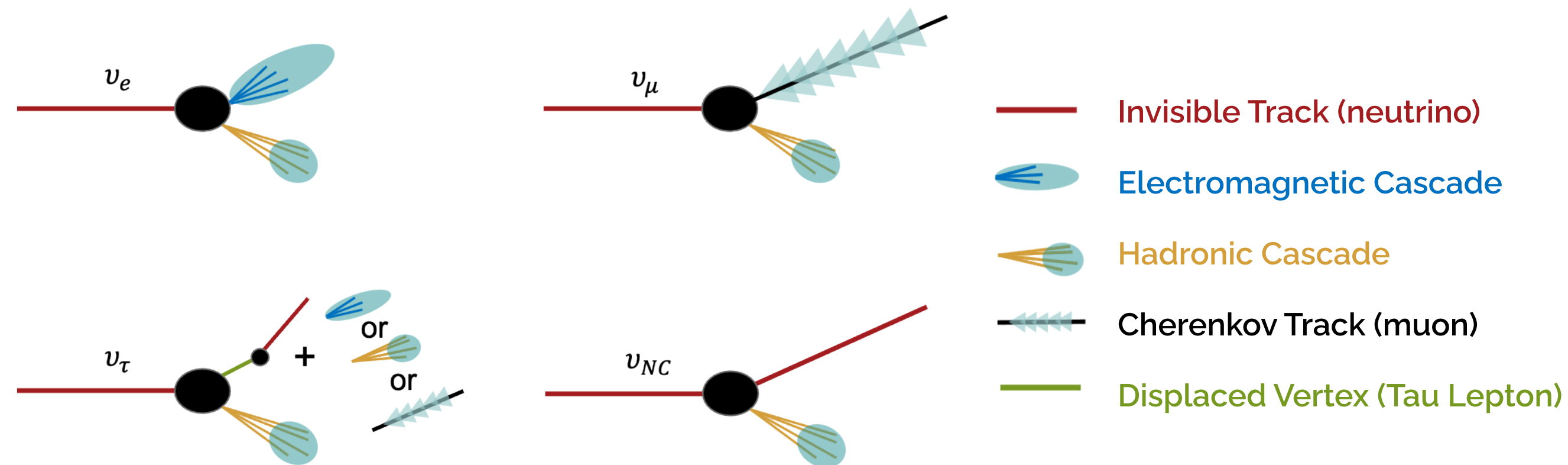


Figure from
Etienne Bourbeau, *Measurement of Tau Neutrino Appearance in 8 Years of IceCube Data*

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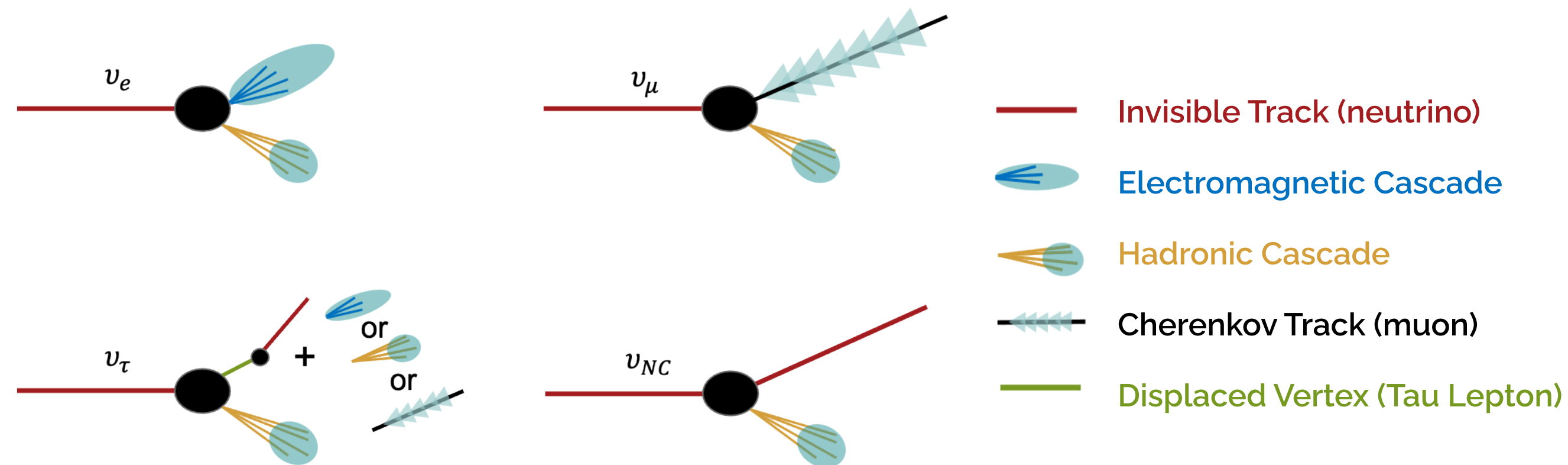


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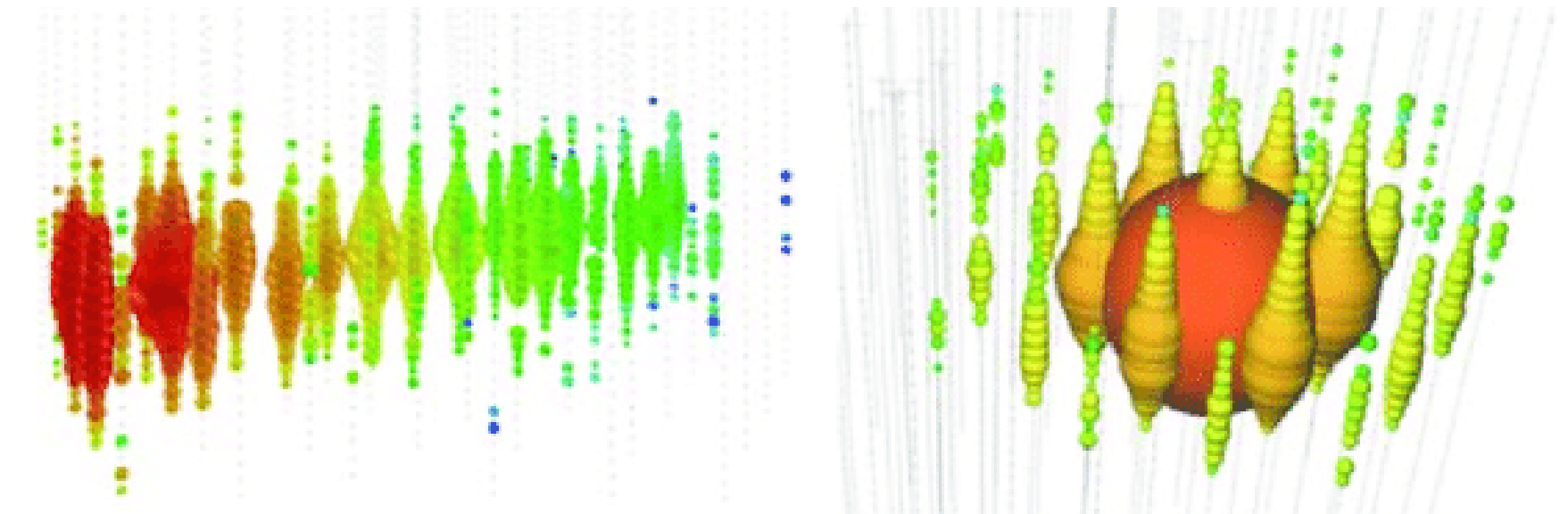


Figure from
Marek Kowalski et al., *Neutrino astronomy with IceCube and beyond*

Charged particles from the Cosmos interact with atomic nuclei in the atmosphere

The products are mostly light unstable mesons, and predominantly **pions**

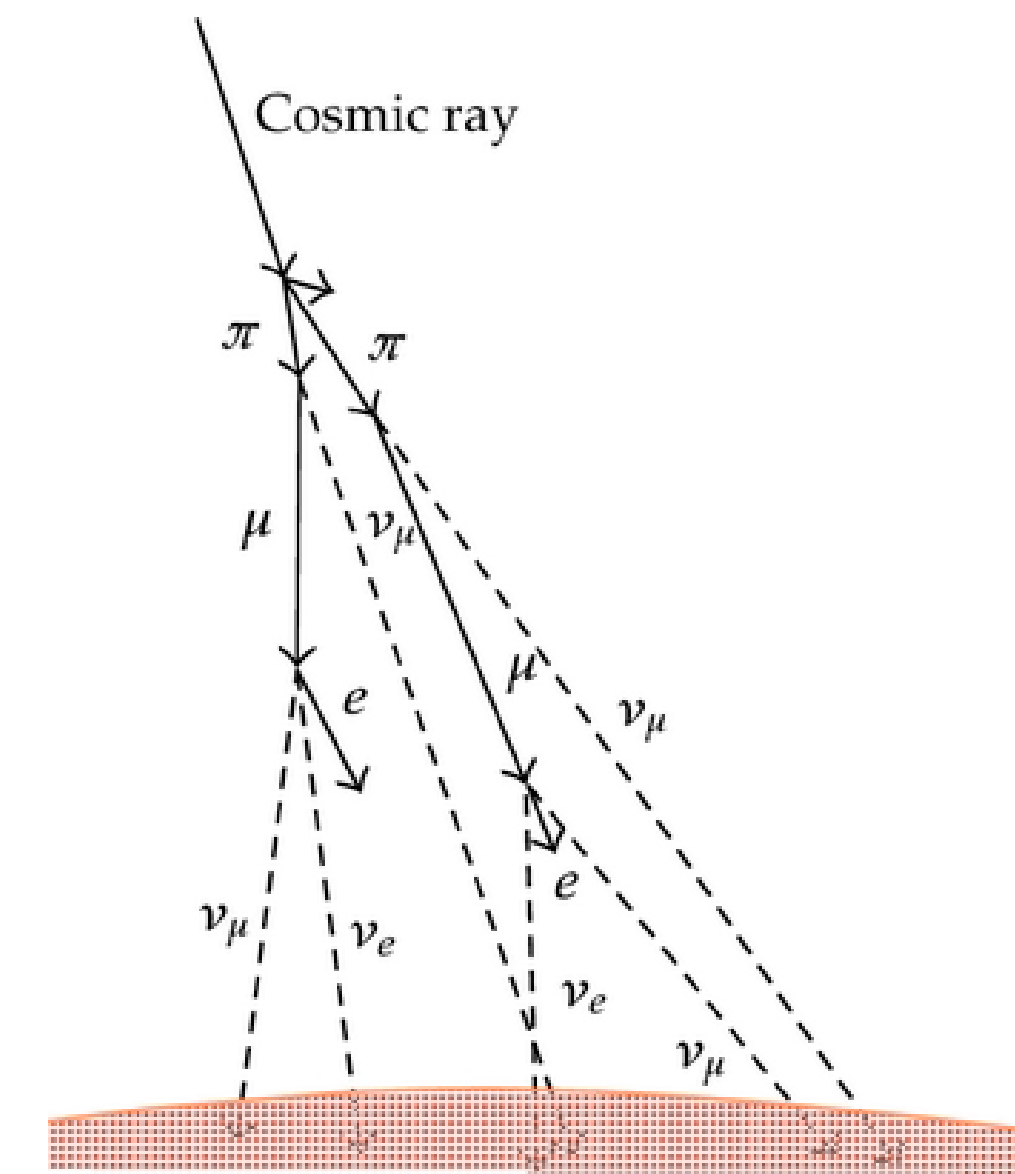


Figure from [Takaaki Kajita, Atmospheric Neutrinos](#)

Charged particles from the Cosmos interact with atomic nuclei in the atmosphere

The products are mostly light unstable mesons, and predominantly **pions**

Charged pions decay to **muons** and **muon antineutrinos** or **antimuons** and **muon neutrinos**

$$\pi^+ \rightarrow \mu^+ + \nu_\mu \quad (99.99\% \text{ of the time})$$

$$\pi^- \rightarrow \mu^- + \bar{\nu}_\mu \quad (99.99\% \text{ of the time})$$

Muons decays produce **electron antineutrinos**

$$\mu^- \rightarrow e^- + \bar{\nu}_e + \nu_\mu \quad (100\% \text{ of the time})$$

- | Muons decays produce **electron antineutrinos** $\mu^- \rightarrow e^- + \bar{\nu}_e + \nu_\mu$ (100% of the time)
- | Many muons **do not decay** but make it to the detector

Most of the recorded events in IceCube are caused by muons or noise from the detectors

These need to be filtered out to perform an analysis of neutrino oscillations

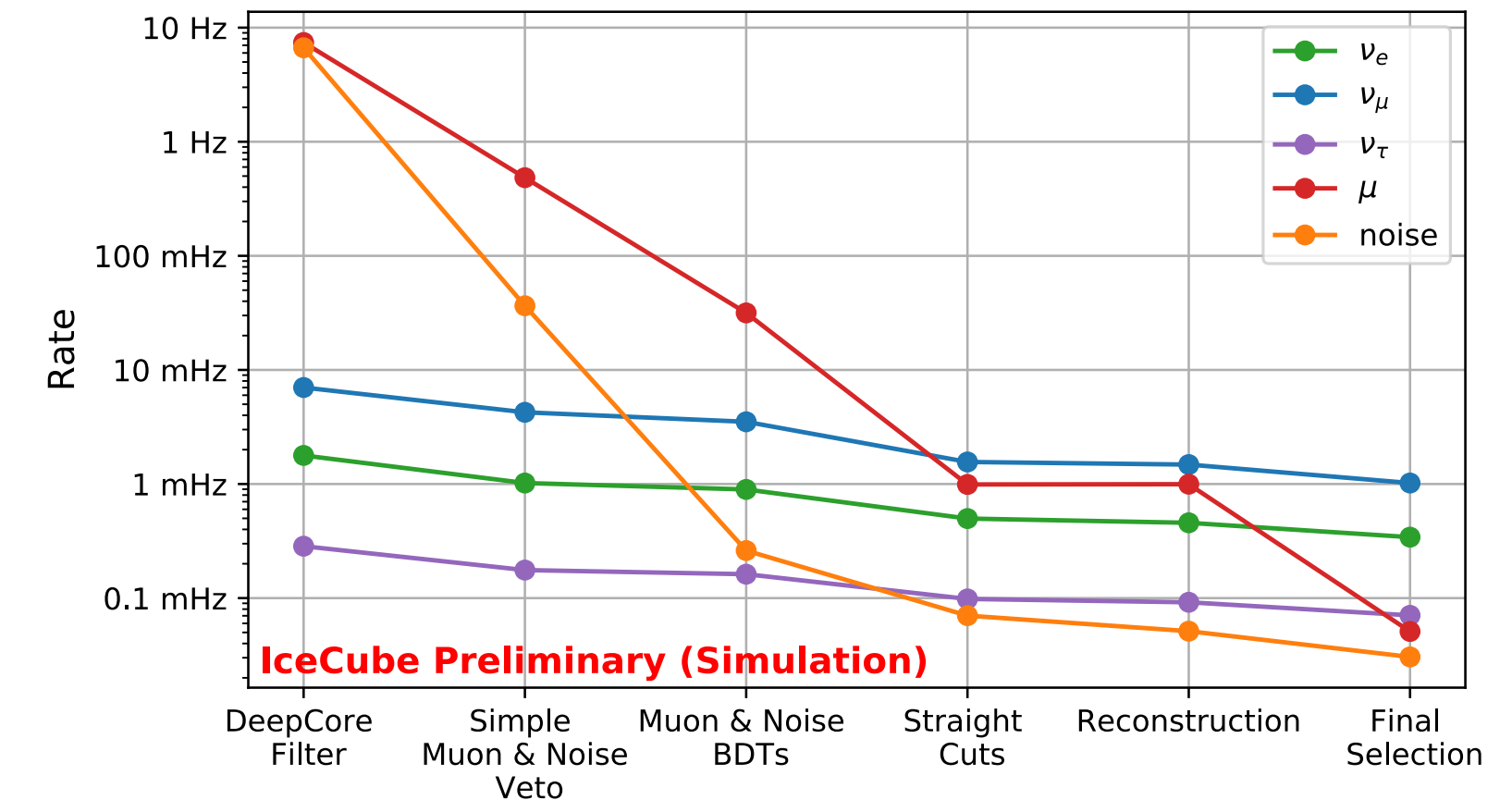
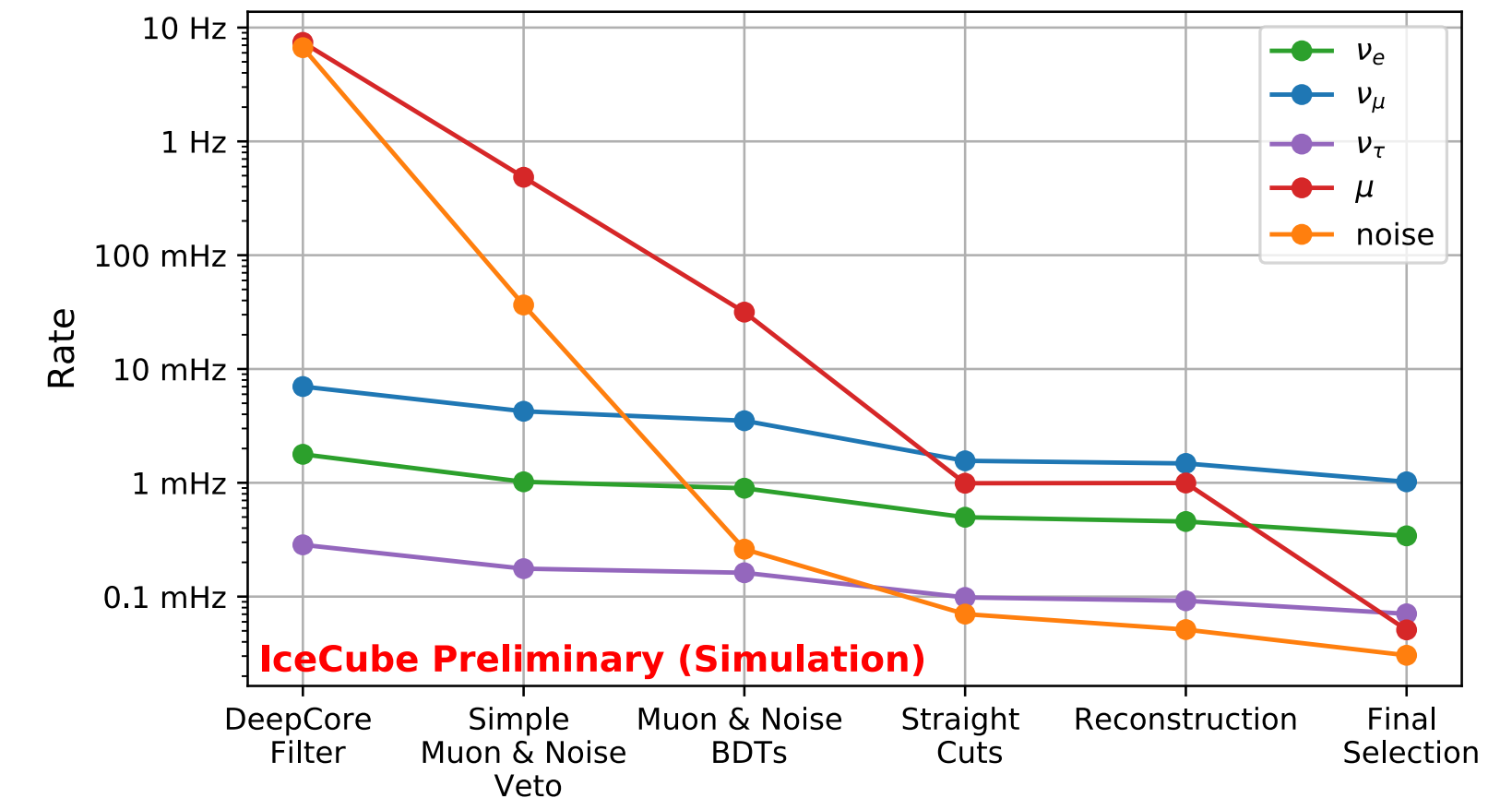


Figure from
Etienne Bourbeau, *Measurement of Tau Neutrino Appearance in 8 Years of IceCube Data*

Partial conclusion: Accurate reconstruction of neutrino events depends on good events selection and reliable reconstruction algorithms. Current methods are slow and inflexible.



Machine Learning

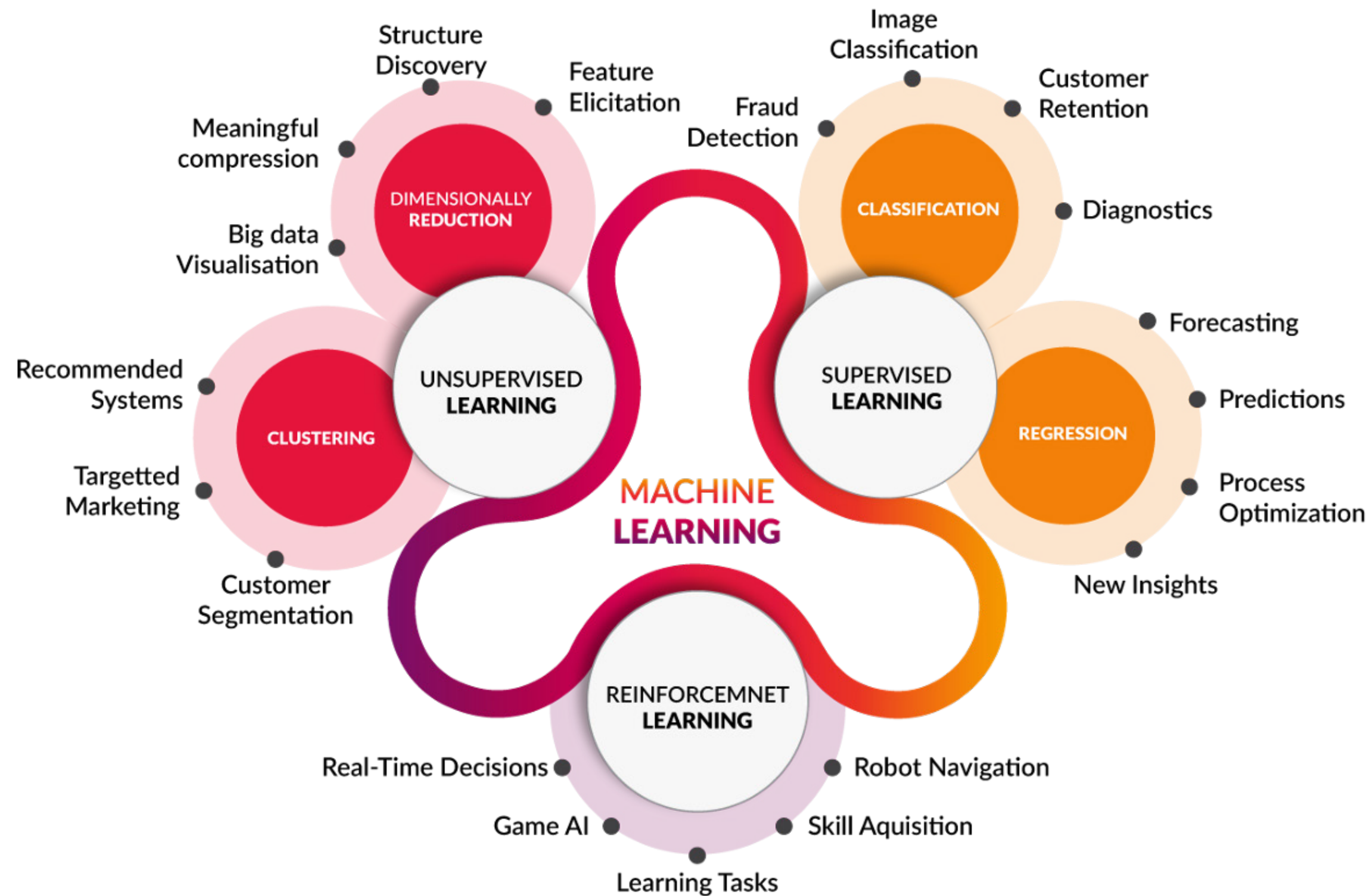


Figure from <http://www.cognub.com/index.php/cognitive-platform/>

Machine Learning: Algorithms designed to let computers “learn” from examples without being explicitly programmed

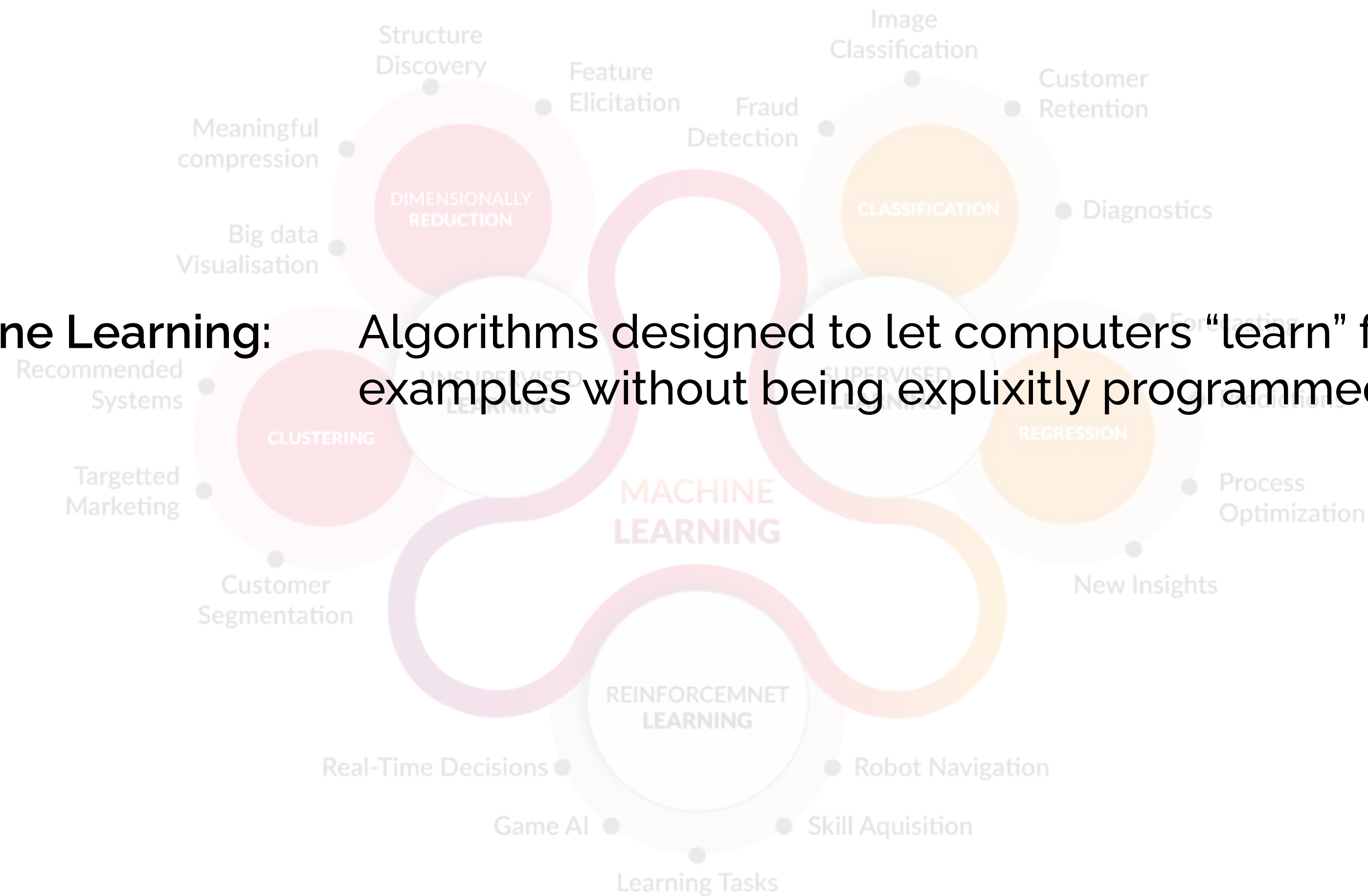
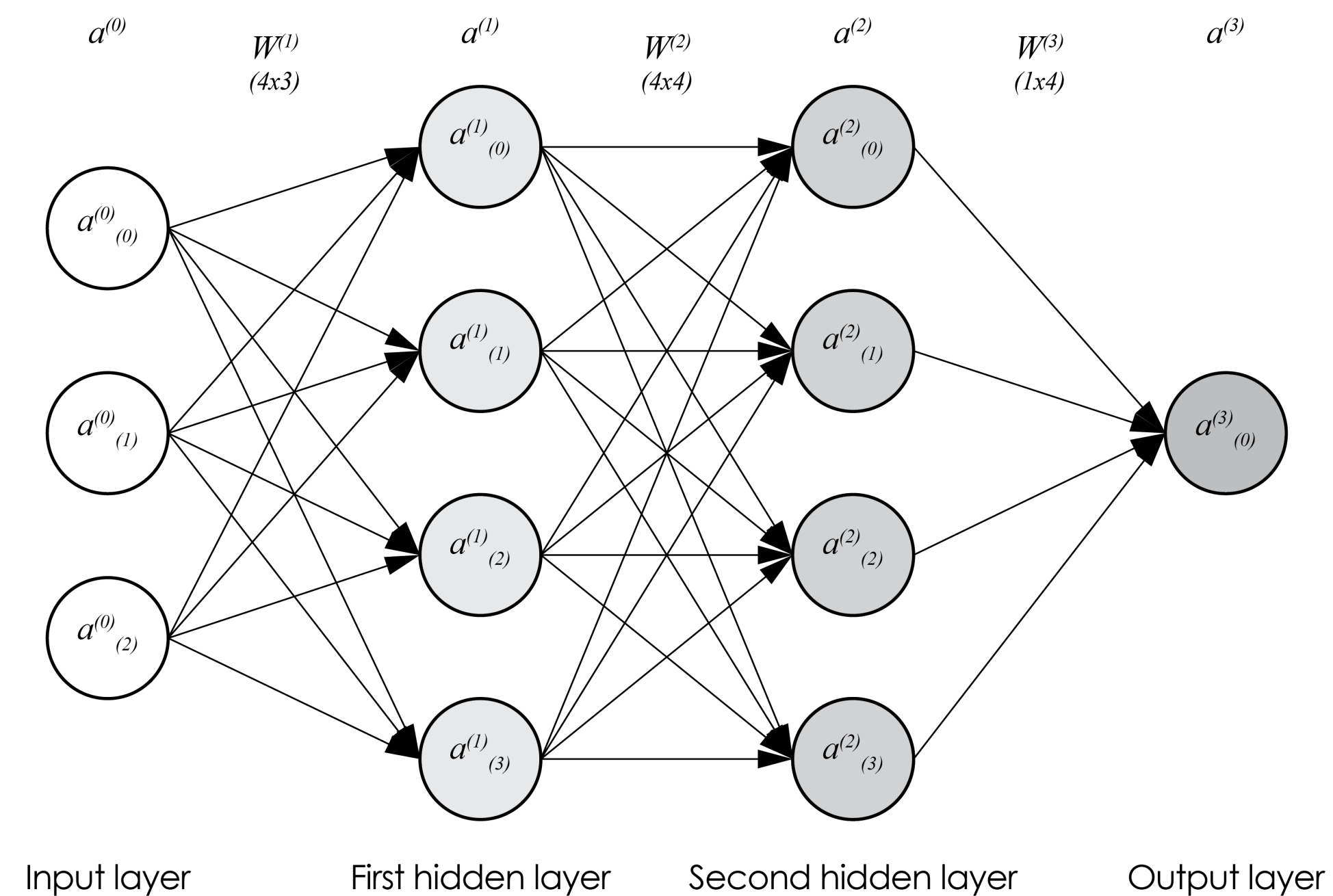
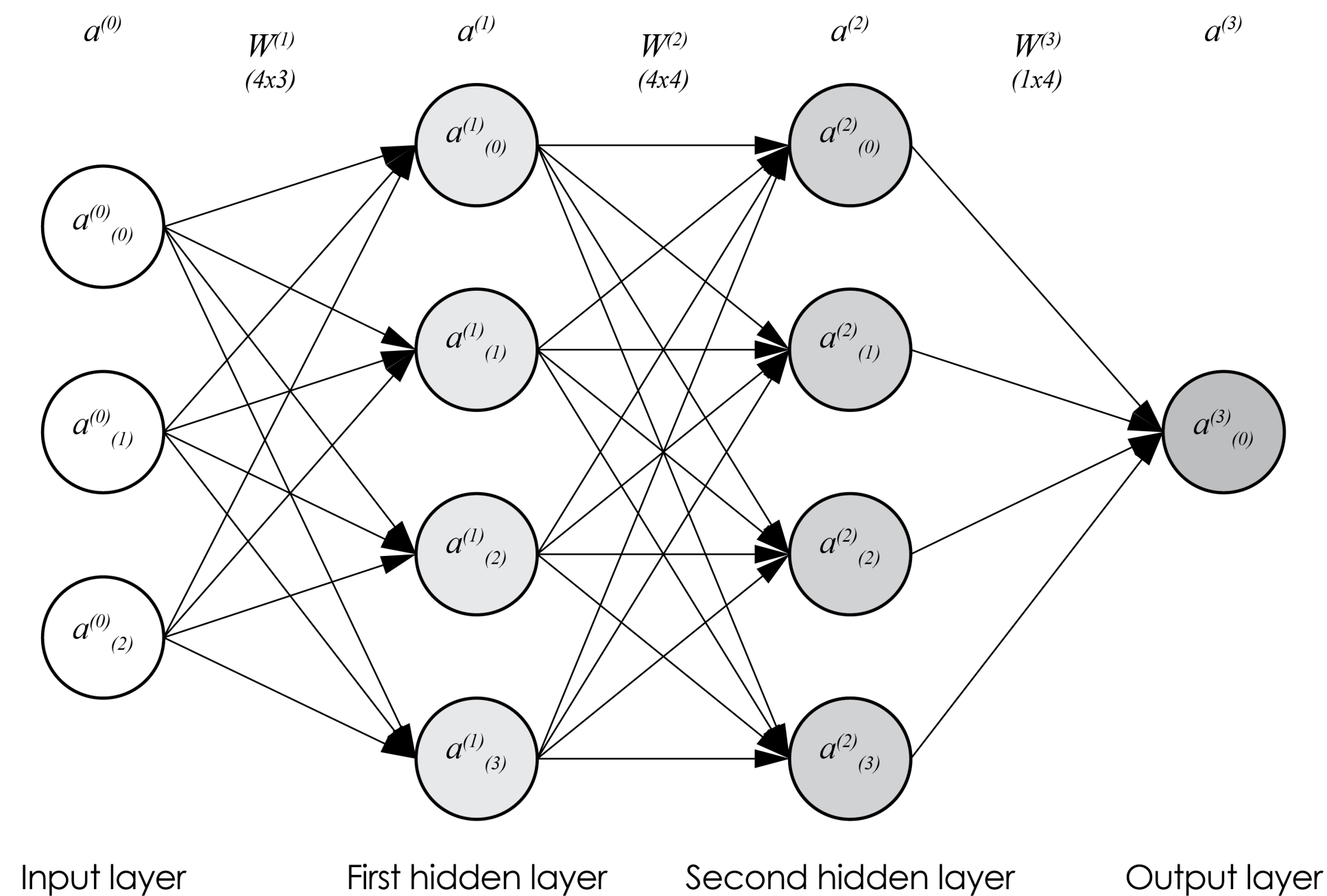


Figure from <http://www.cognub.com/index.php/cognitive-platform/>

Neural networks: Machine learning models made up of **layers** of **nodes** connected by **weights**

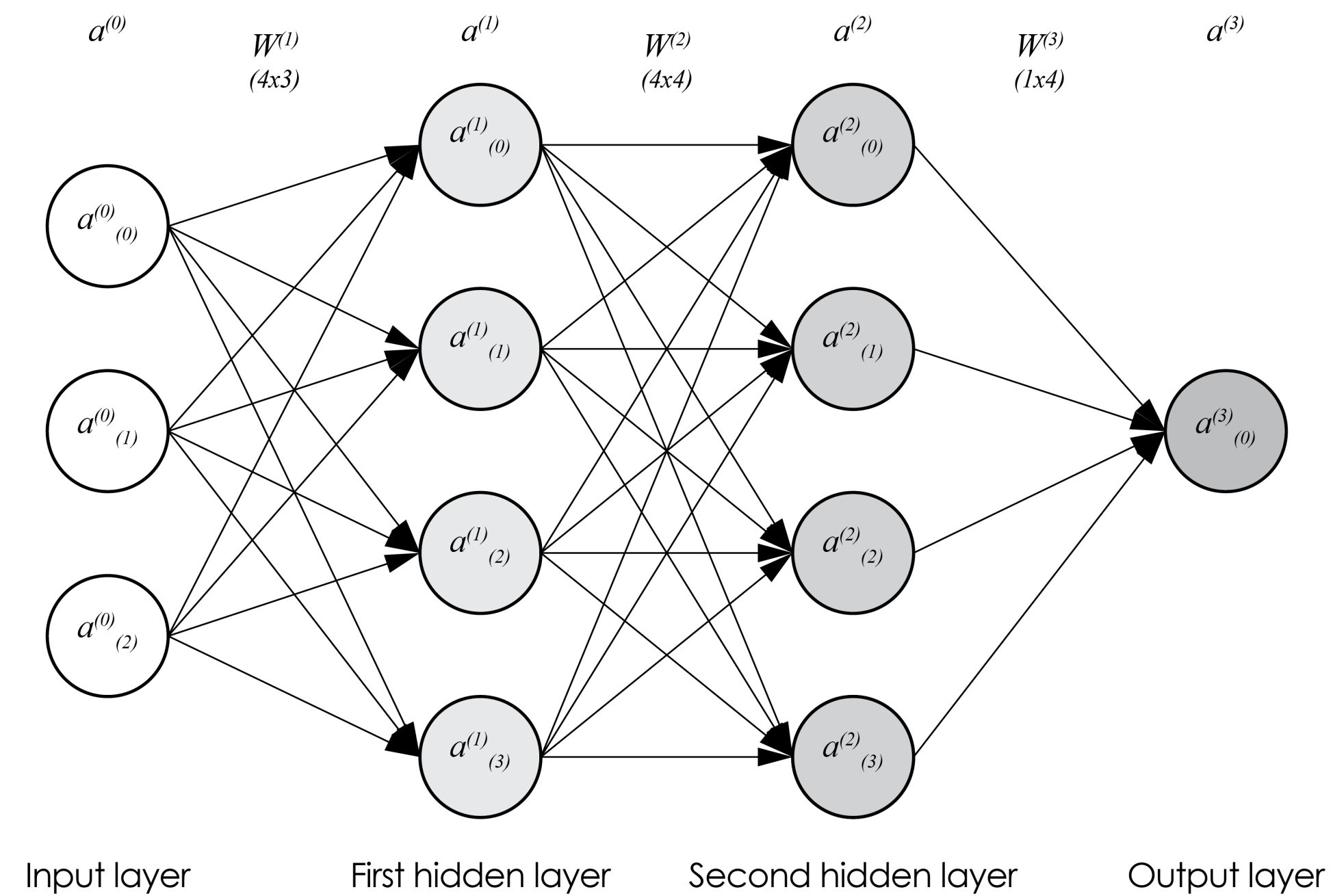


| Neural networks: Machine learning models made up of **layers** of **nodes** connected by **weights**

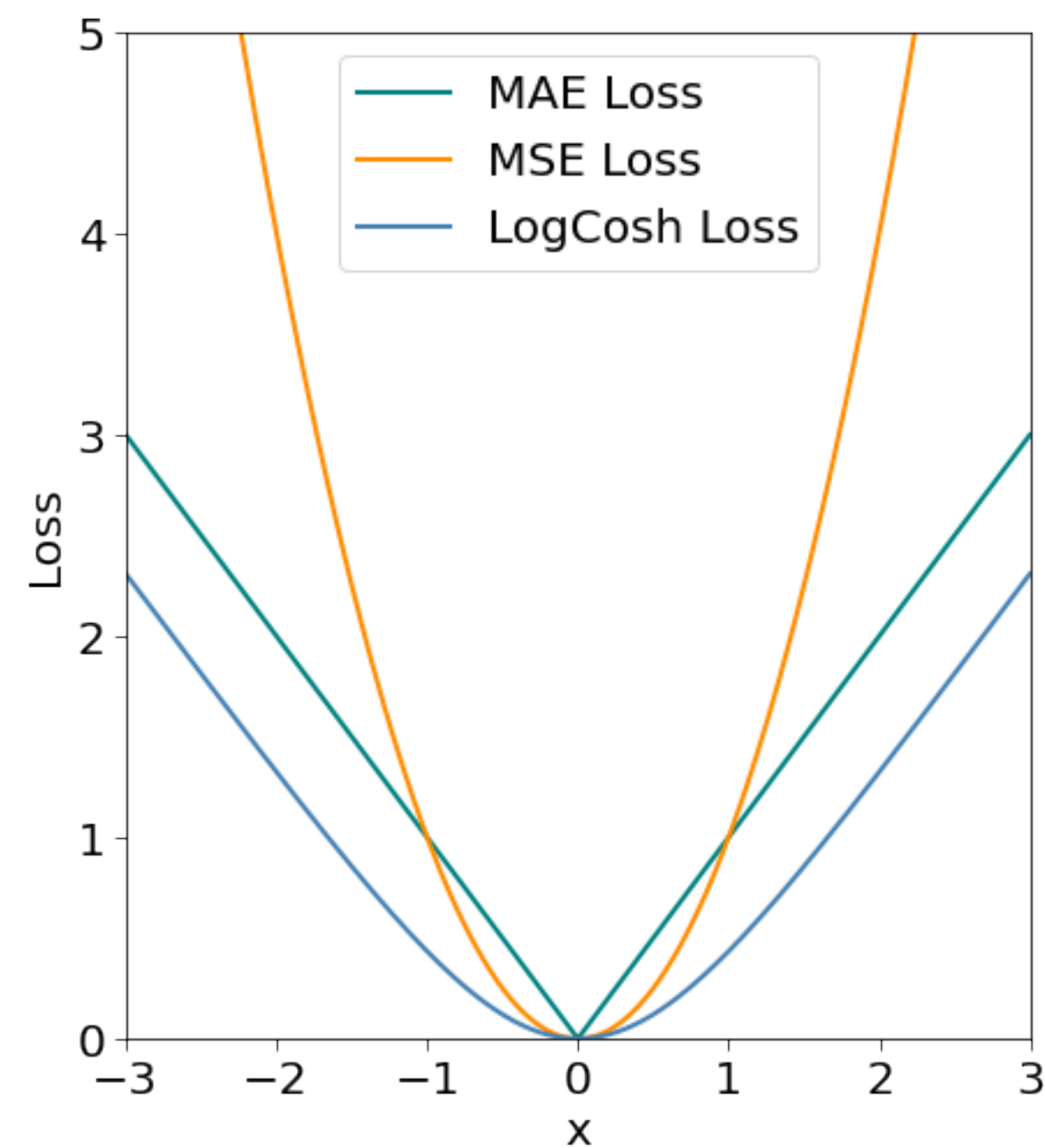


$$a_{(i)}^{(k)} = f \left(\sum_{j=0}^{N-1} \left(w_{(i,j)}^{(k)} \cdot a_{(j)}^{(k-1)} \right) + b_{(i)}^{(k)} \right)$$

| Weights (and biases) are the learnable parameters of the neural network



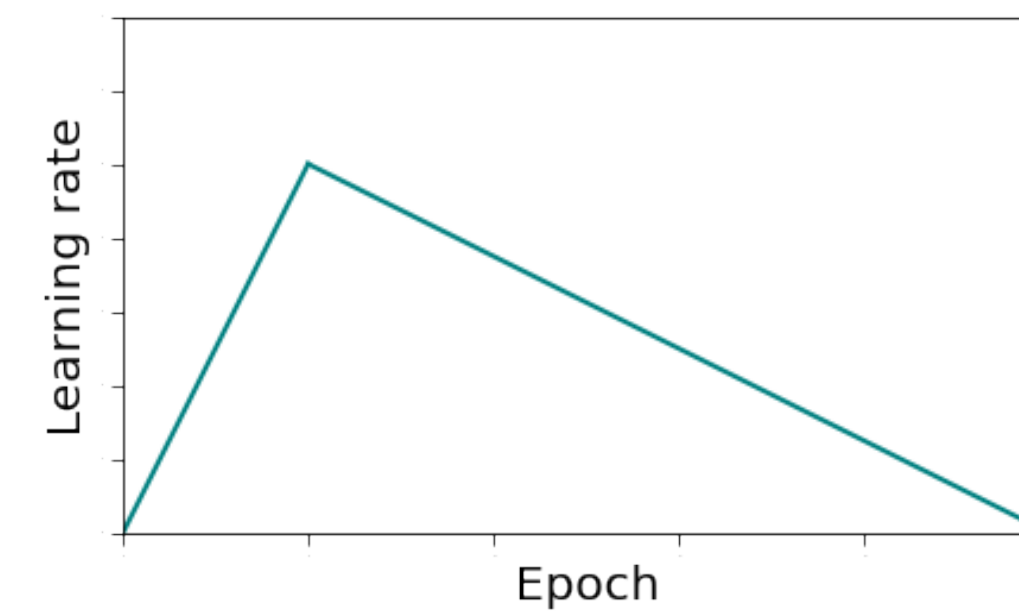
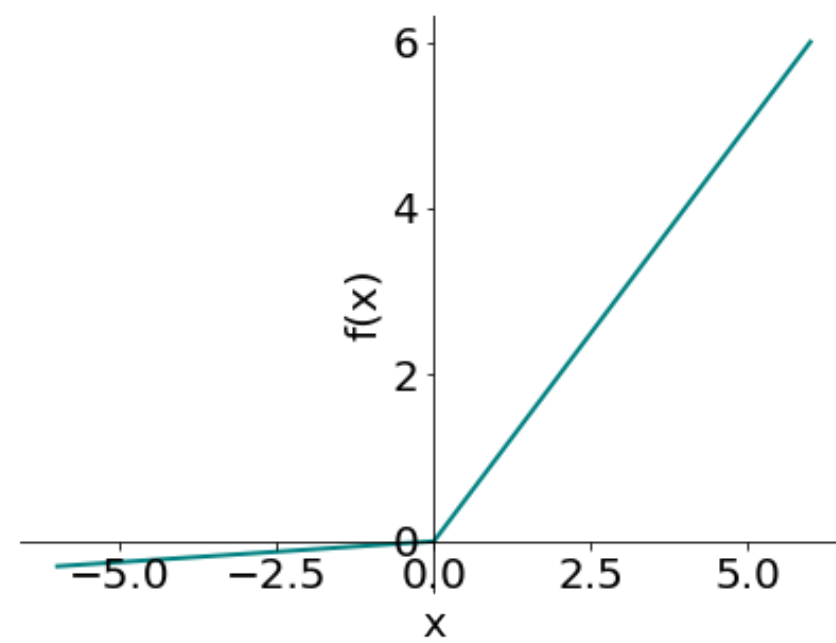
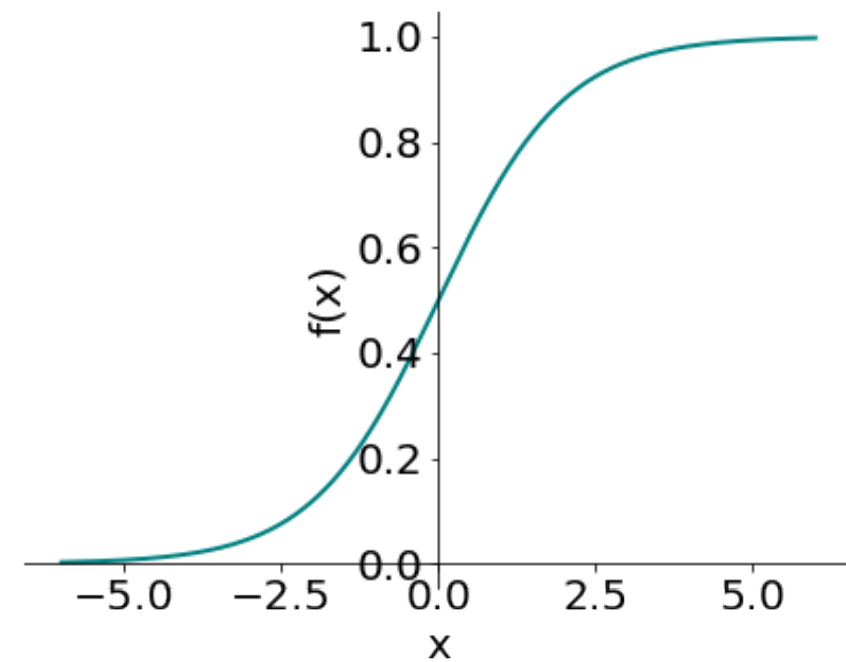
Learning is carried out by optimising the weights and biases to minimise the **loss**



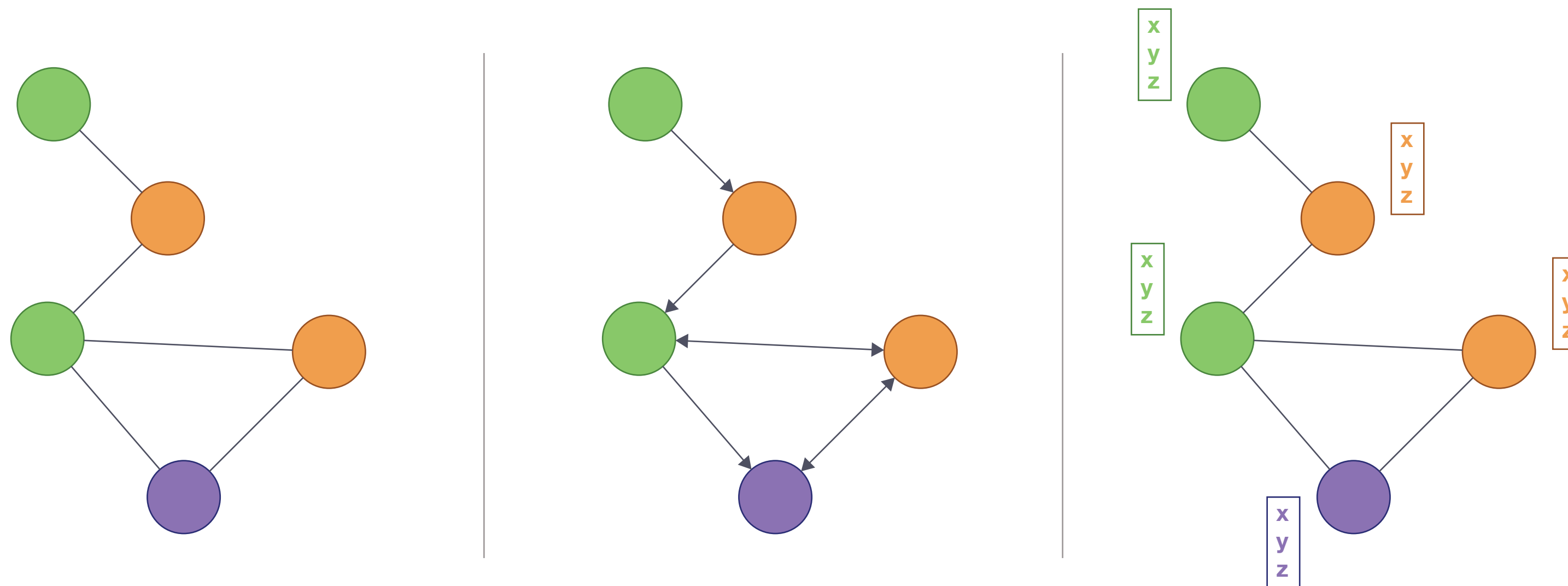
| Learning is carried out by optimising the weights and biases to minimise the **loss**

| The loss function differs between tasks

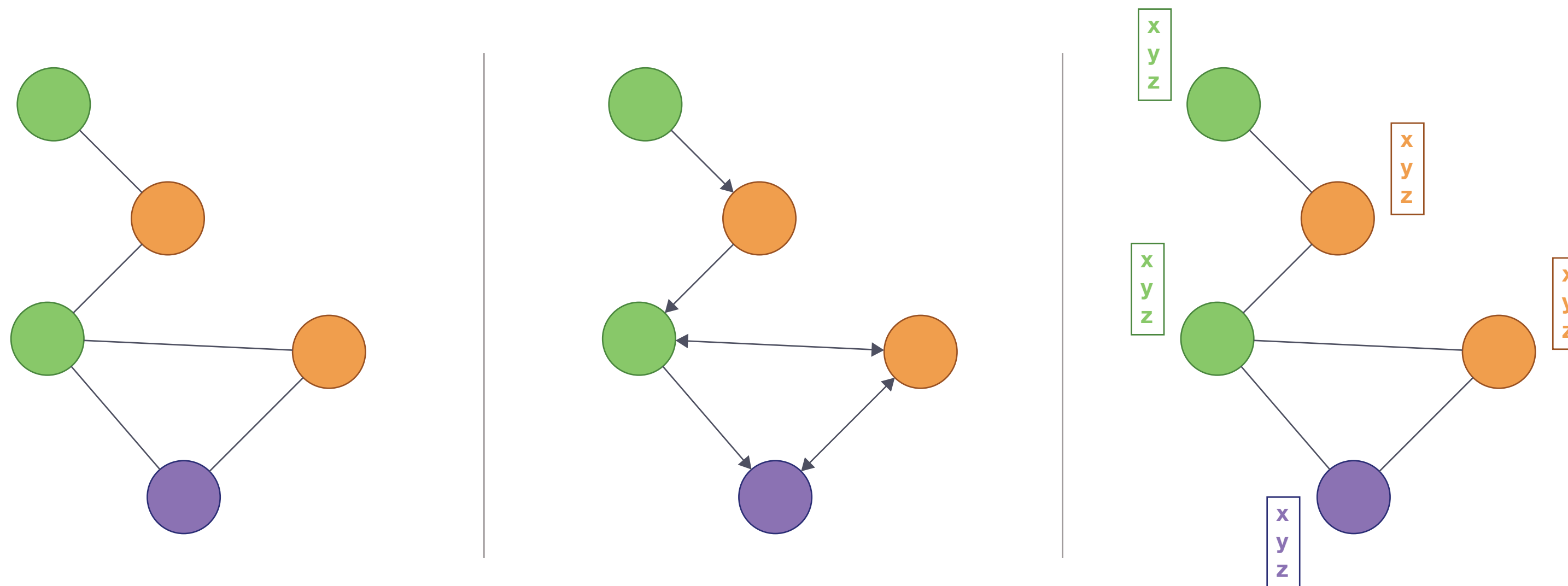
| Activation functions, optimisers, train/validation split, learning rates, early stopping



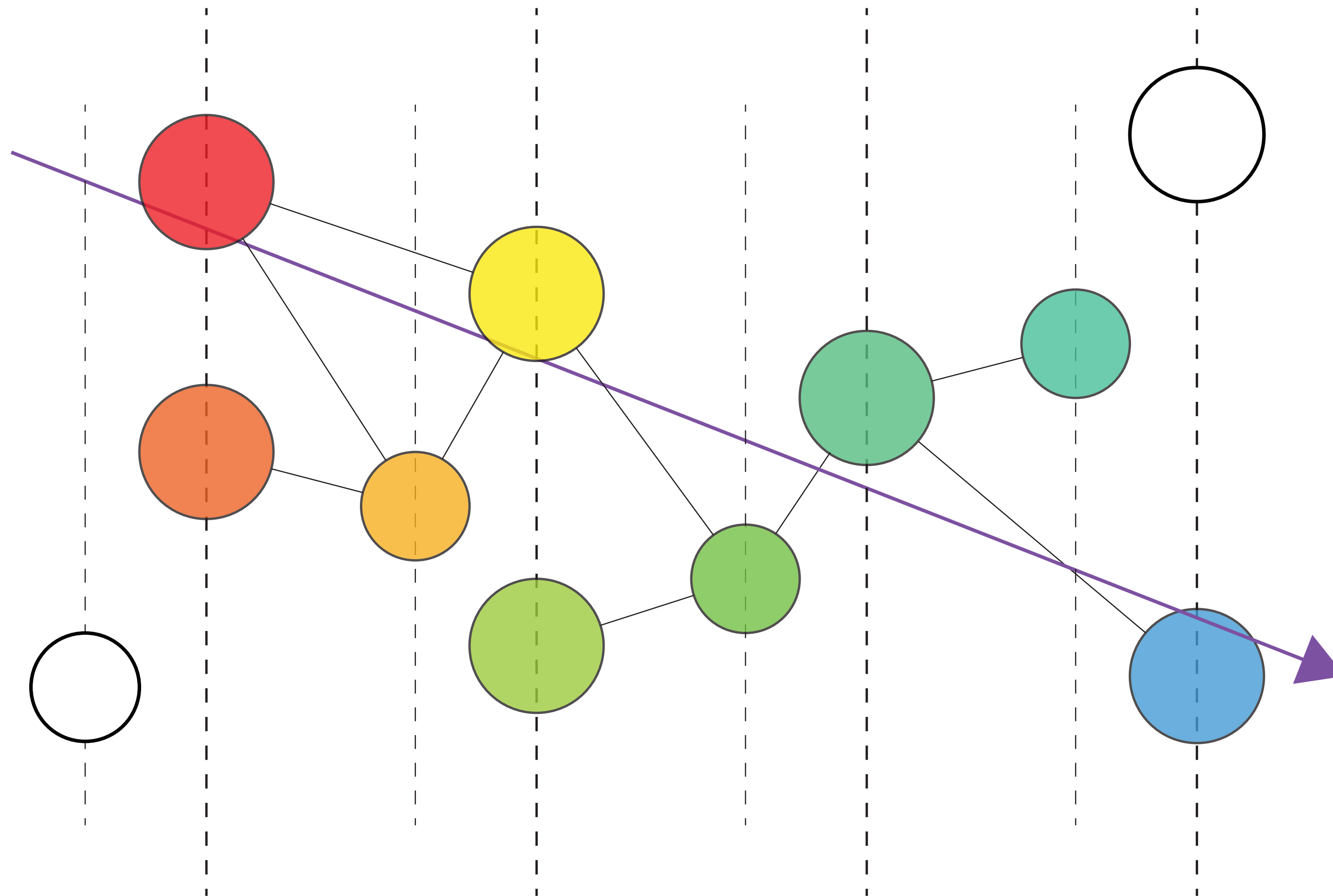
- | Based on mathematical theory of graphs, consisting of nodes and edges
- | Well suited for data that lacks a rigid grid-like structure, but still contains a hierarchy



- | Uses message passing schemes between each layer
- | The number of node- and edge-features may change but the number of nodes stay the same



| KNN method is used to create graph from pulses in an event





GraphNeT

Graph Neural Networks for
Neutrino Telescope Event Reconstruction

| GraphNeT is the combined GNN efforts within IceCube

| DynEdge is the common GNN architecture used within GraphNeT and in this work

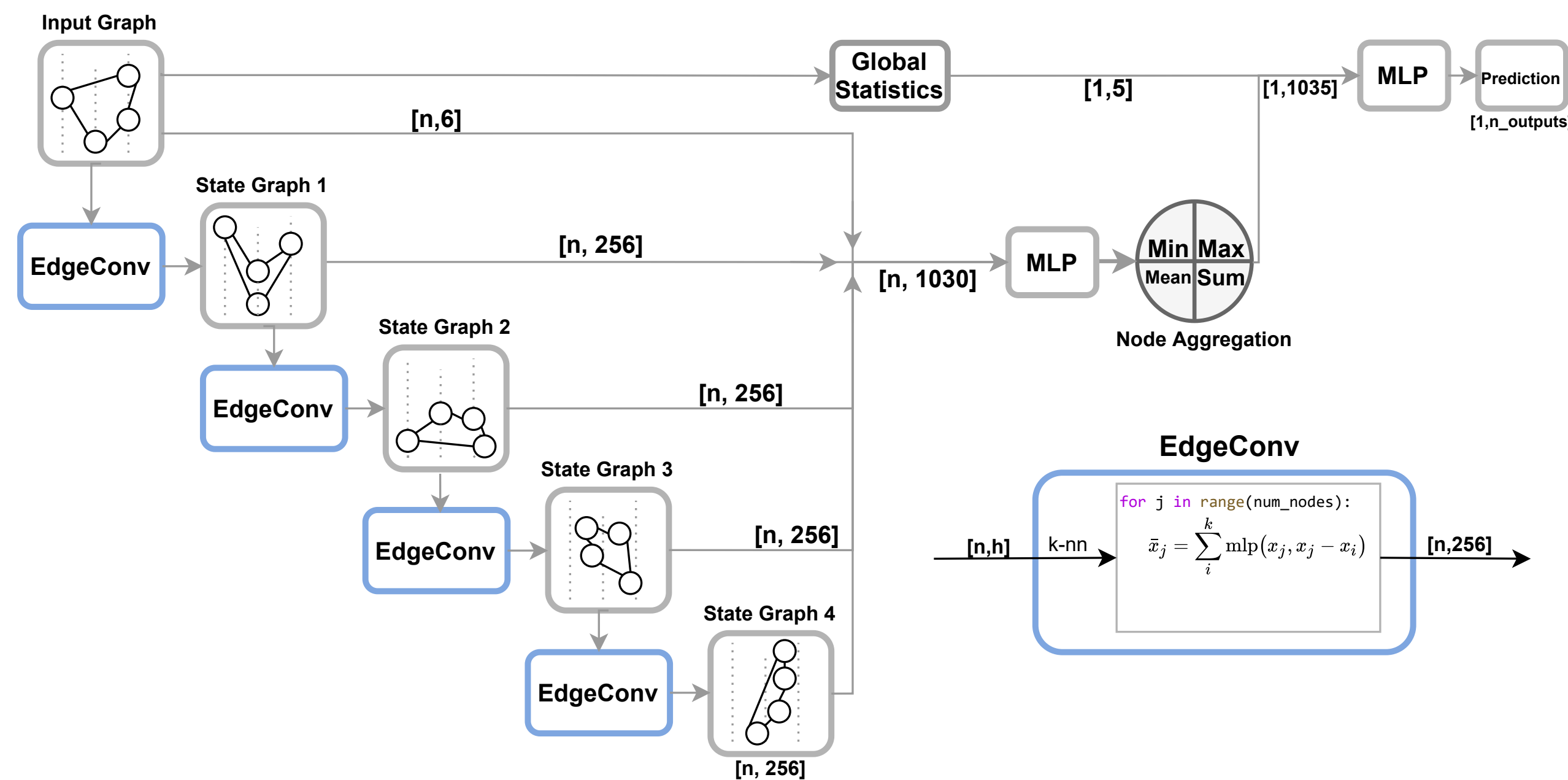


Figure by Rasmus Ørsøe

Partial conclusion: GNNs have already been shown to work well on IceCube regression and classification tasks. But what range of problems are they suited for and what do we stand to gain from it?

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My Work

Time Regression

Event Cleaning

Upgrade Pulse Cleaning

Regression of Cleaned Pulses

Intermezzo 1: Improvement of Pulse Cleaning

Intermezzo 2: Quality of Cleaned Events

Conclusions & Outlook

Loss functions:

Classification: Binary Cross Entropy
Angular regression: 2D Von Mises-Fisher

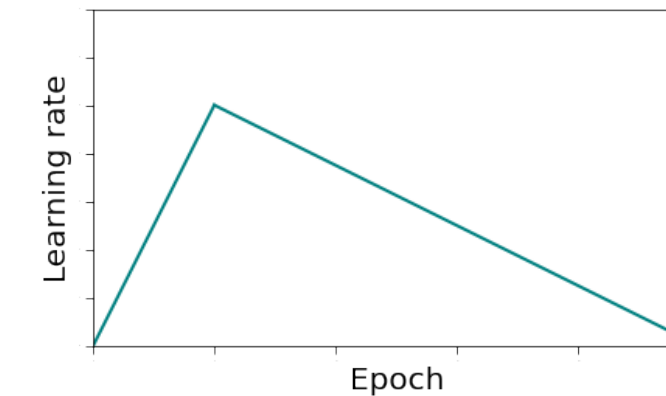
Other regressions: LogCosh

Optimiser:

ADAM

Learning rate:

Slanted triangular LR schedule with early stopping

**Sample distribution:**

Even when possible

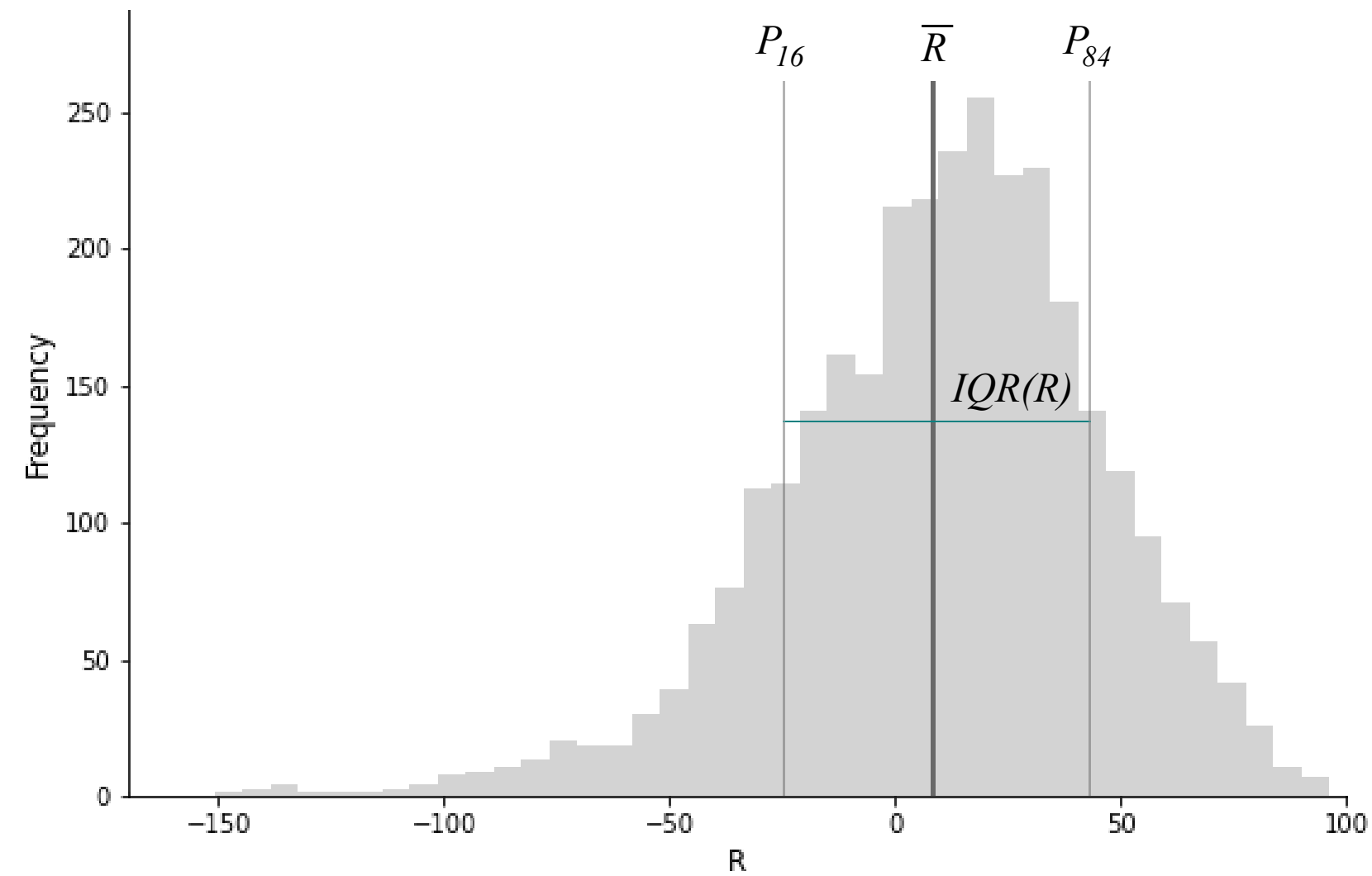
Comparison:

RetroReco

Training data:

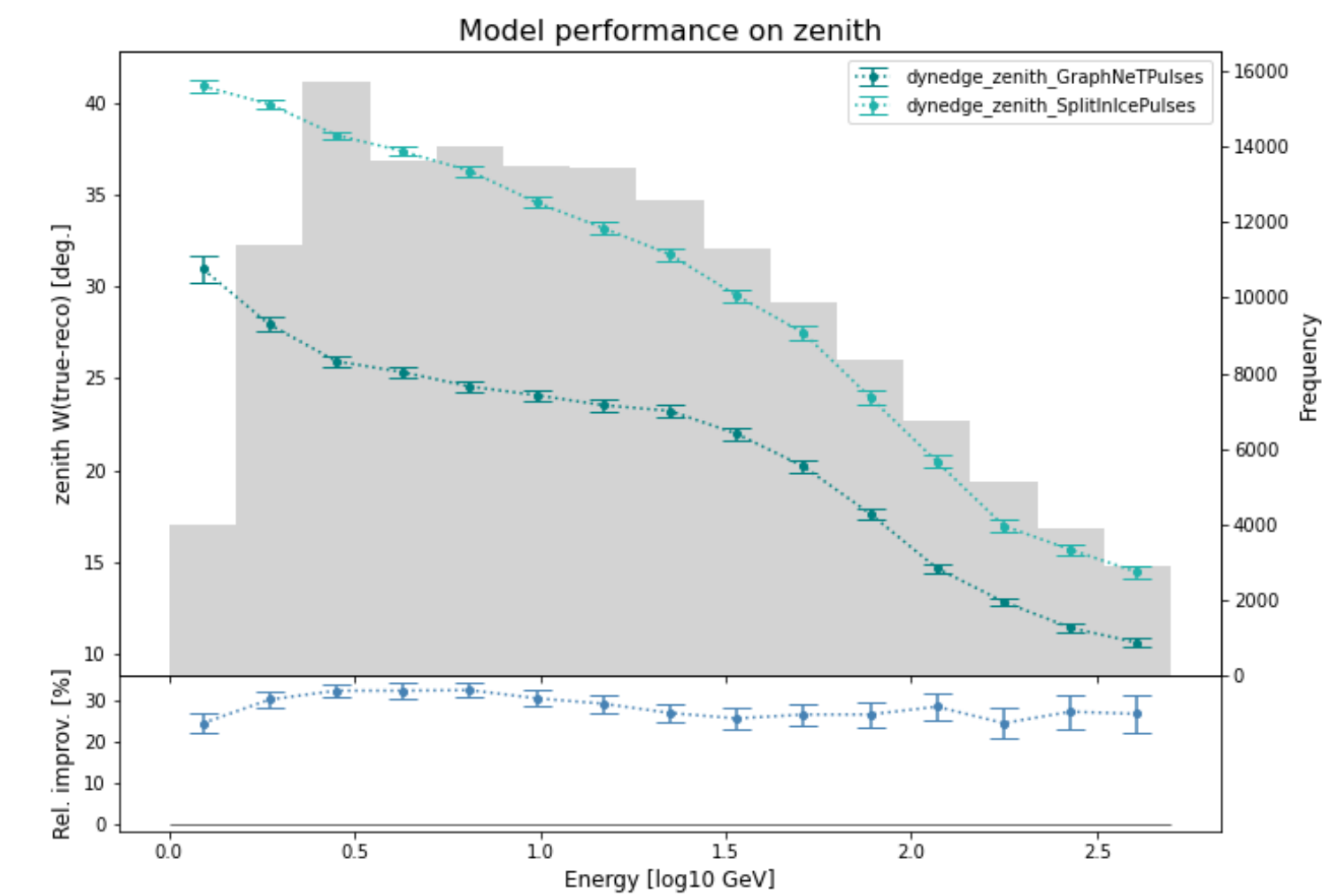
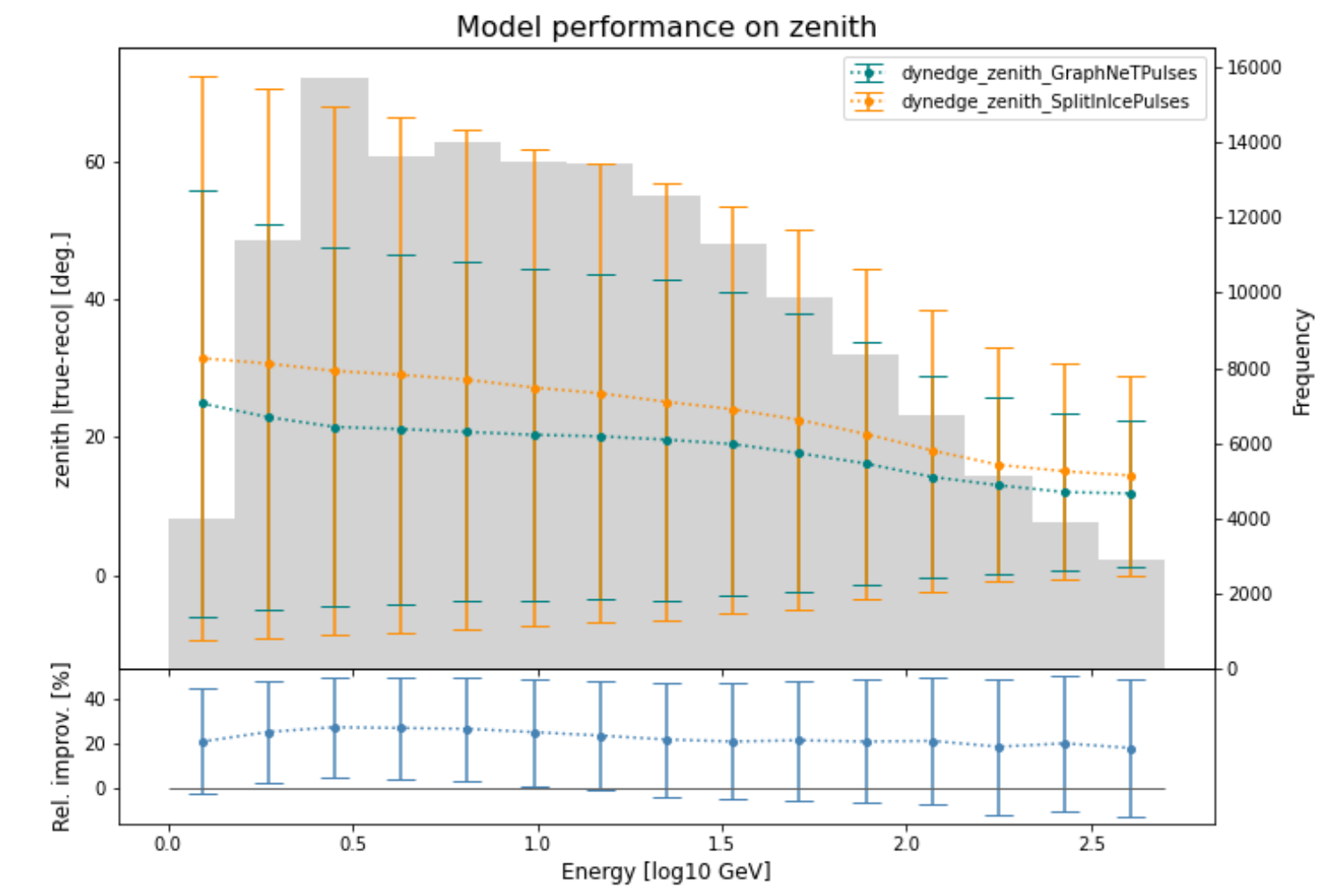
IceCube MC simulations

| Plot types

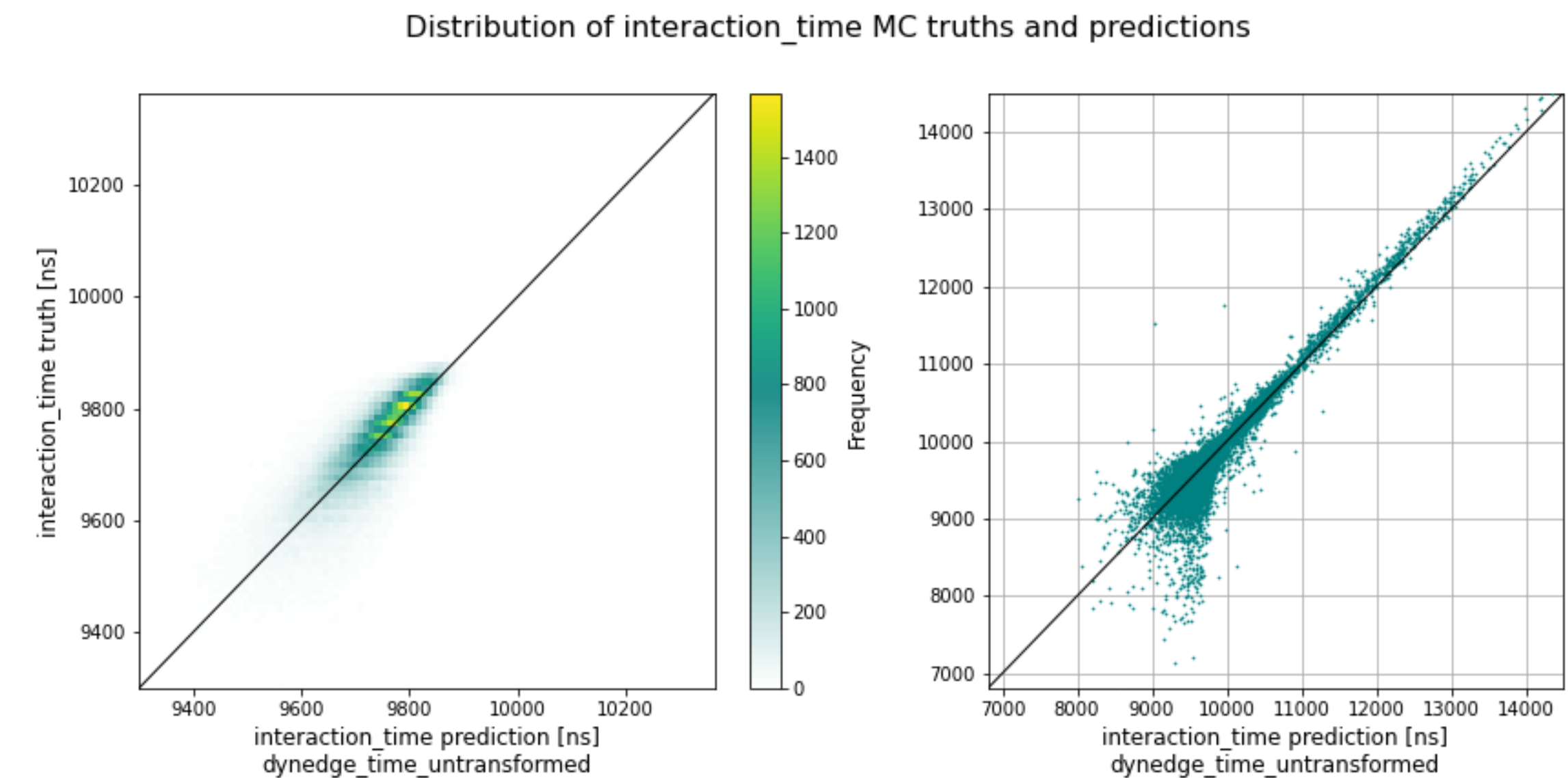
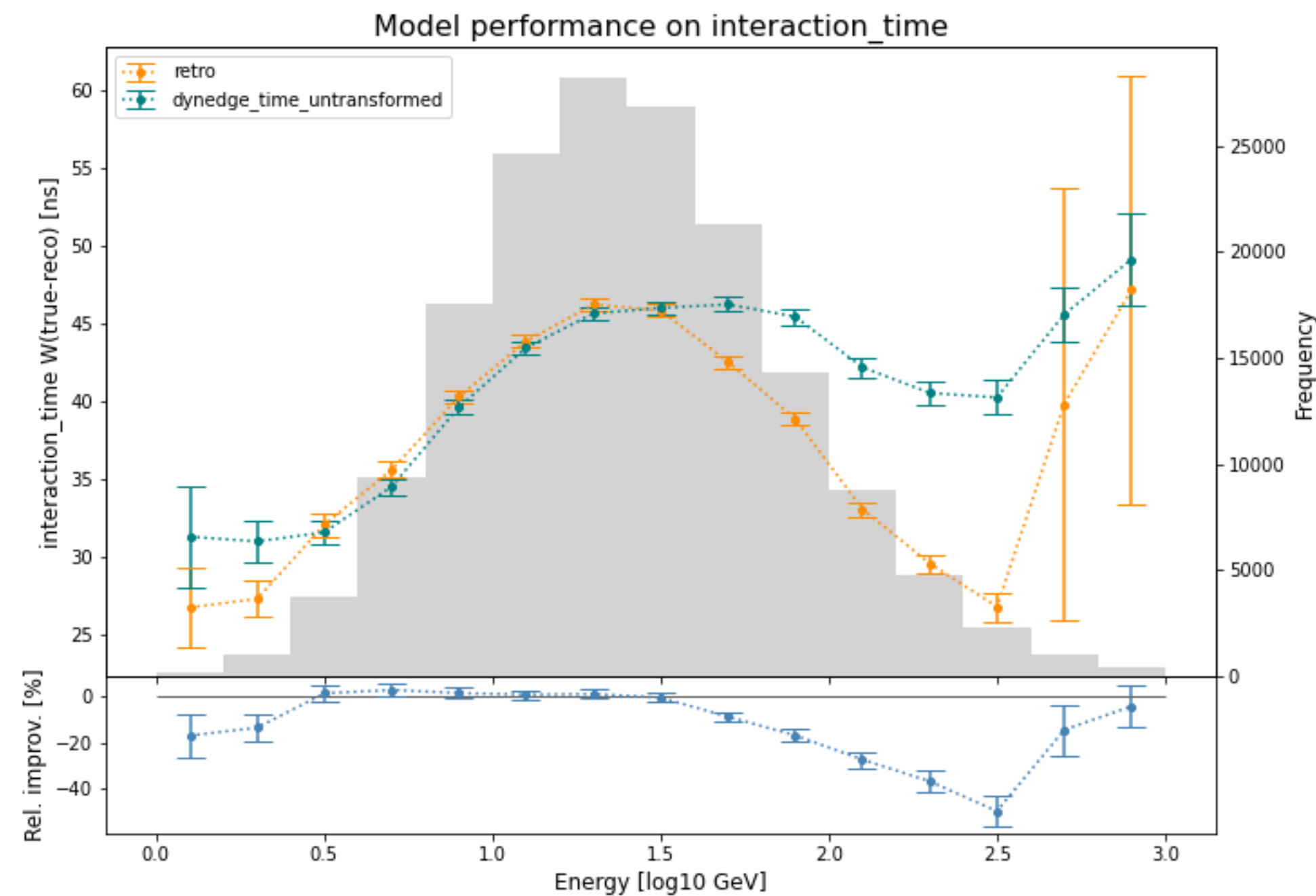


| $R = \text{truth} - \text{reco}$ (most often)

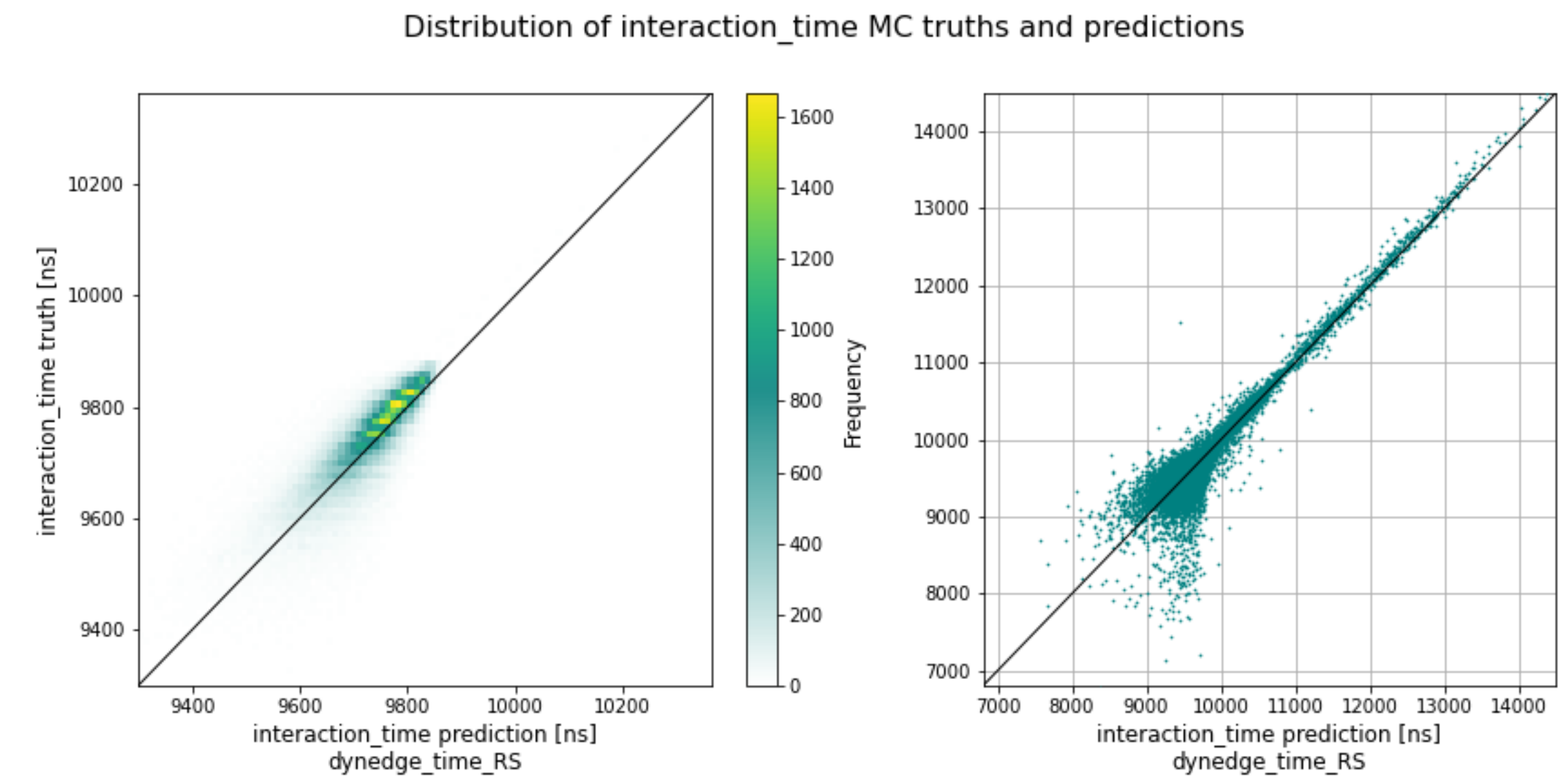
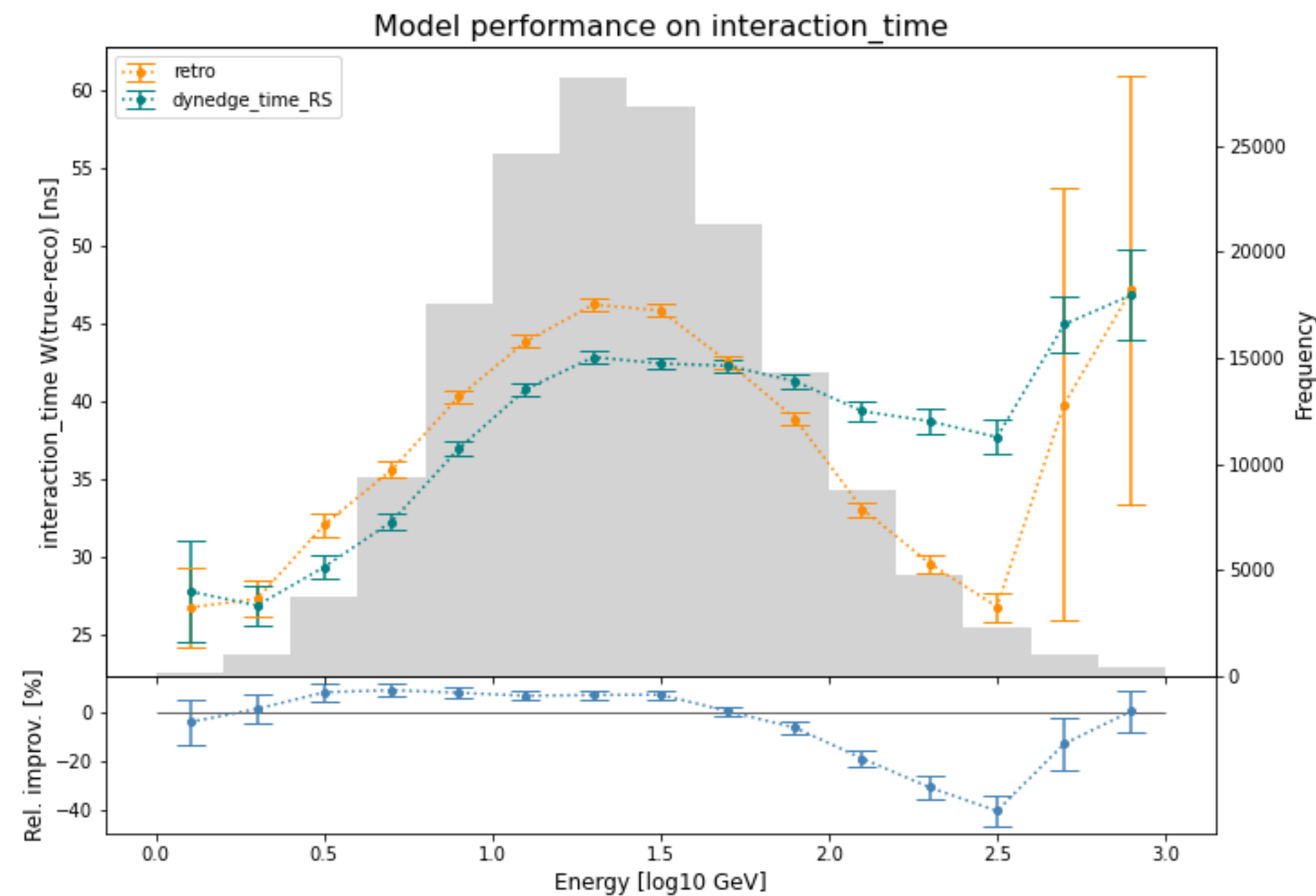
| $W(R) = IQR(R)/1.349$



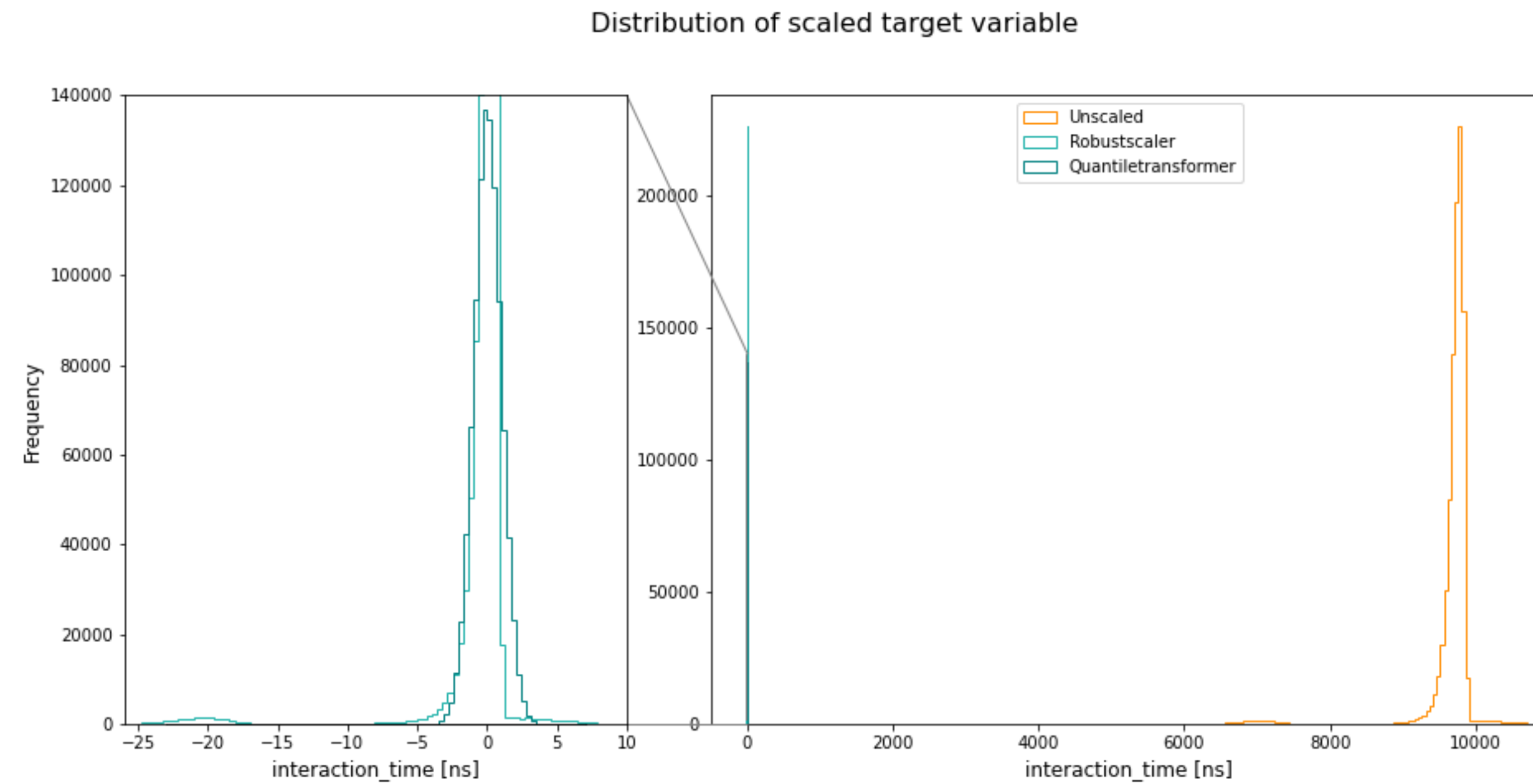
Setup: Regression of the time of neutrino interaction can be useful for some studies, but the GNN reconstruction struggles with this task. The problem is likely the uneven distribution of the target variable.



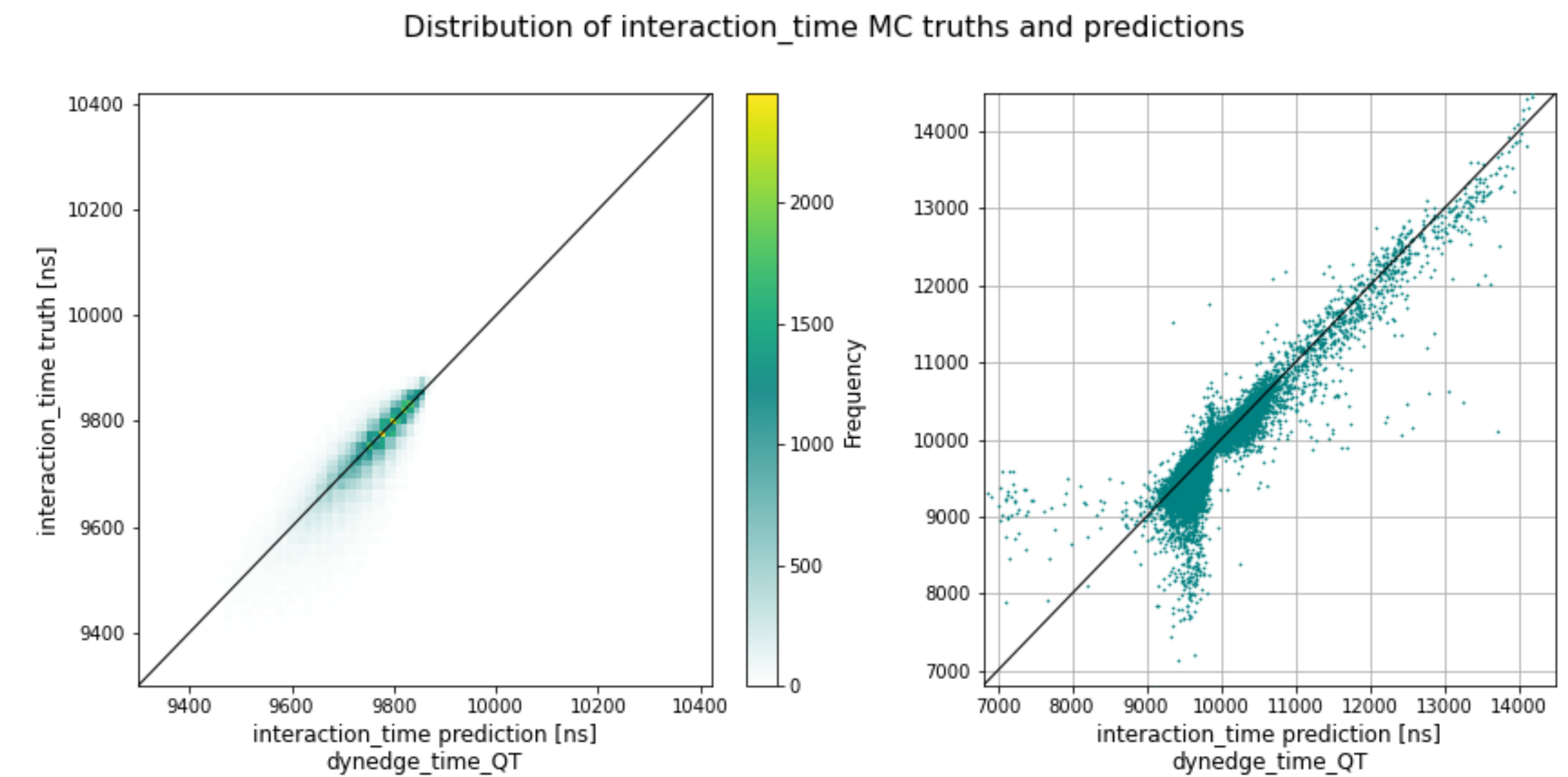
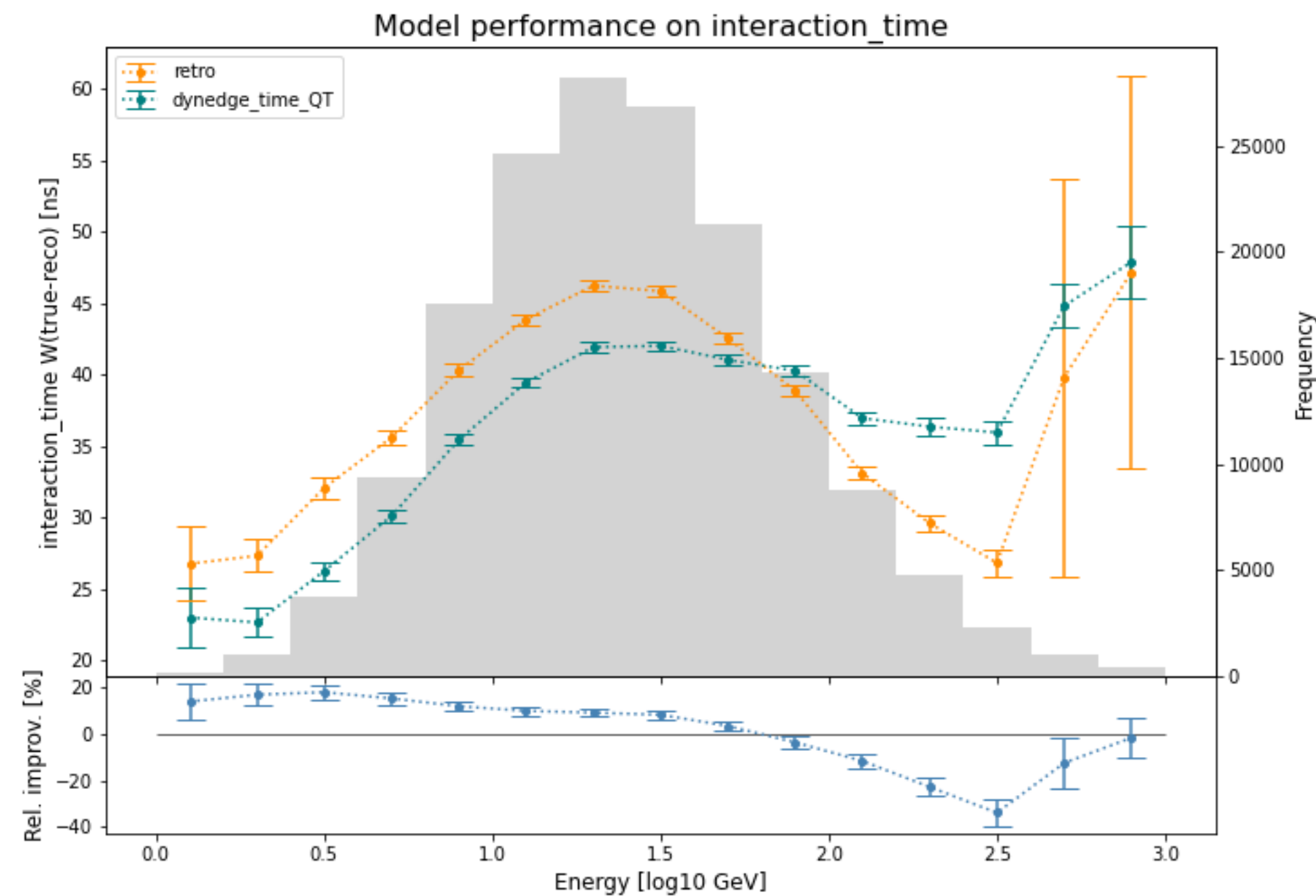
Approach: Apply scaling to the target variable. Attempt 1: RobustScaler



Approach: Apply scaling to the target variable. Attempt 2: QuantileTransformer

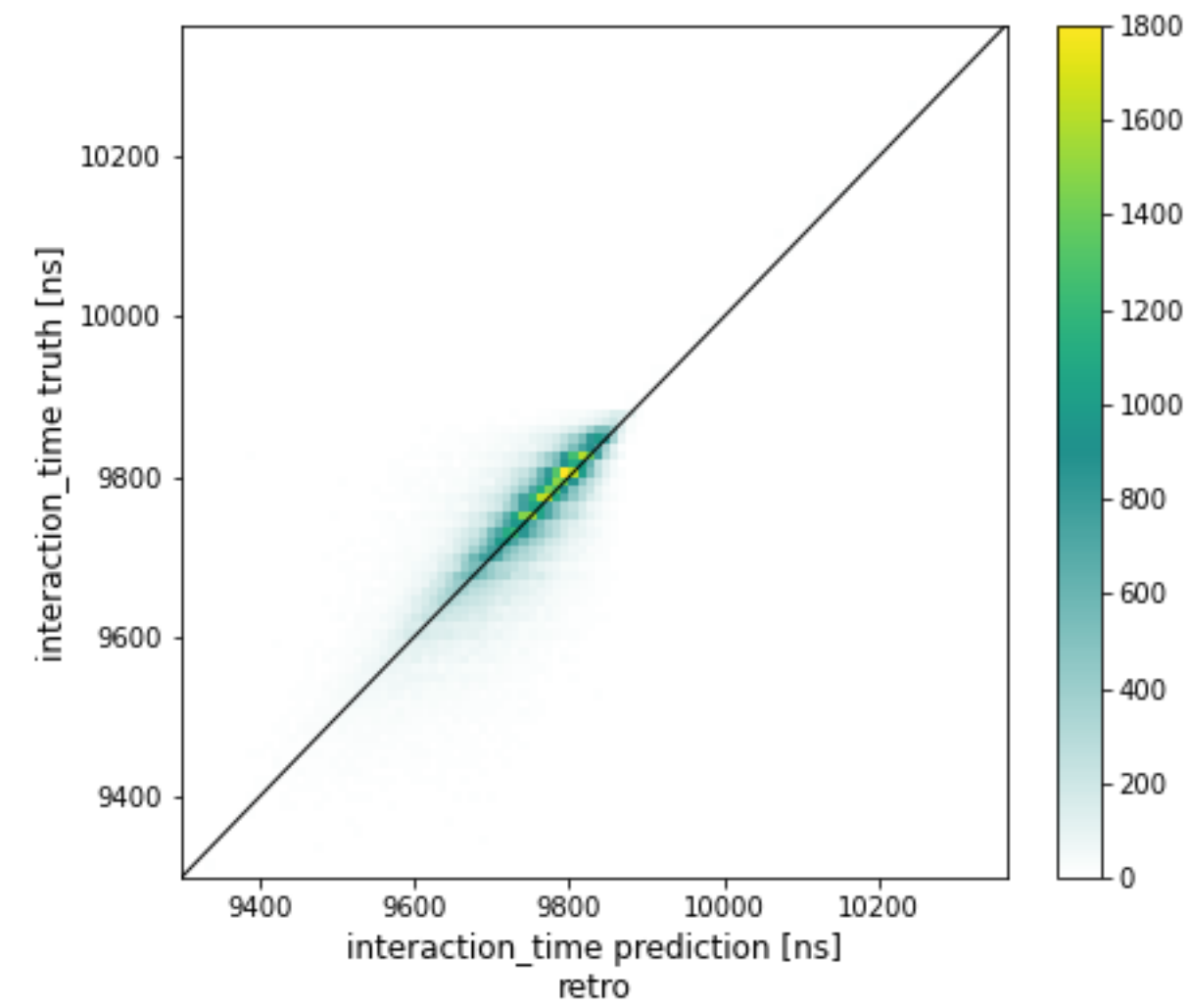


Approach: Apply scaling to the target variable. Attempt 2: QuantileTransformer

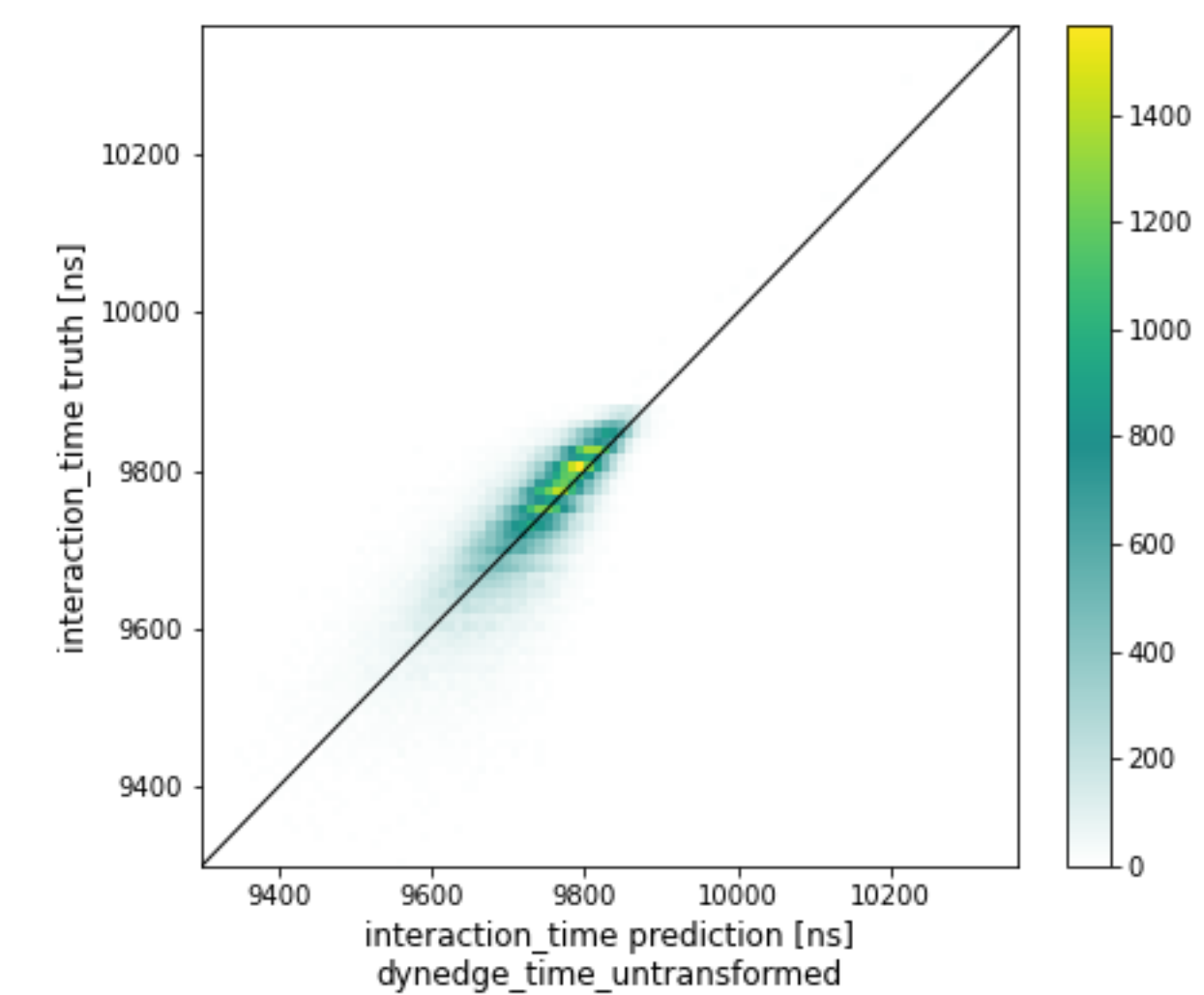


Interaction Time Regression

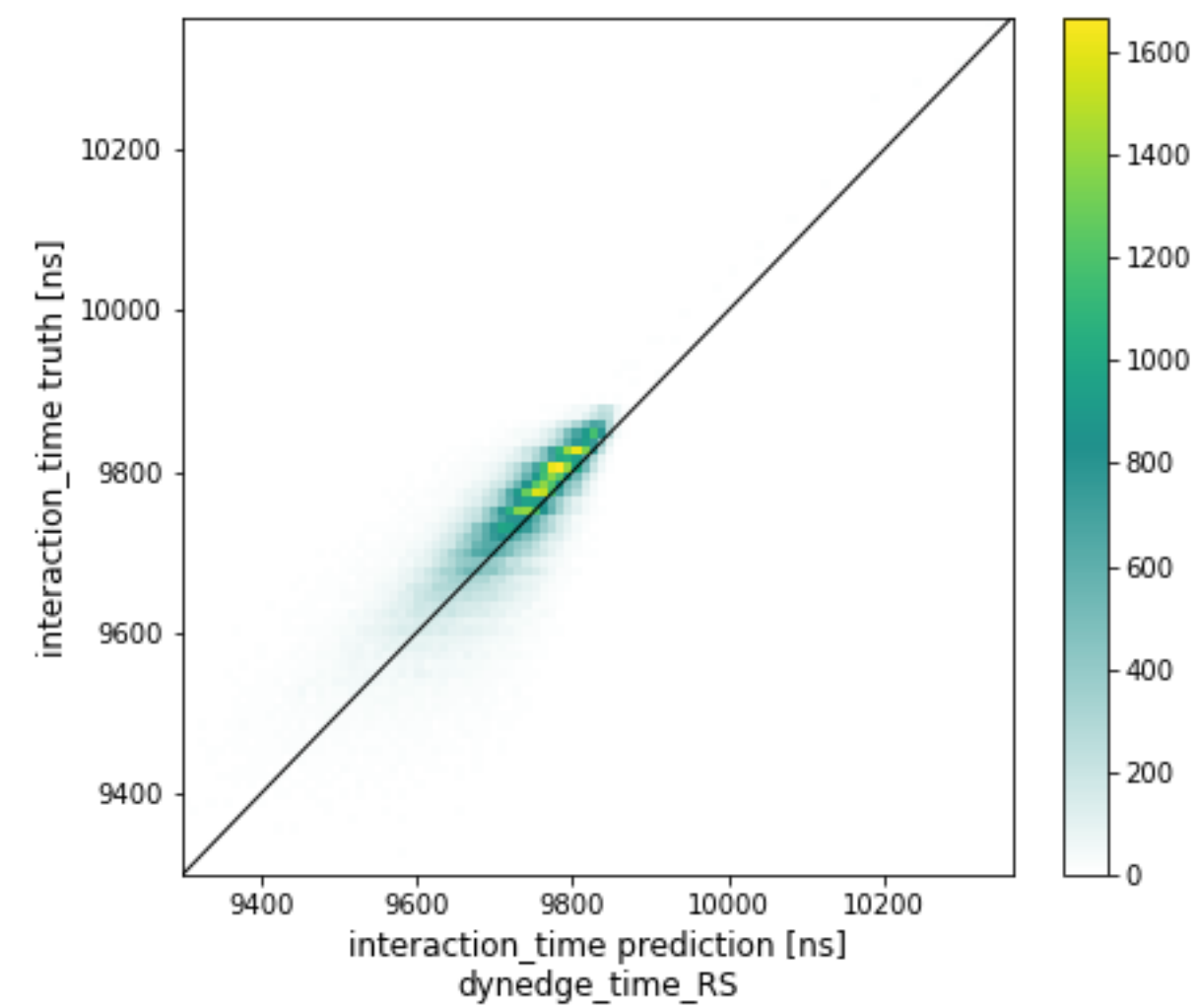
RetroReco



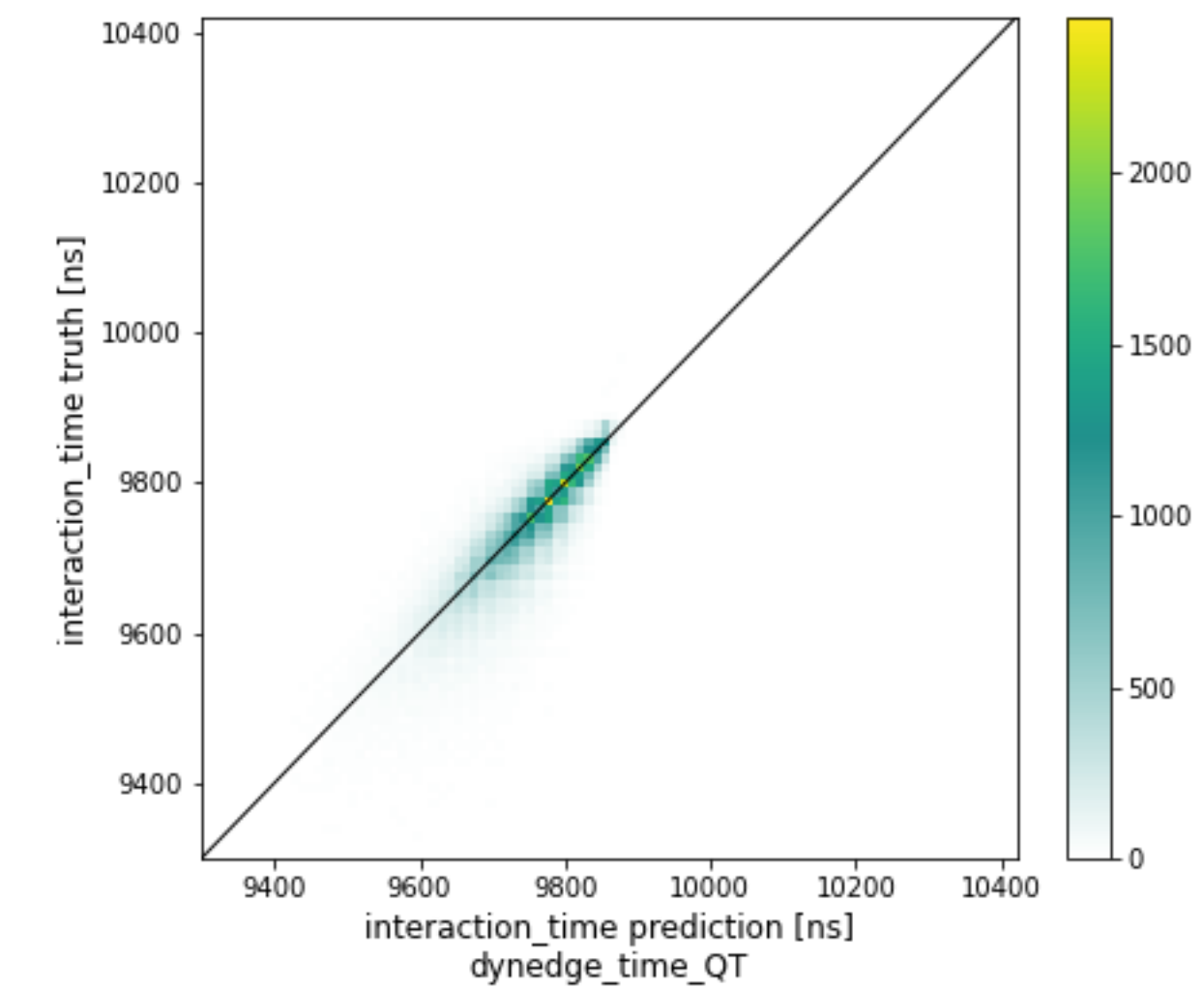
Untransformed



RobustScaler



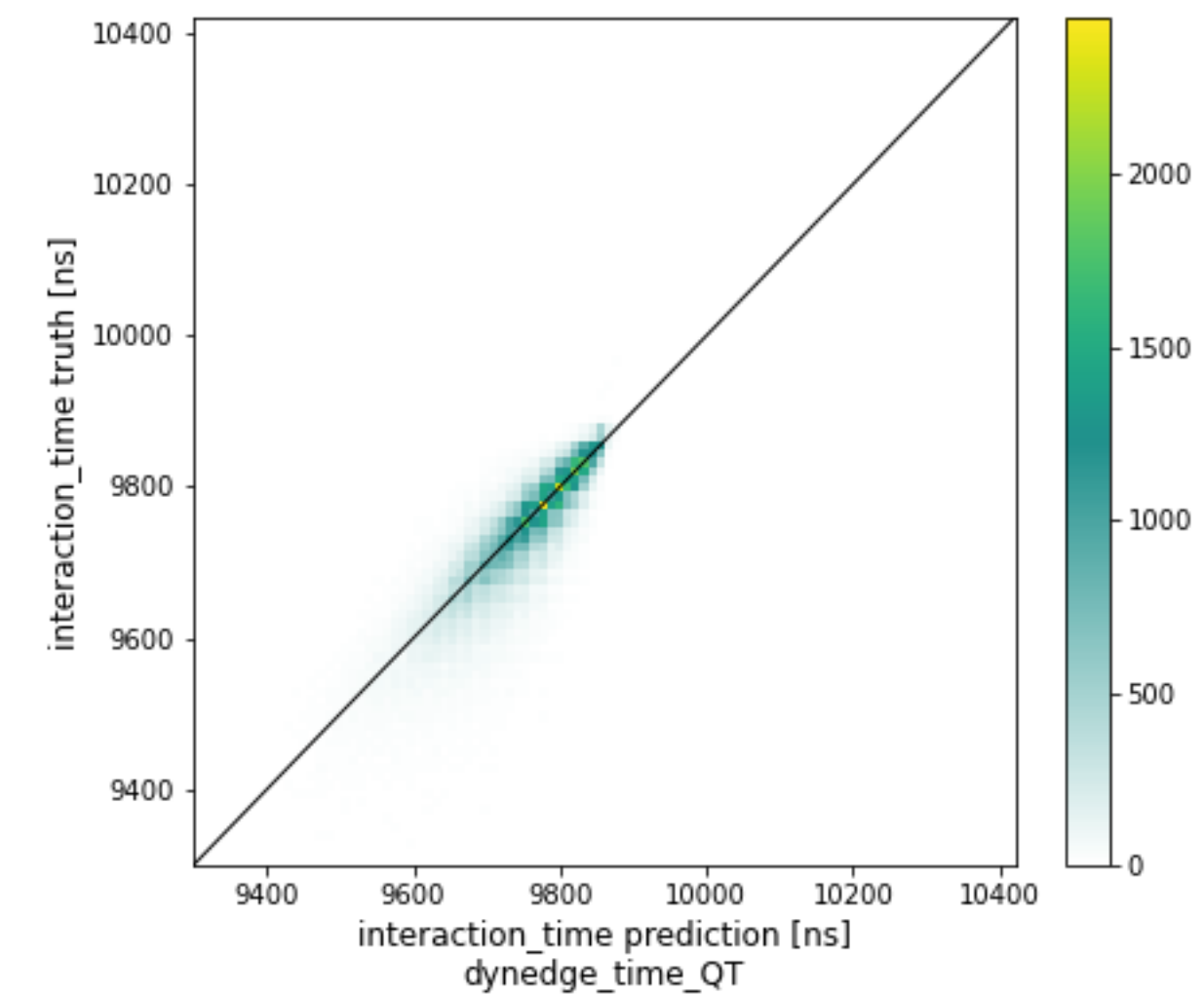
QuantileTransformer



Conclusion:

While non-linear transformations do not work well during ML optimisation, it can be necessary for some regression tasks.

The GraphNeT group has since implemented this in the framework.



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Upgrade Pulse Cleaning

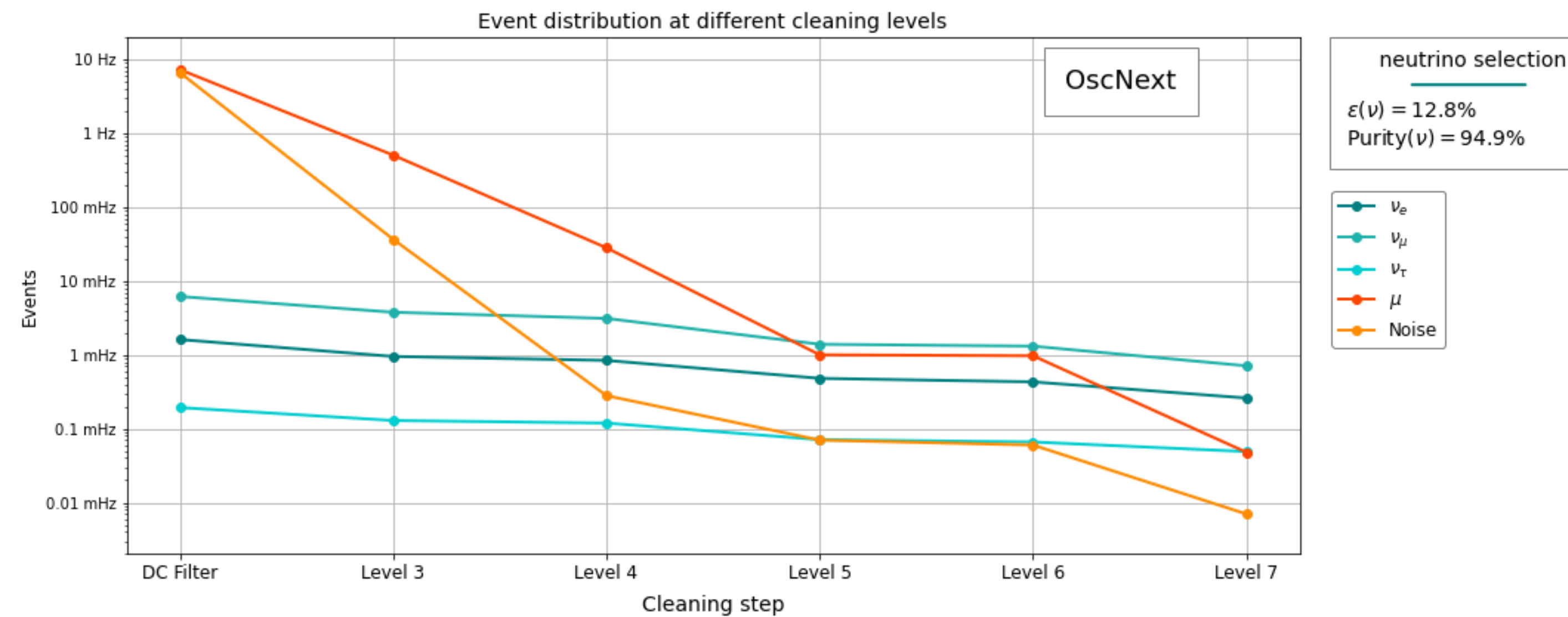
Regression of Cleaned Pulses

Intermezzo 1: Improvement of Pulse Cleaning

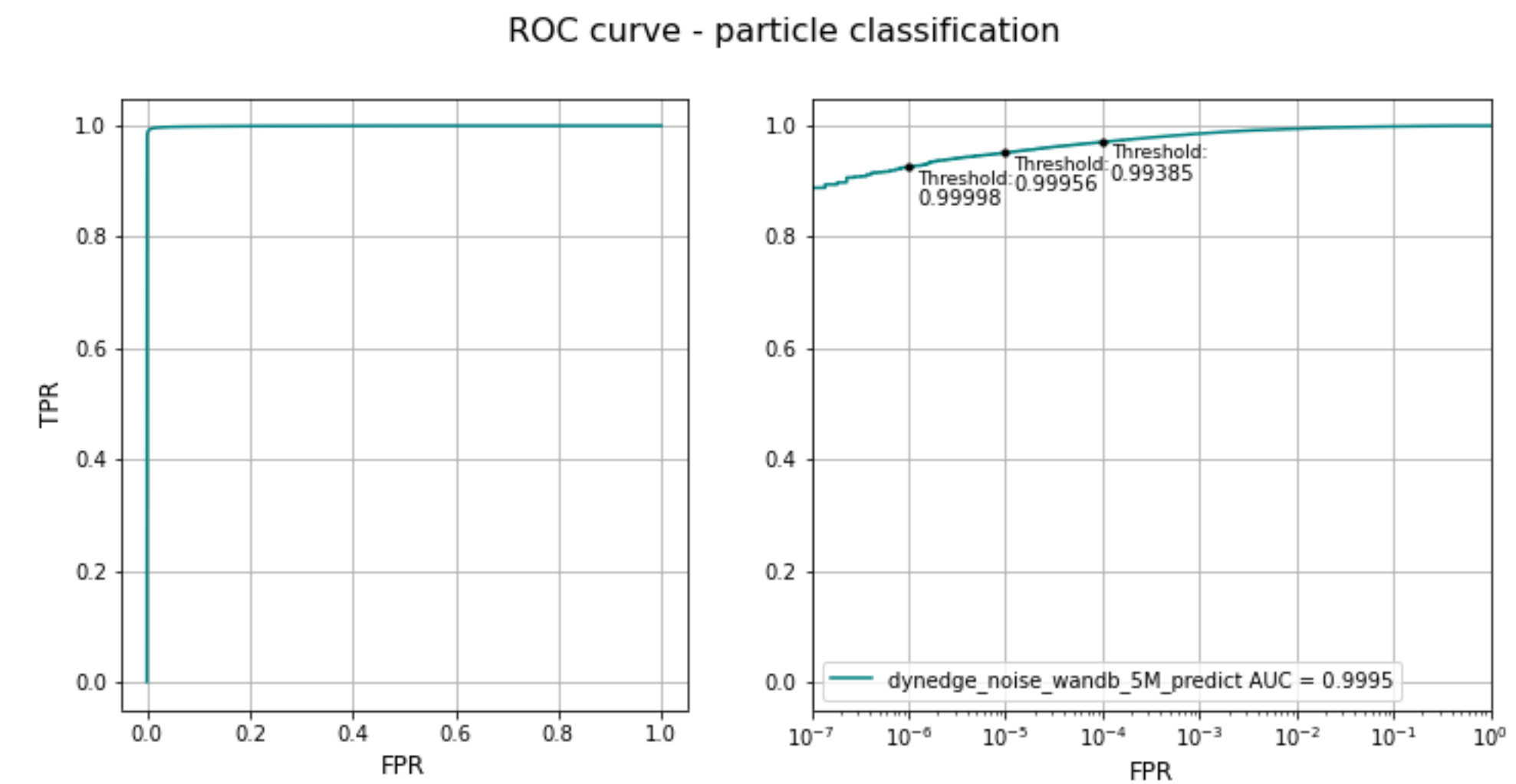
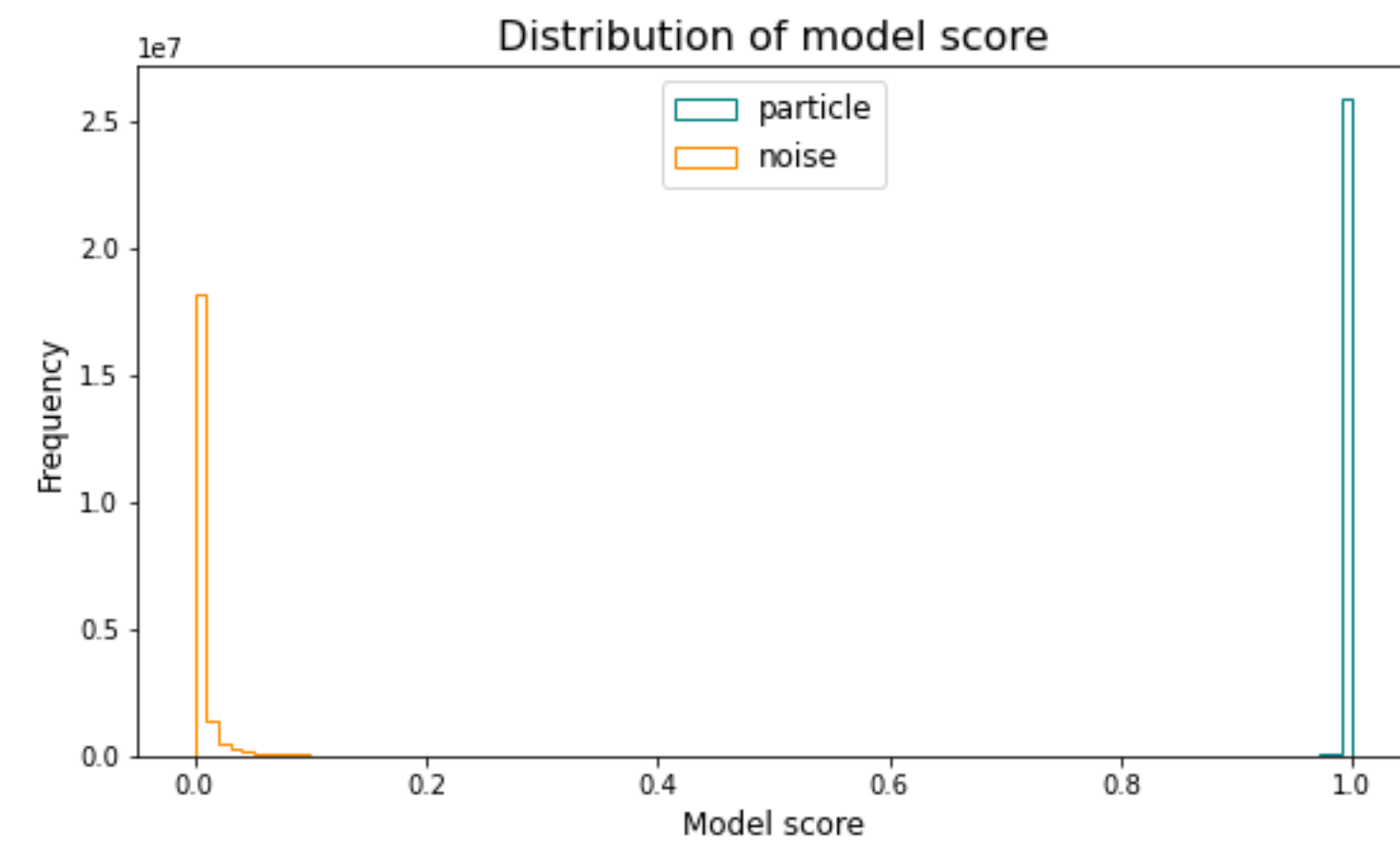
Intermezzo 2: Quality of Cleaned Events

Conclusions & Outlook

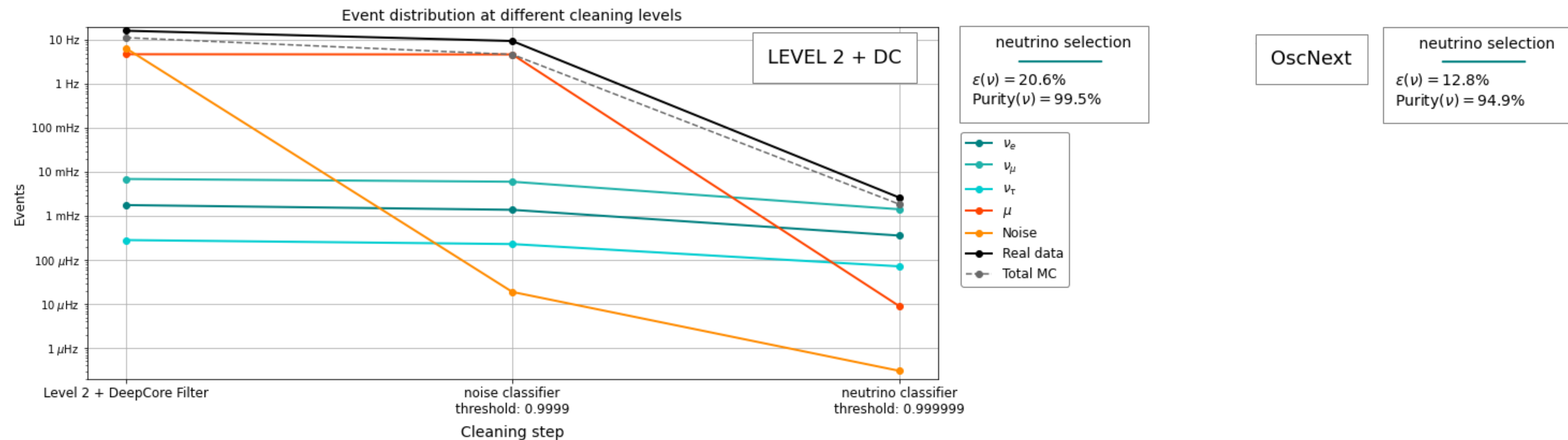
Setup: GNNs have been shown to work well at separating neutrino events from noise and muons. But will it actually improve the OscNext cleaning pipeline, and if so by how much?



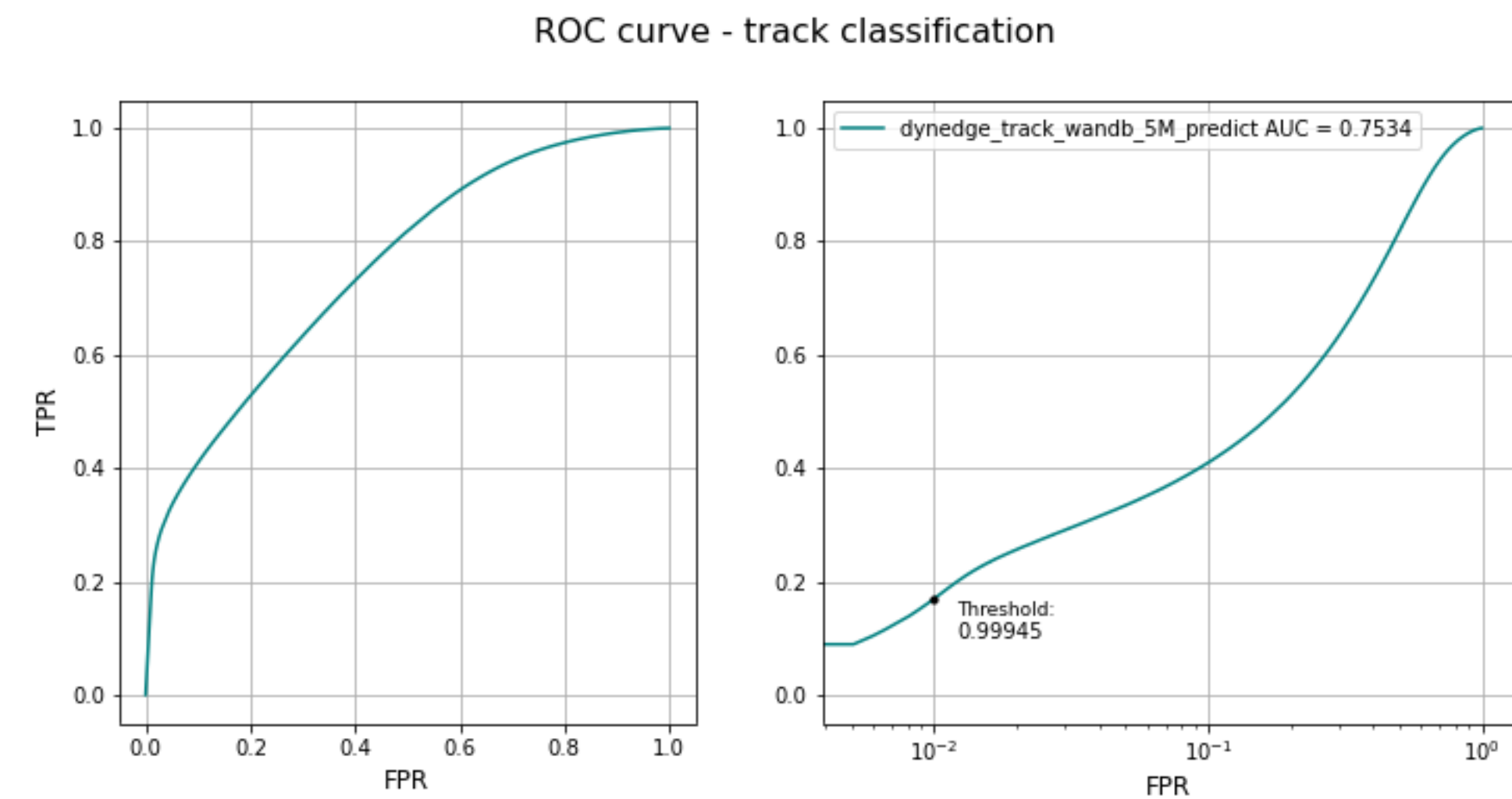
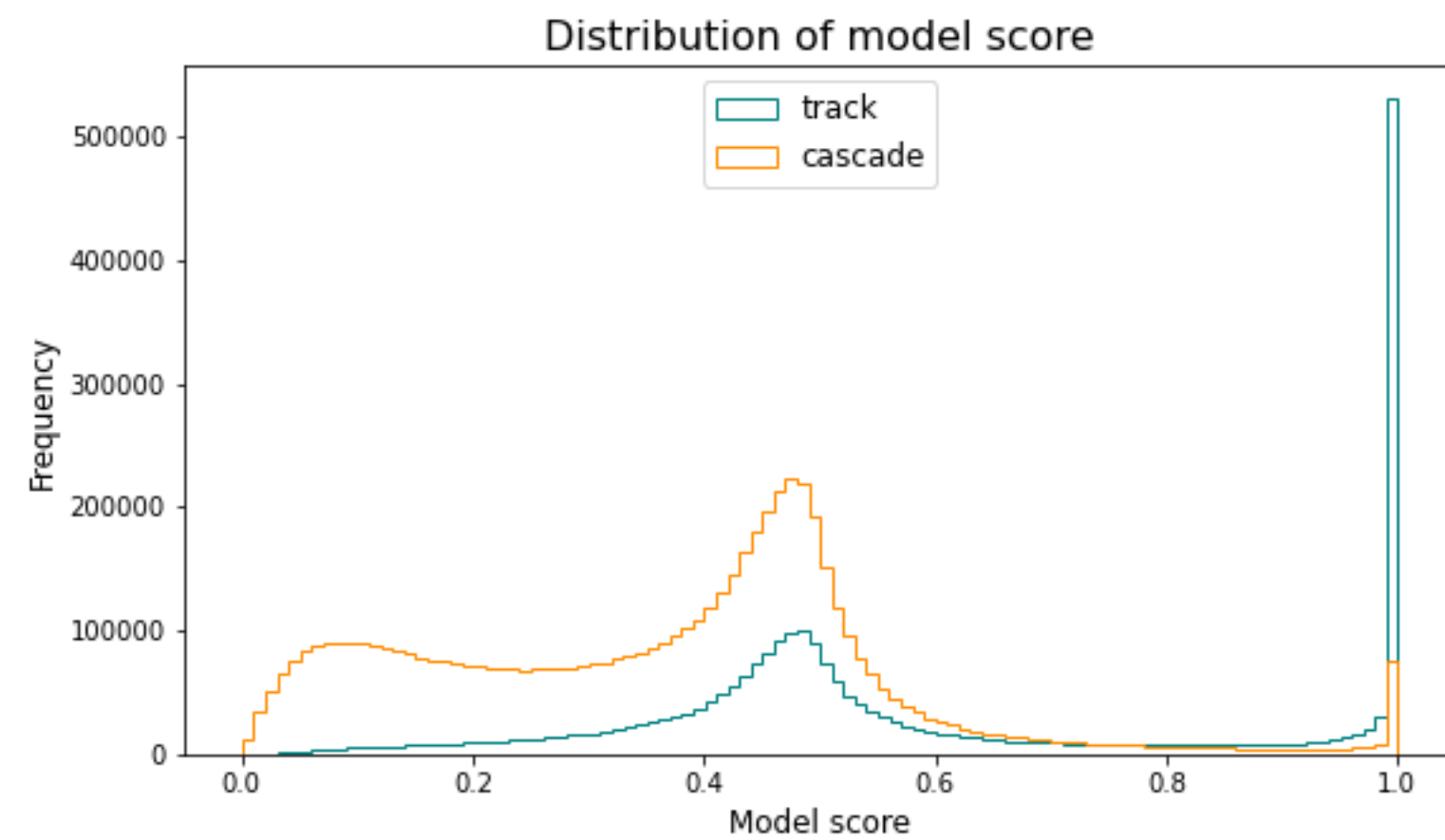
Approach: Train particle/noise classification model



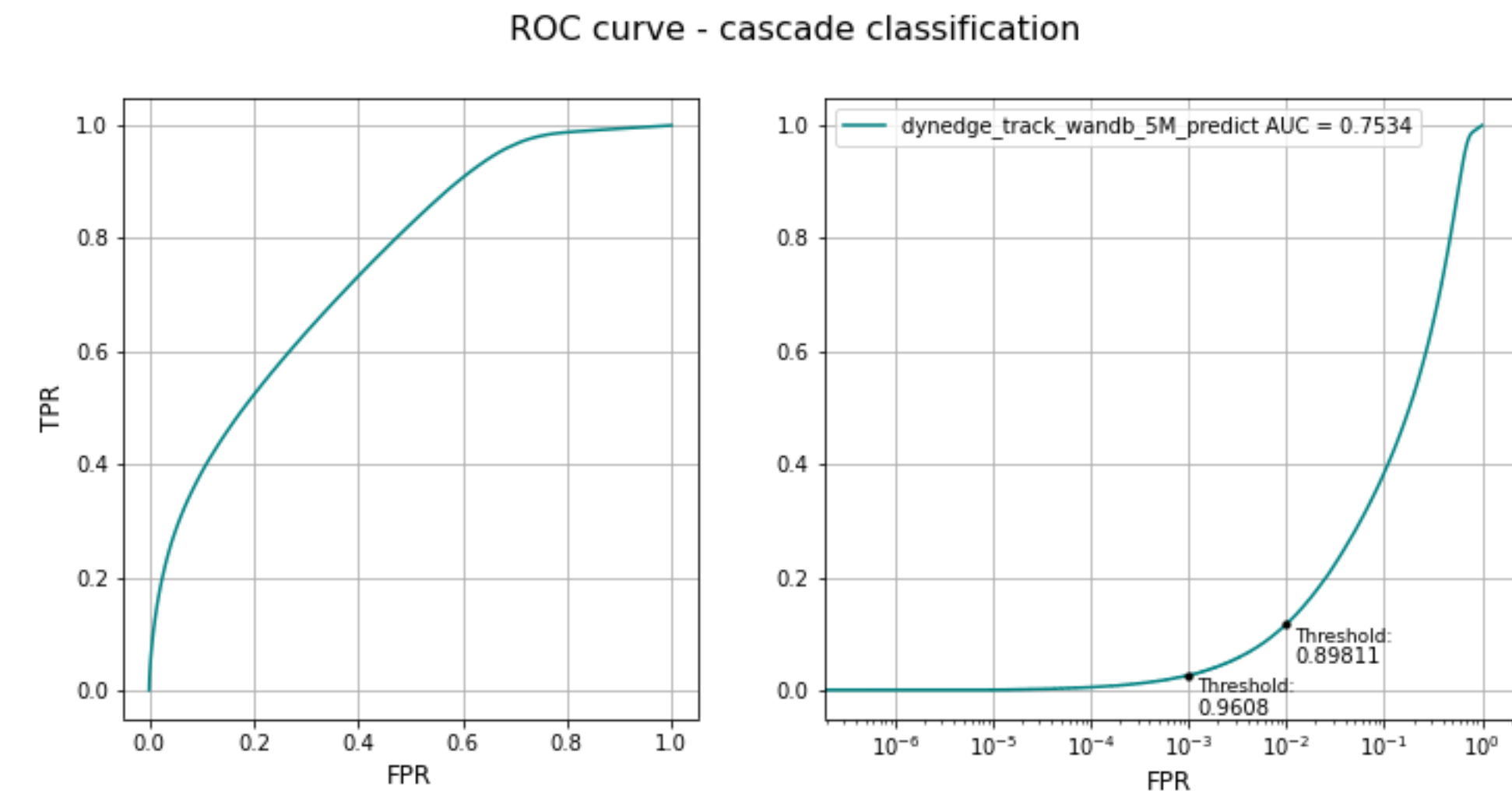
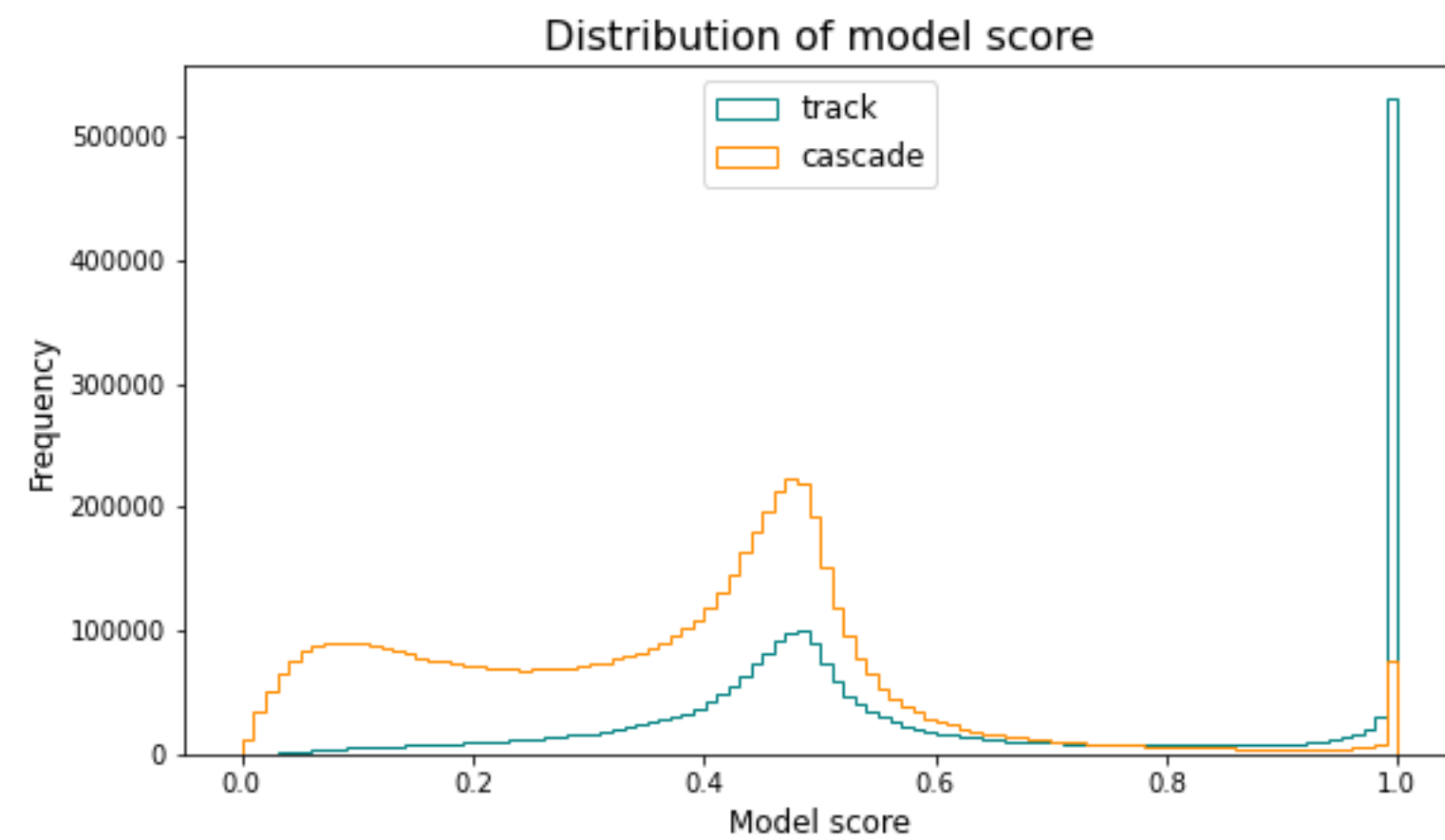
Approach: Train particle/noise classification model (and add neutrino/muon classifier)



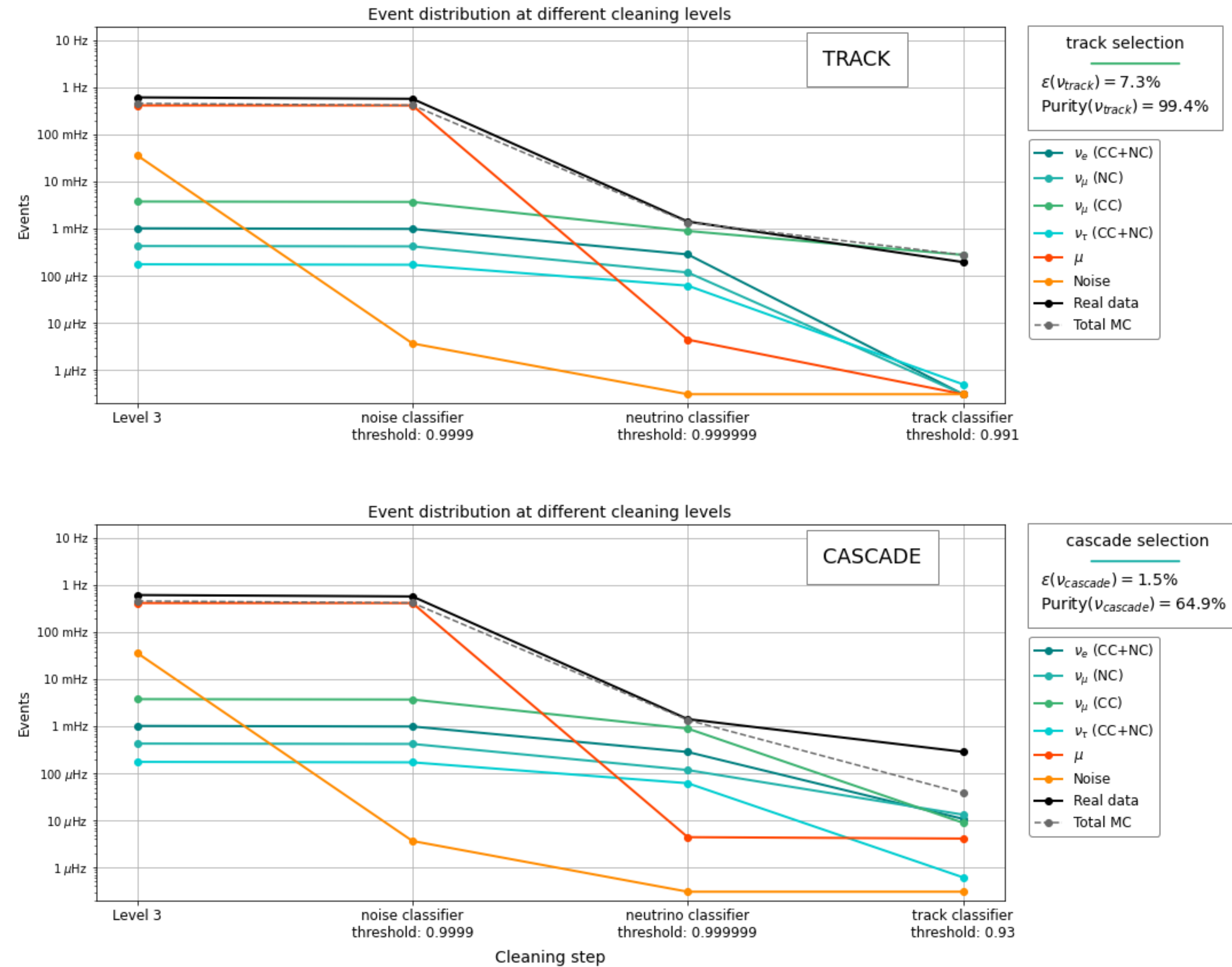
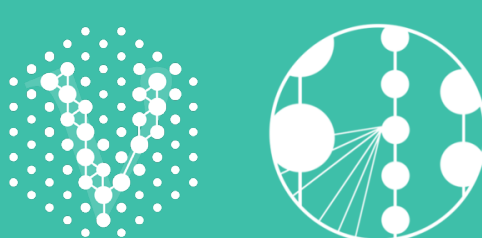
Approach: Add track/cascade classification model



Approach: Add track/cascade classification model



Event Selection Pipeline



Conclusions:

Using GNNs for the OscNext events selection could improve the efficiency from 12.8% to 20.6% and the purity from 94.9 % to 99.5 %.

Real data comparison looks promising.

Track/cascade separation is hard but possible.

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IceCube Upgrade is the envisioned low-energy-focused extension of the IceCube detector array

Upgrade features higher detector density and new DOM types

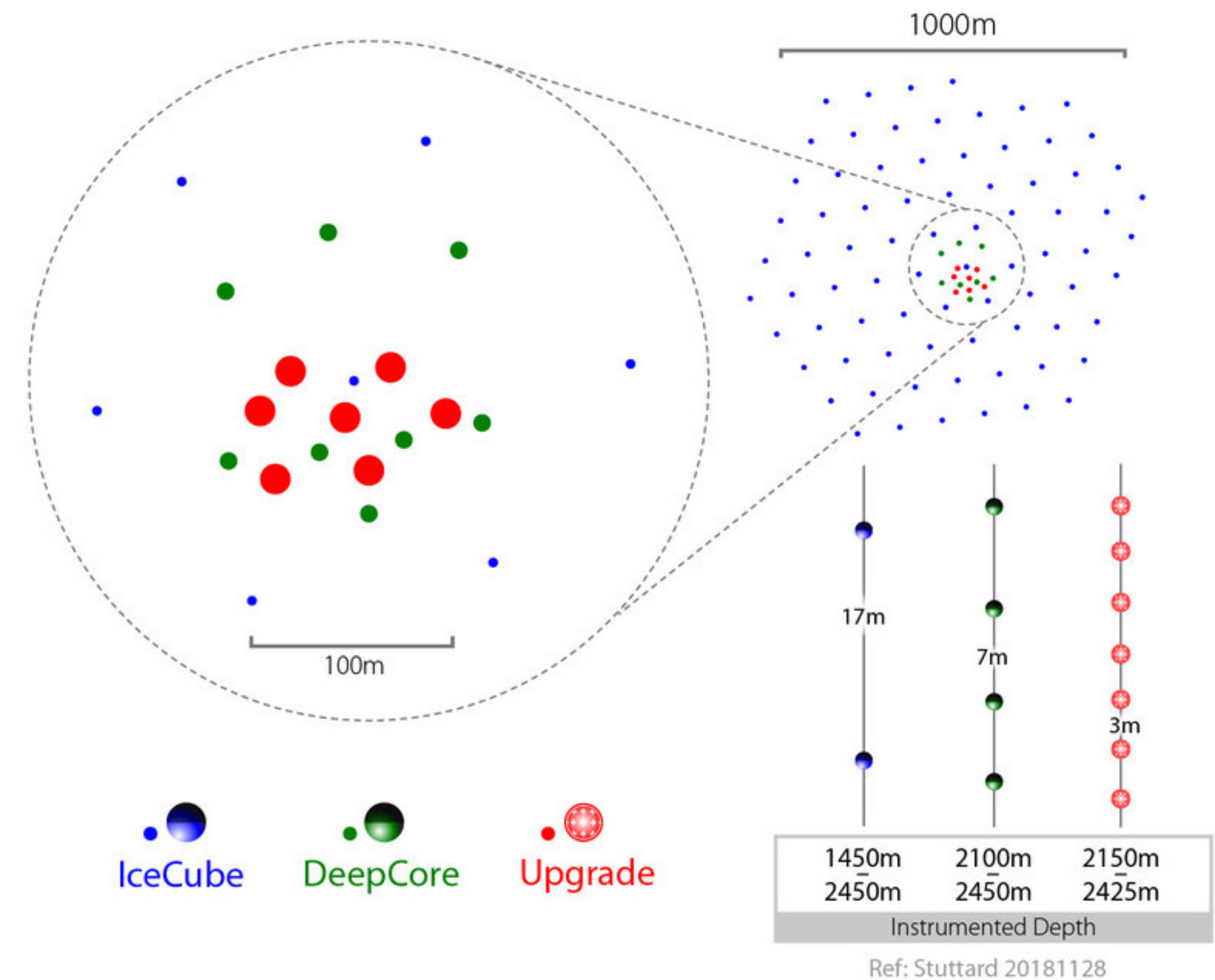


Figure from Marek L. Kowalski, *Next generation neutrino detectors at the South Pole*

Setup: The new Upgrade DOMs are very noisy due to contamination with radioactive isotopes.

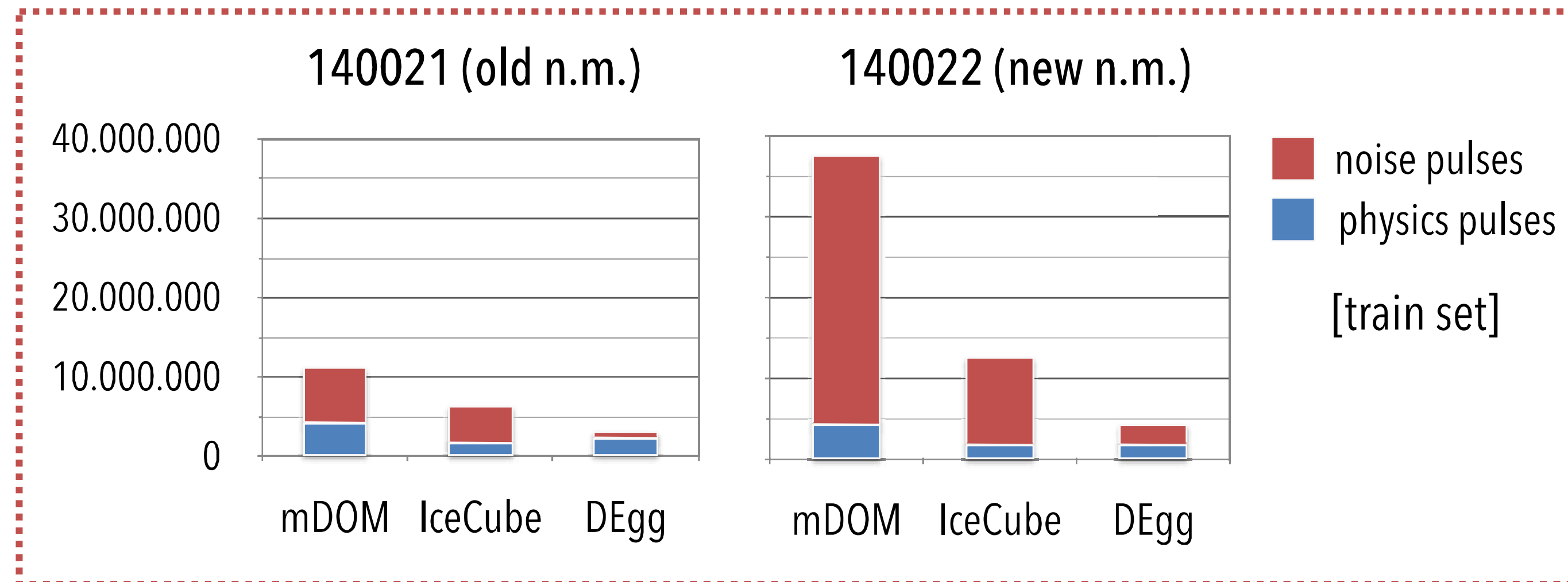


Figure from [Tania Kozynets & Tom Stuttard](#), *GNN-assisted pulse cleaning for the IceCube-Upgrade*

Setup: The new Upgrade DOMs are very noisy due to contamination with radioactive isotopes.

Promising pulse cleaning has already been demonstrated using a simple GNN.

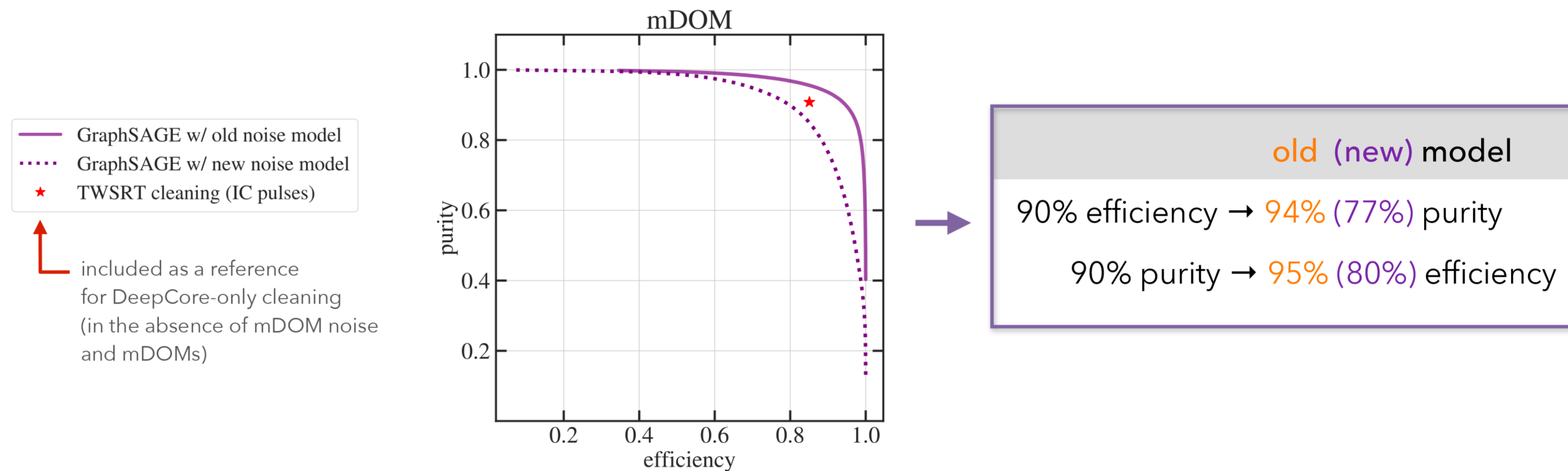
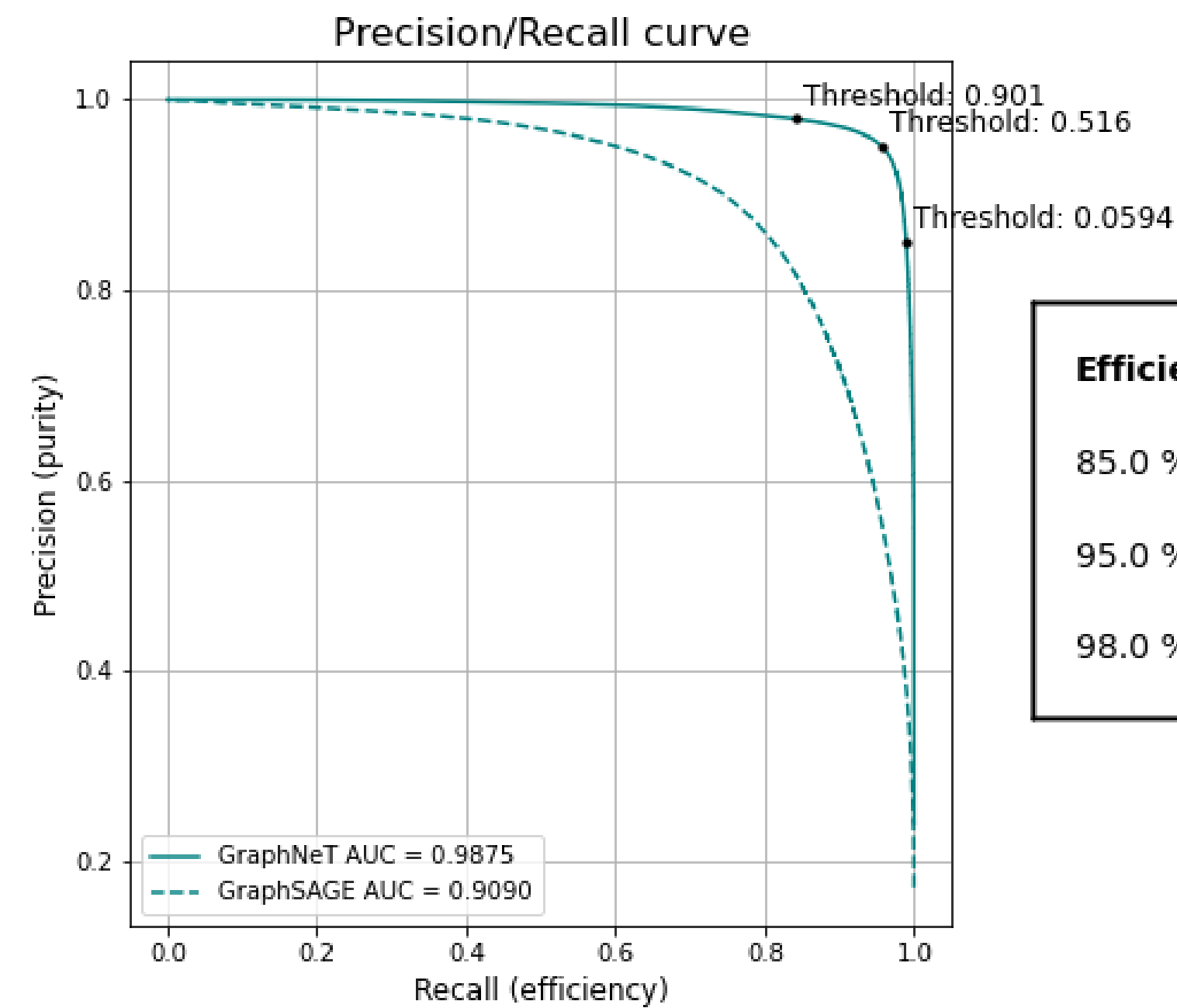
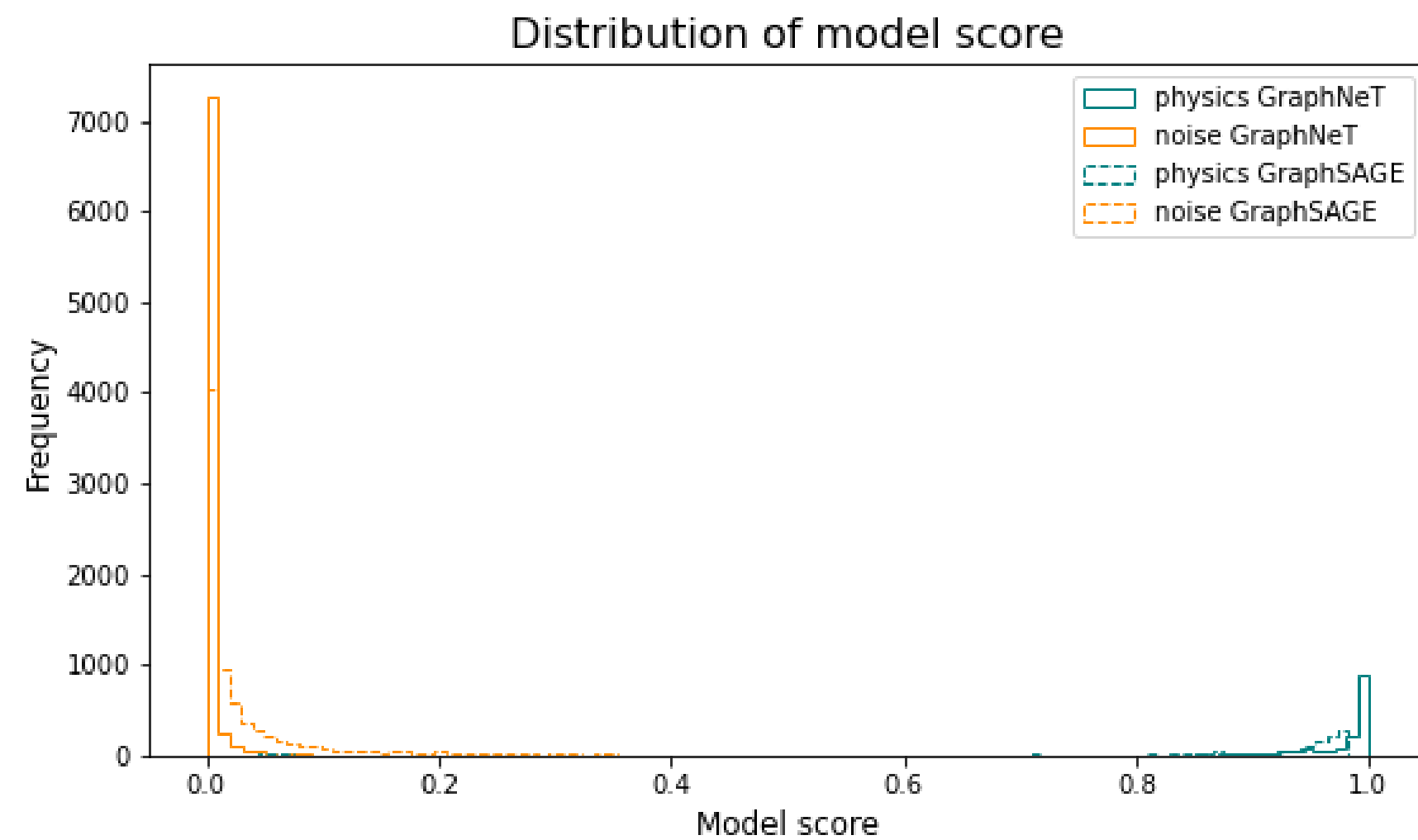


Figure from Tania Kozynets & Tom Stuttard, *GNN-assisted pulse cleaning for the IceCube-Upgrade*

Approach: Train a model for pulse-level noise cleaning using the DynEdge architecture

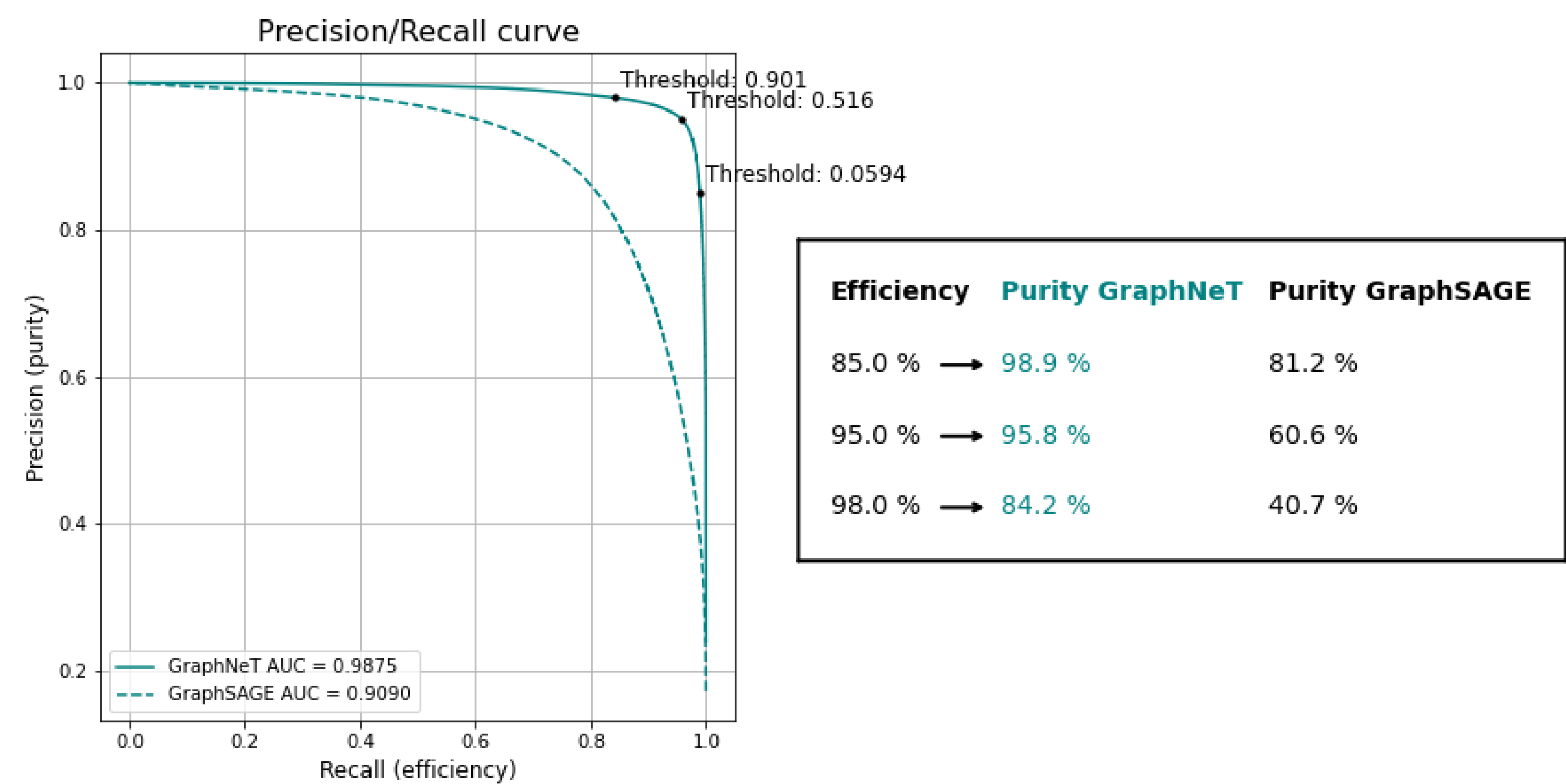


Efficiency	Purity GraphNeT	Purity GraphSAGE
85.0 %	→ 98.9 %	81.2 %
95.0 %	→ 95.8 %	60.6 %
98.0 %	→ 84.2 %	40.7 %

Conclusions:

Pulse cleaning using DynEdge works well compared to the previous model.

The real test should to see if the additional noise can be nullified by the pulse cleaning.



Introduction

My Work

Time Regression

Event Cleaning

Upgrade Pulse Cleaning

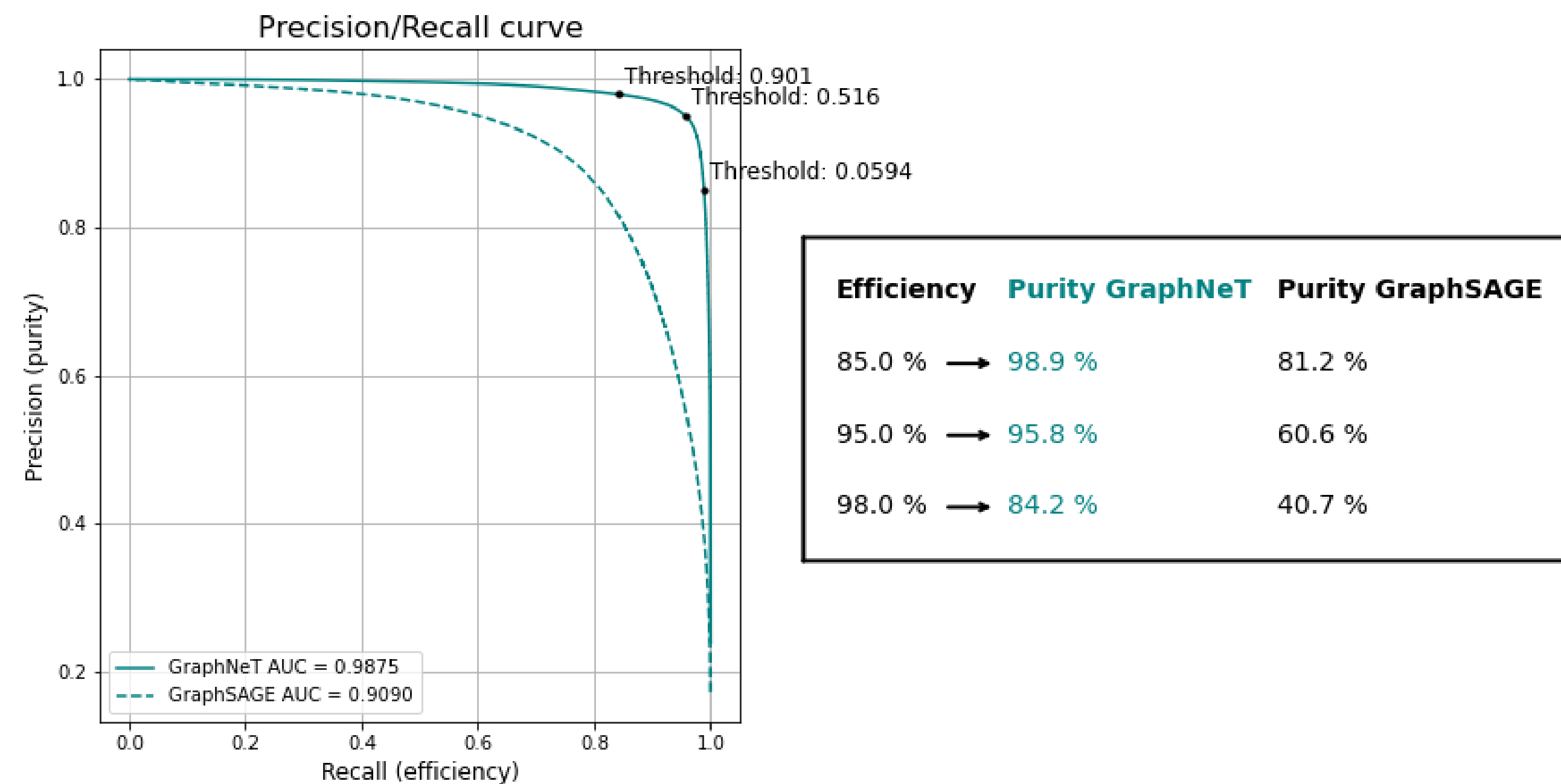
Regression of Cleaned Pulses

Intermezzo 1: Improvement of Pulse Cleaning

Intermezzo 2: Quality of Cleaned Events

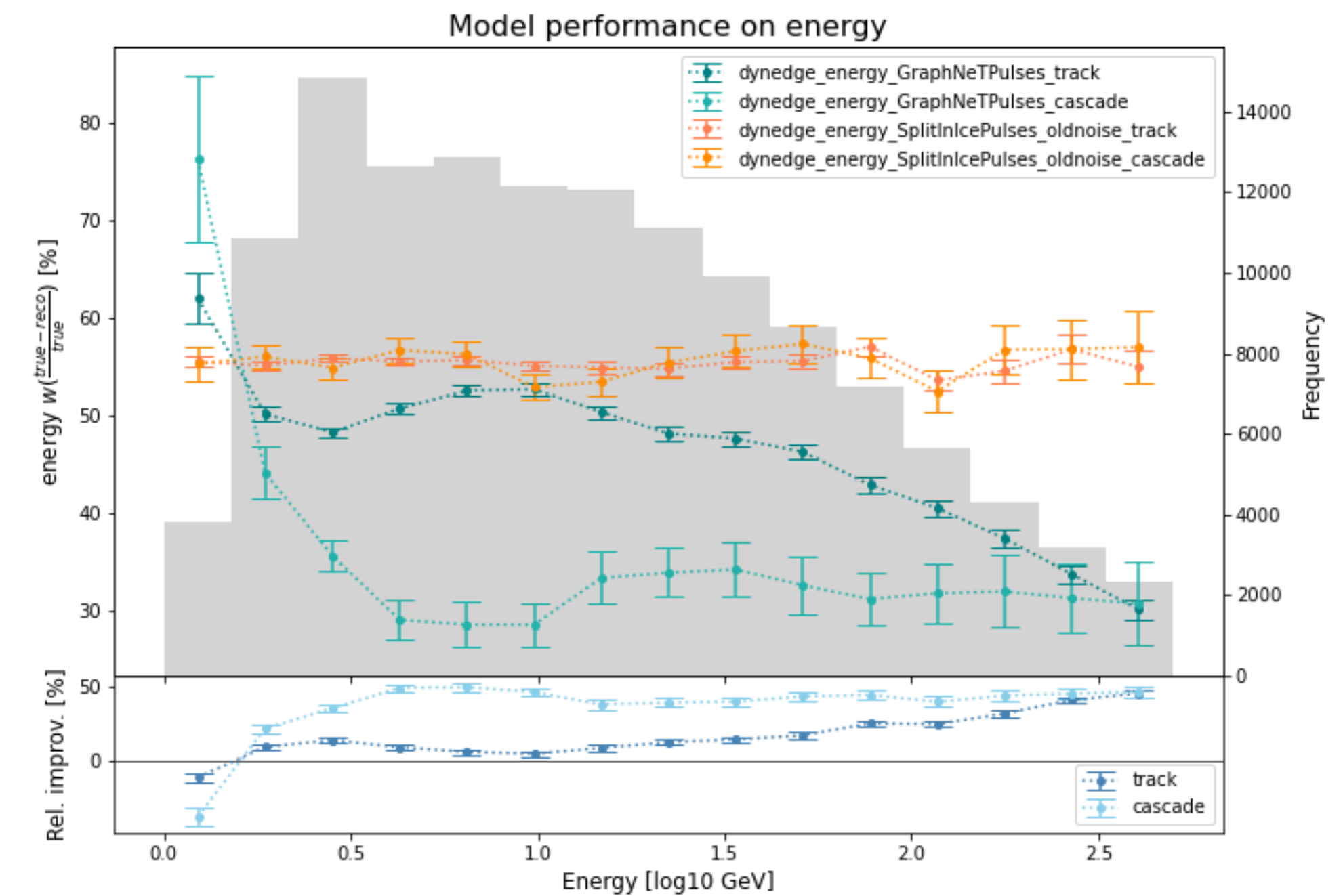
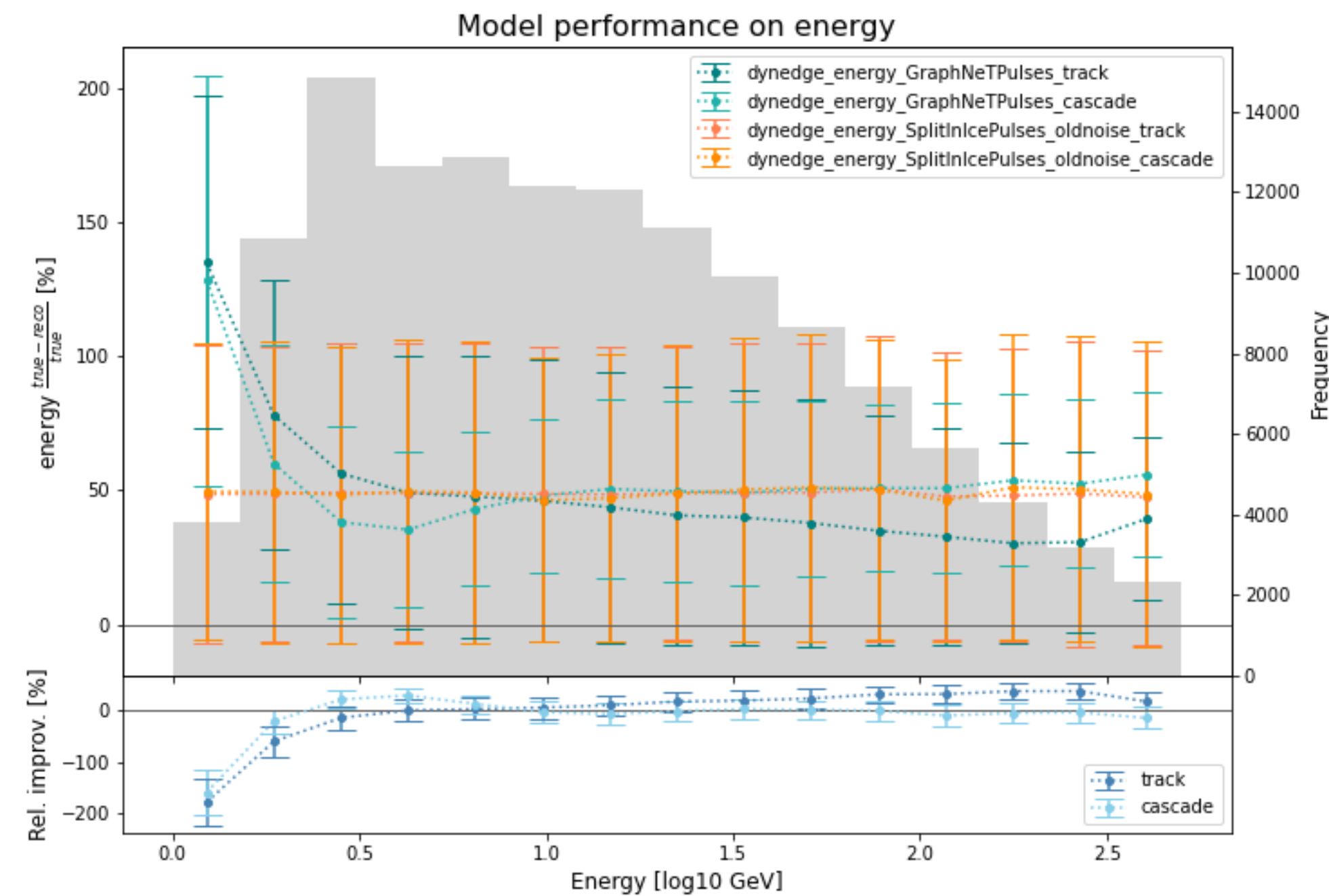
Conclusions & Outlook

Setup: With no real comparison for the pulse cleaning, we want to get a measure of its effect on the upgrade data.



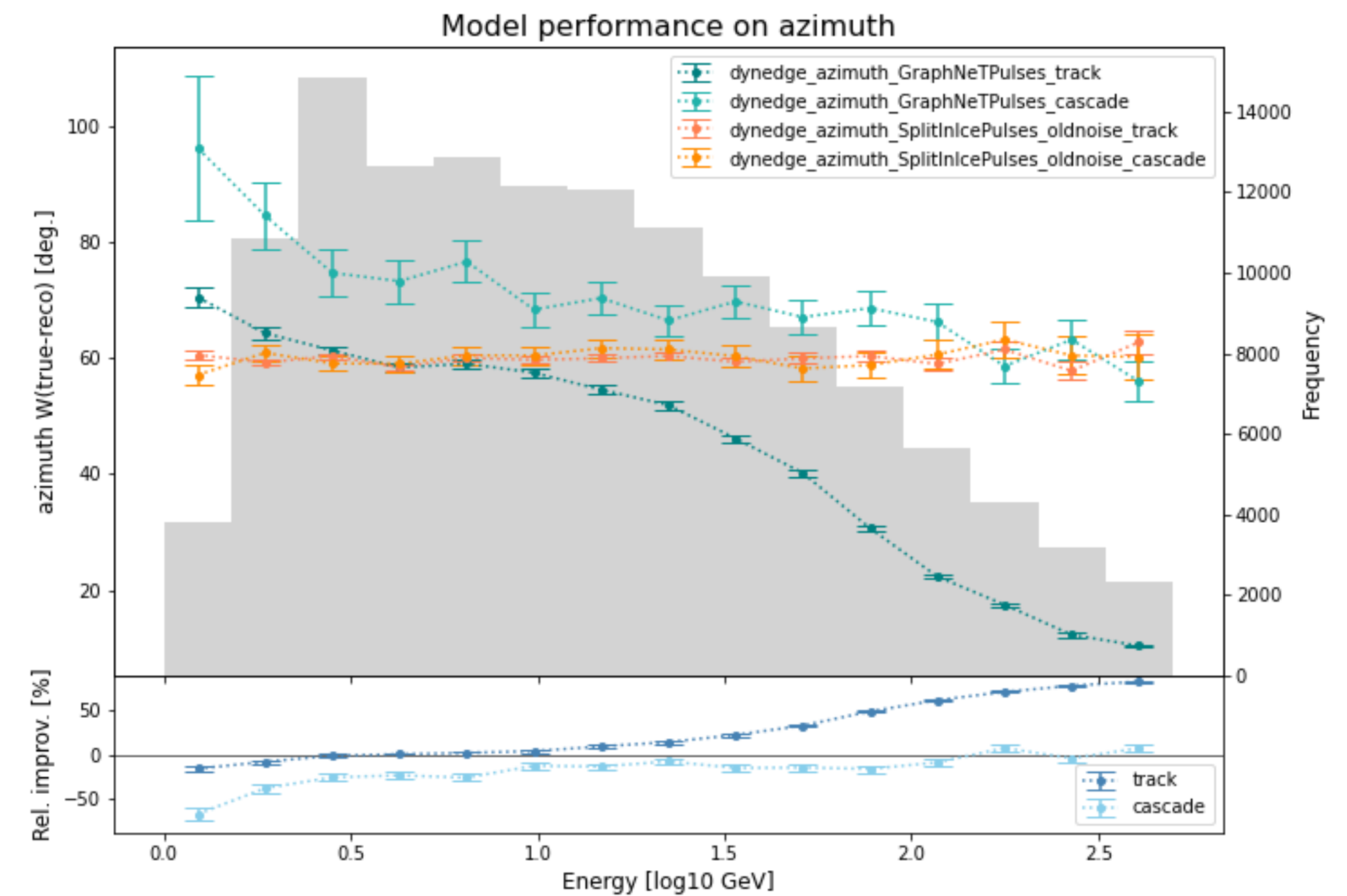
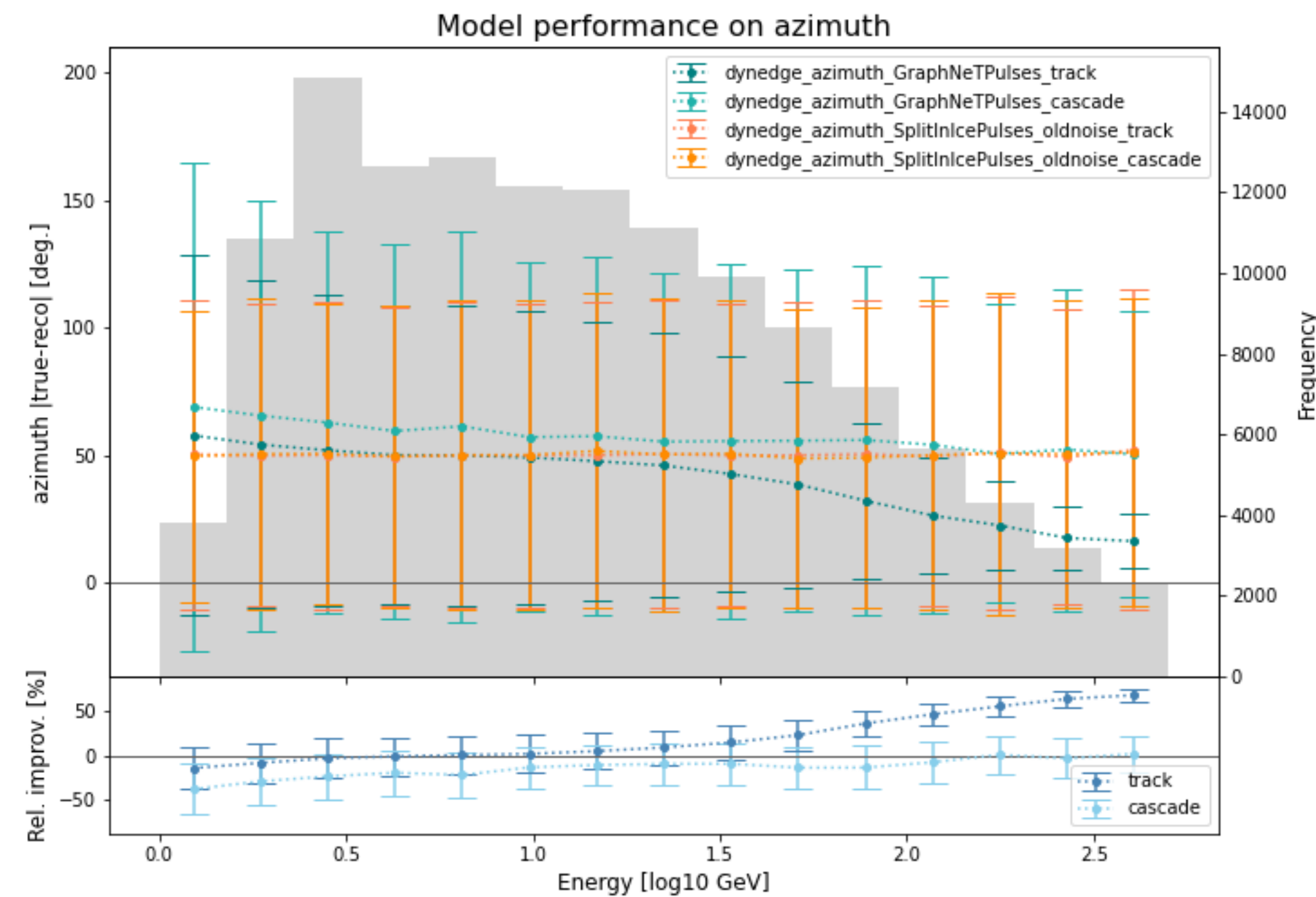
Approach: Train regression models on cleaned data and uncleaned data with the old and new noise models.

Energy



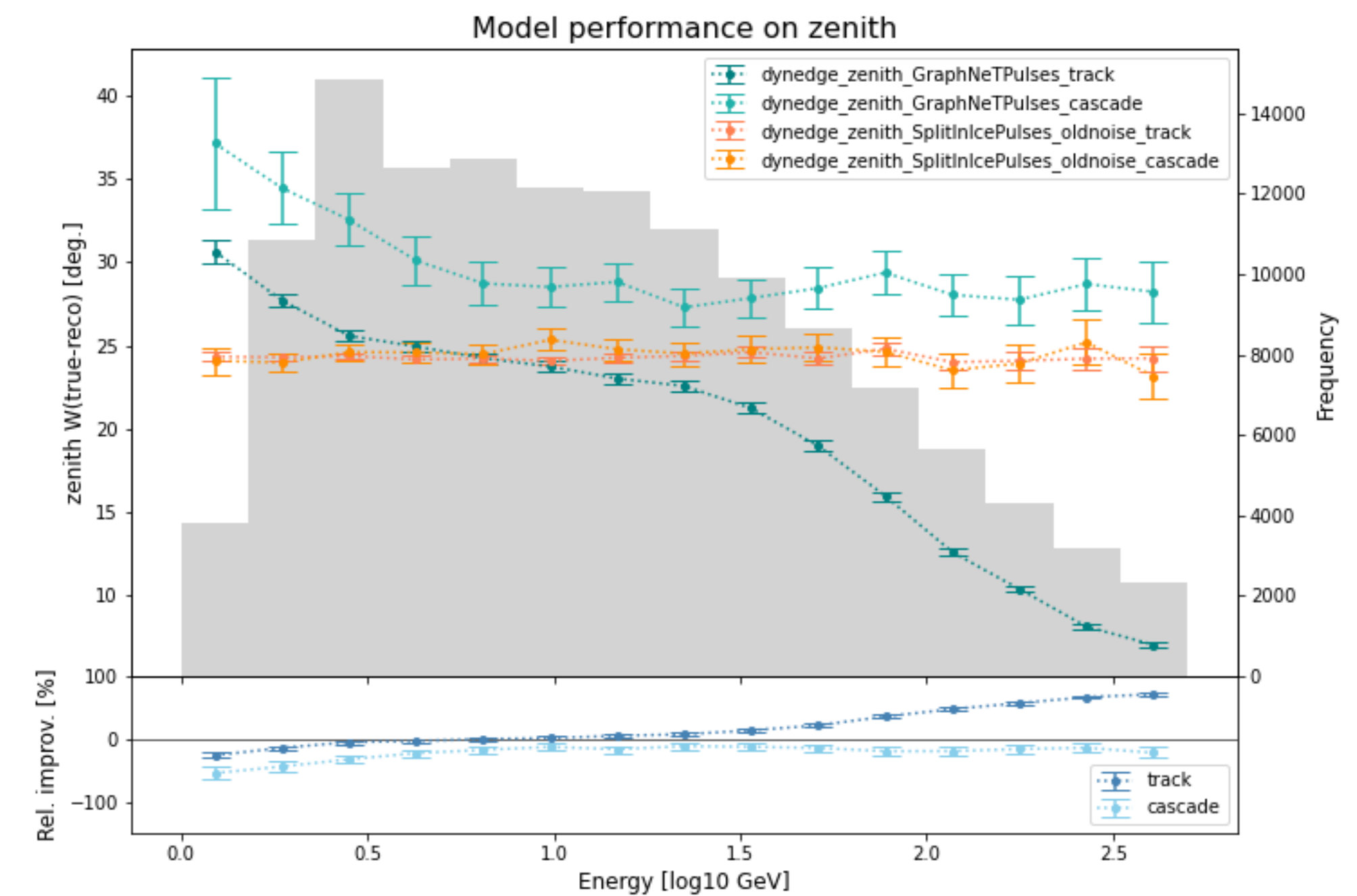
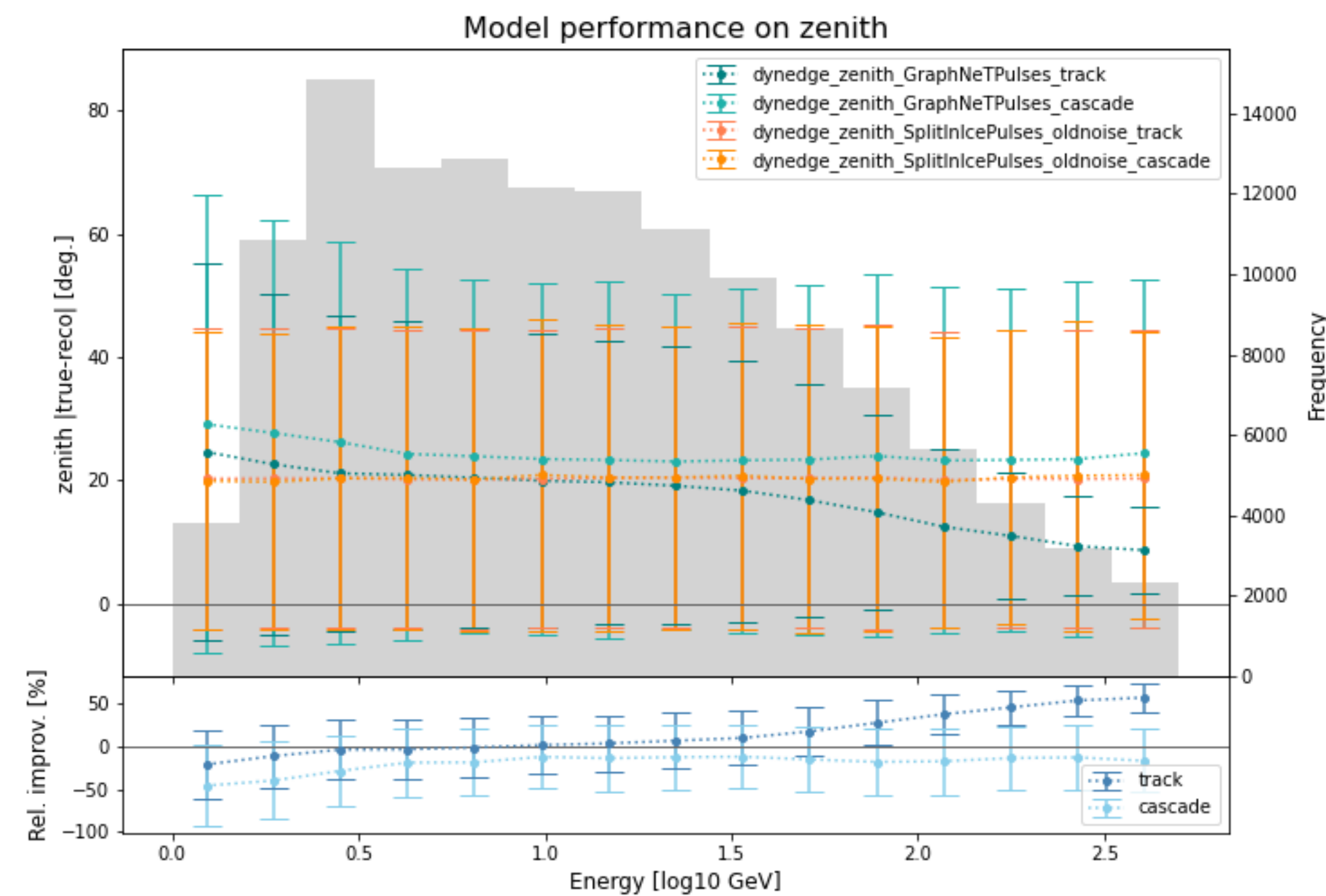
Approach: Train regression models on cleaned data and uncleaned data with the old and new noise models.

Azimuth



Approach: Train regression models on cleaned data and uncleaned data with the old and new noise models.

Zenith



Conclusions:

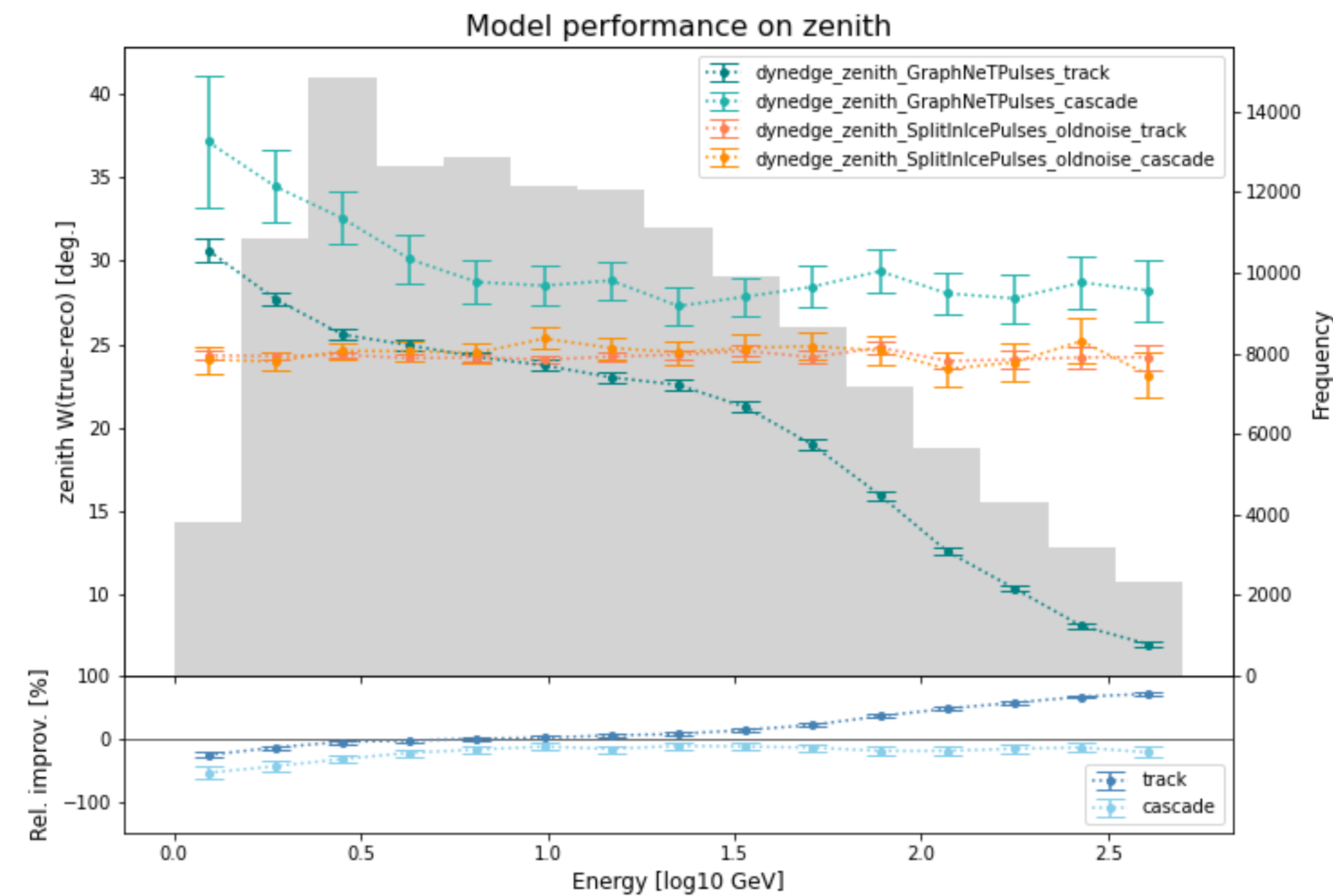
Pulse cleaning improves reconstruction performance so that it is comparable to the old noise model.

Reconstruction is still lacking in certain ranges, namely the low-energy regime and the cascade-like events.

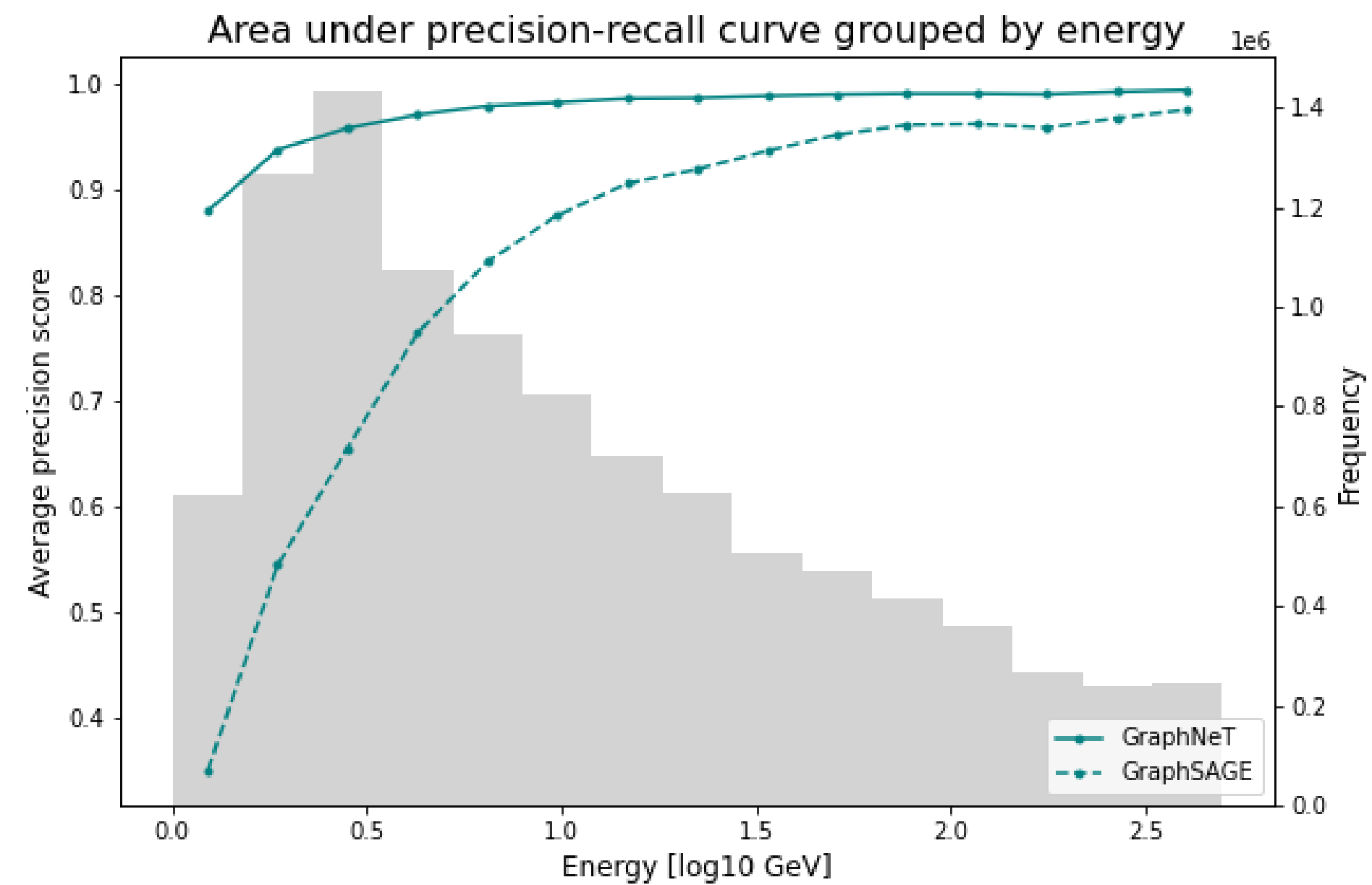
Intermezzo 1

Revisiting Pulse Cleaning

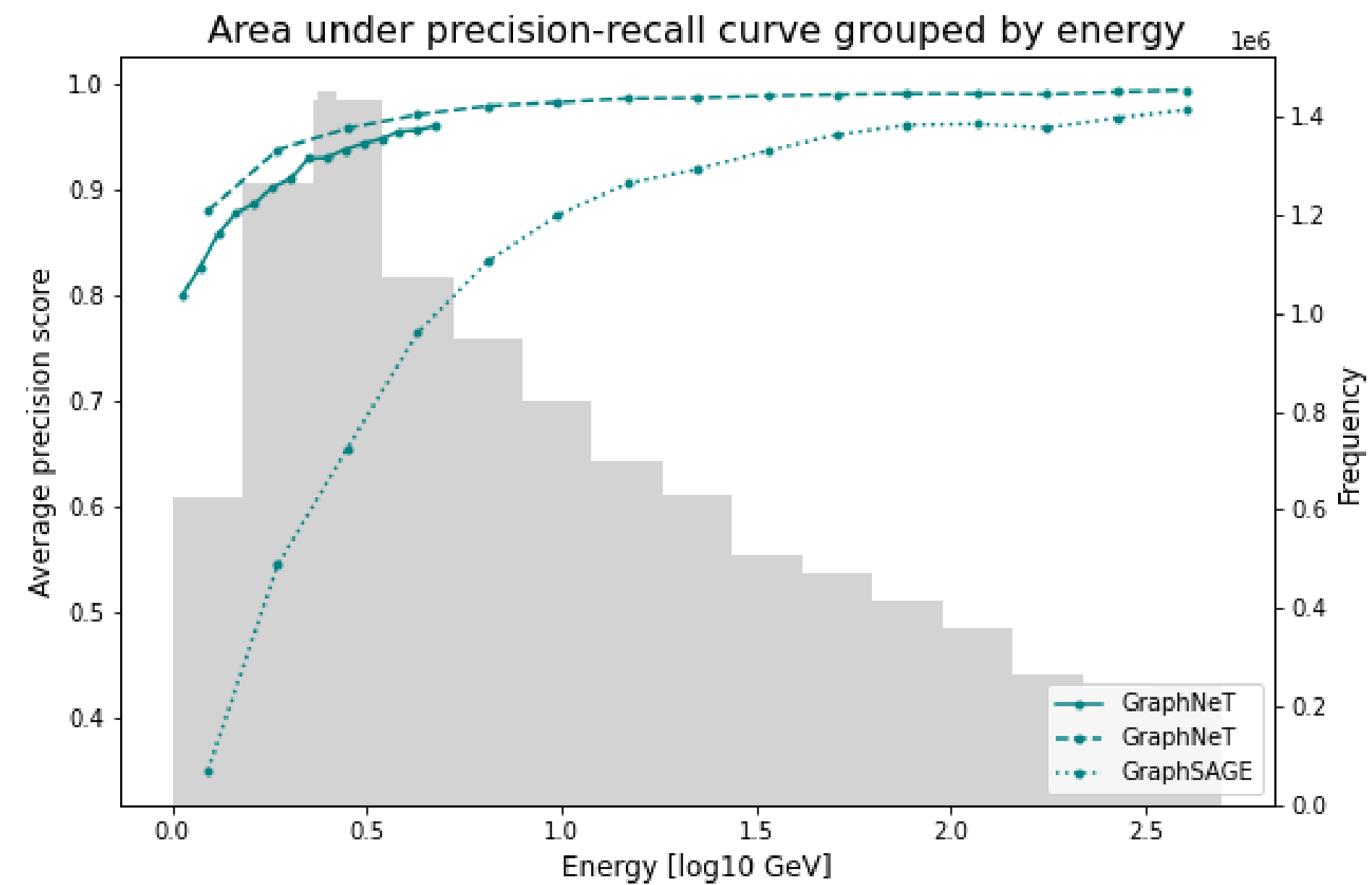
Setup: With reconstruction performance lacking in distinct ranges, improvements to the pulse cleaning or event selection could improve reconstruction.



Approach 1: Train a model for low energy events separately

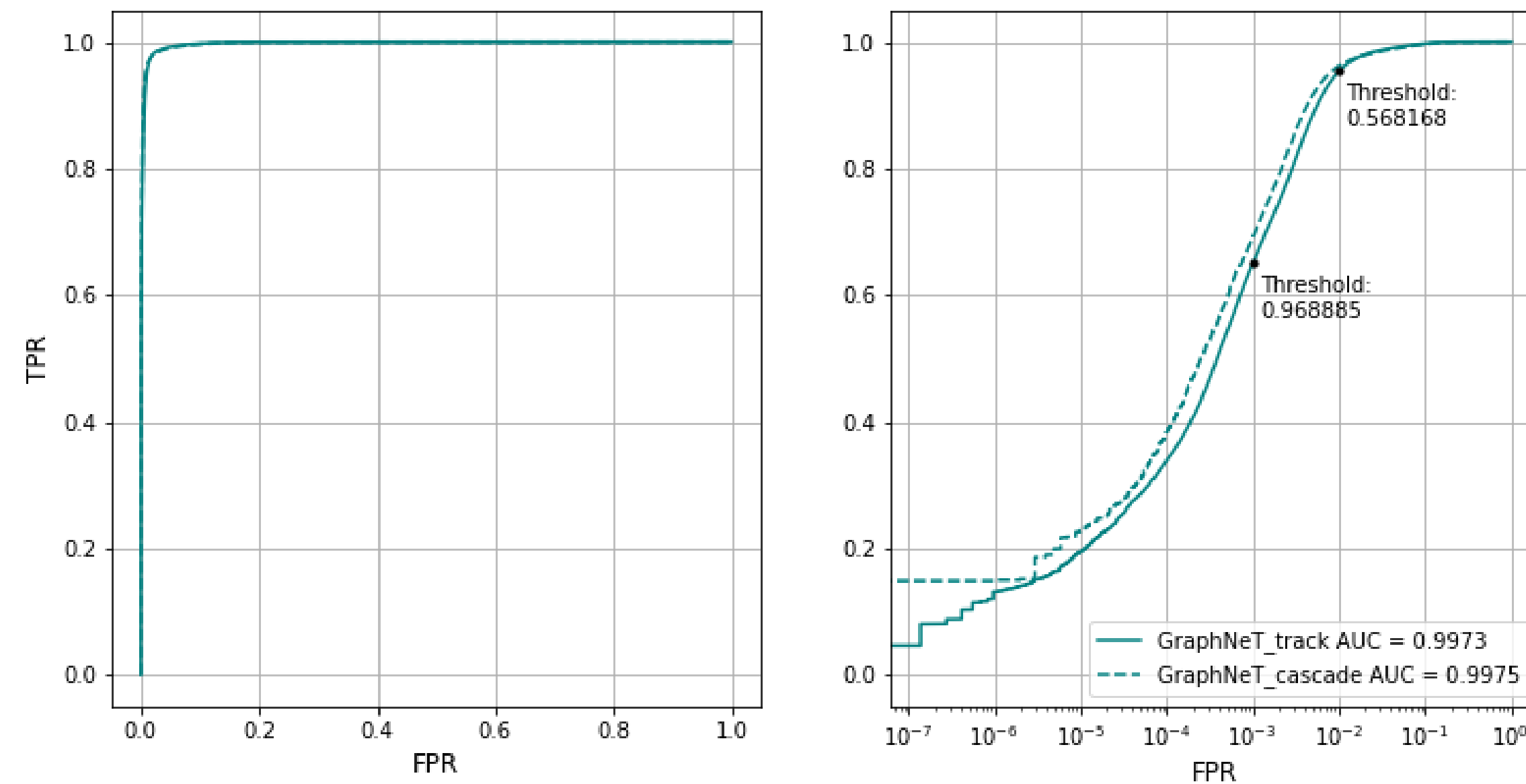


Approach 1: Train a model for low energy events separately

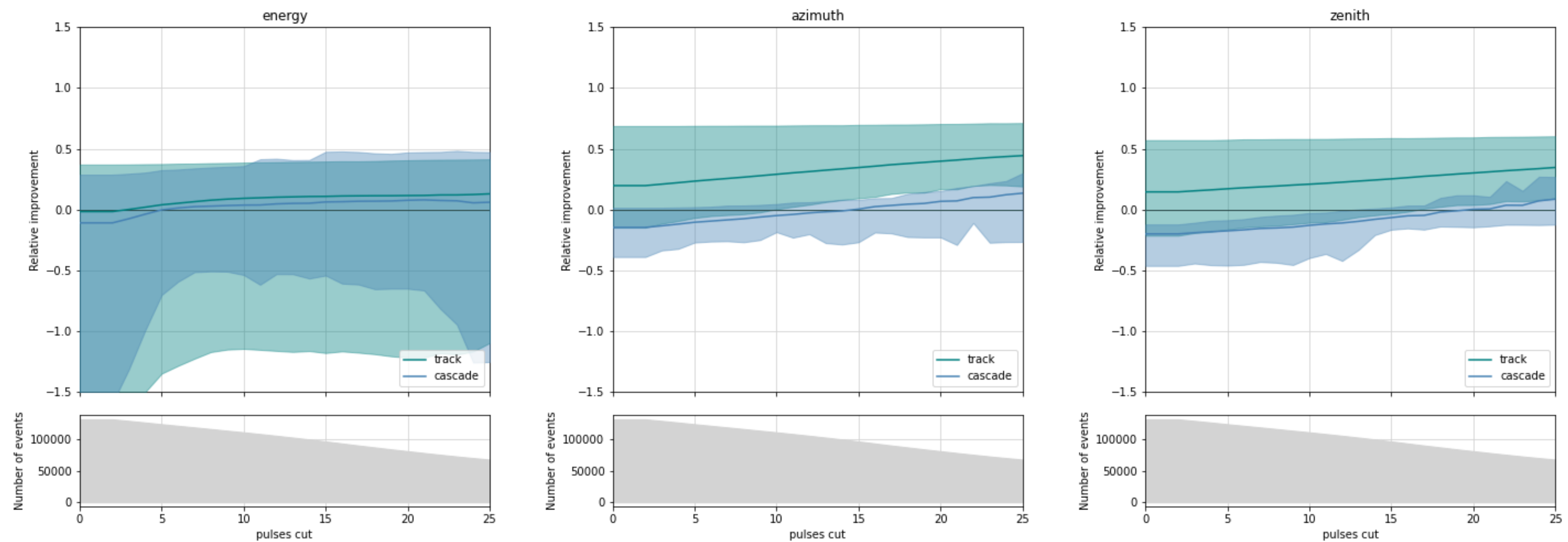


Approach 2: Train a model for track/cascade-like events separately

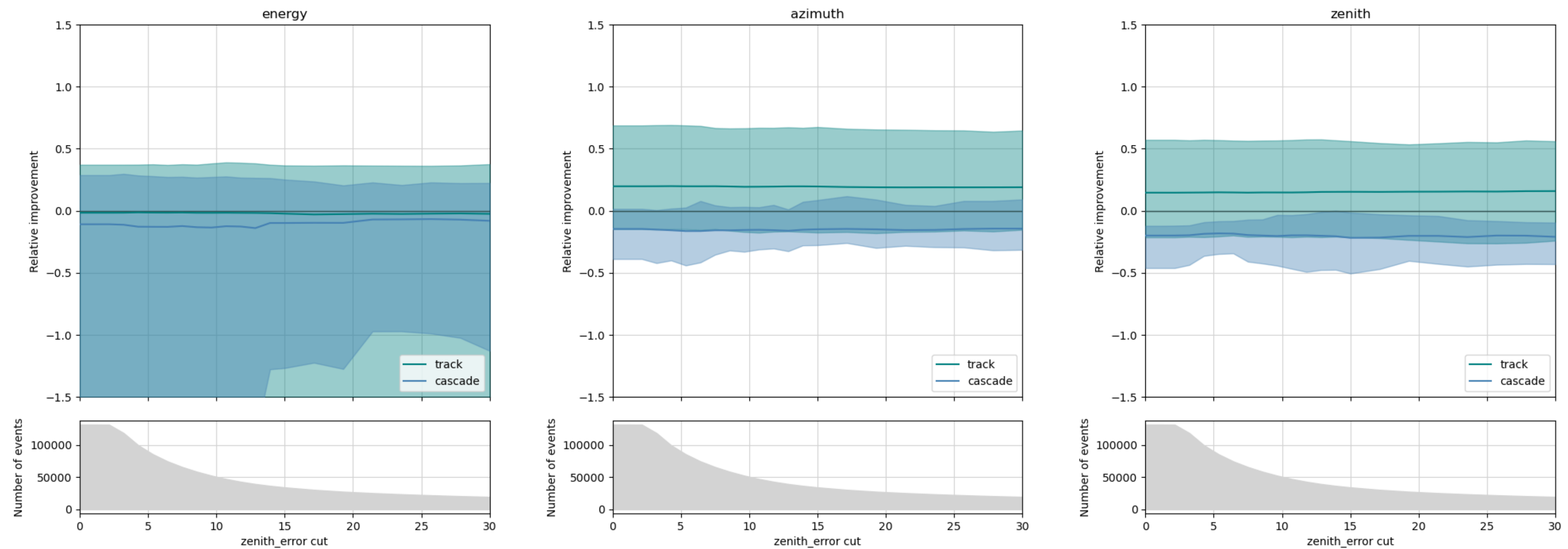
ROC curve



Approach 3: Use number of pulses as a parameter for event selection

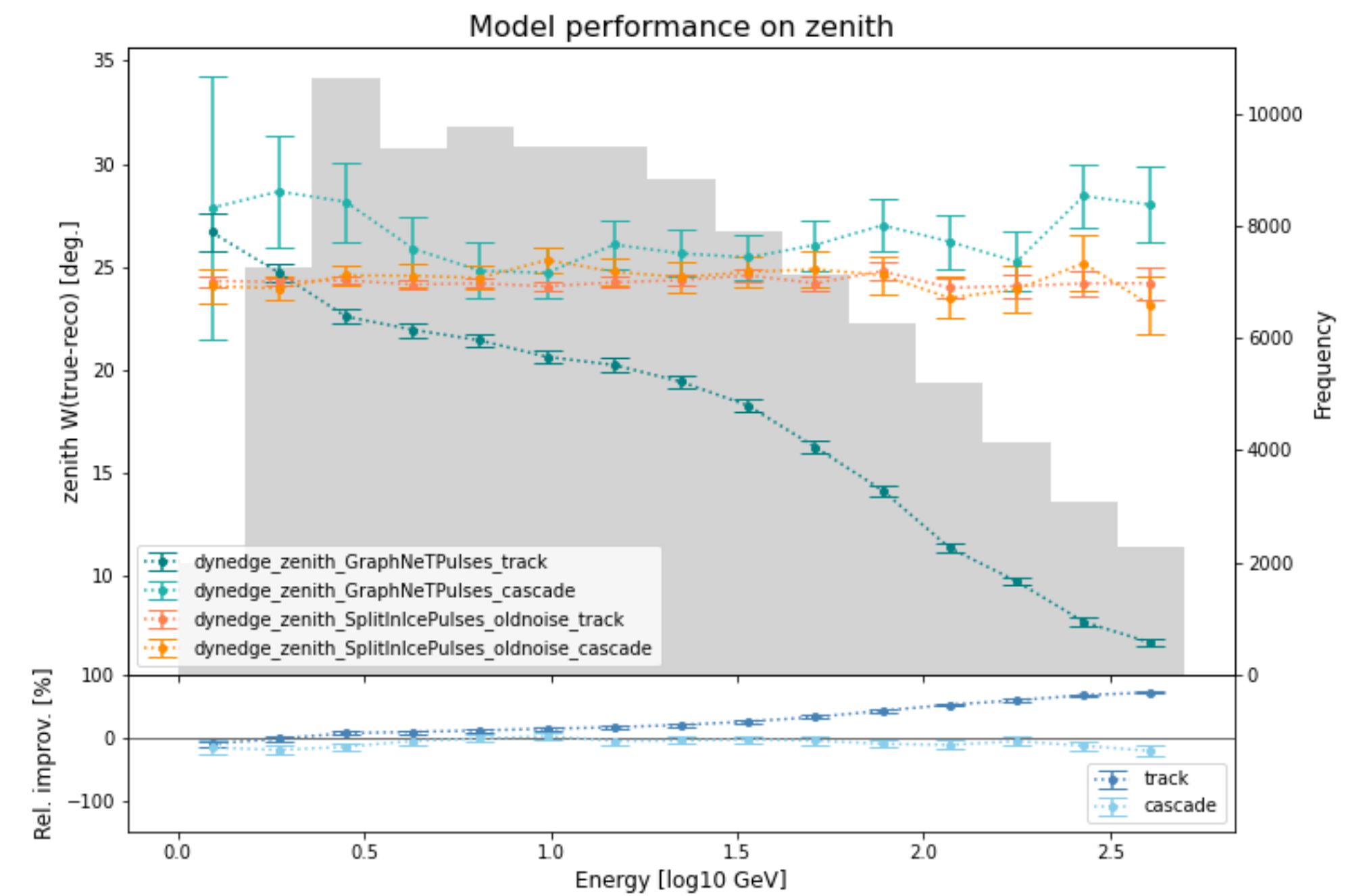
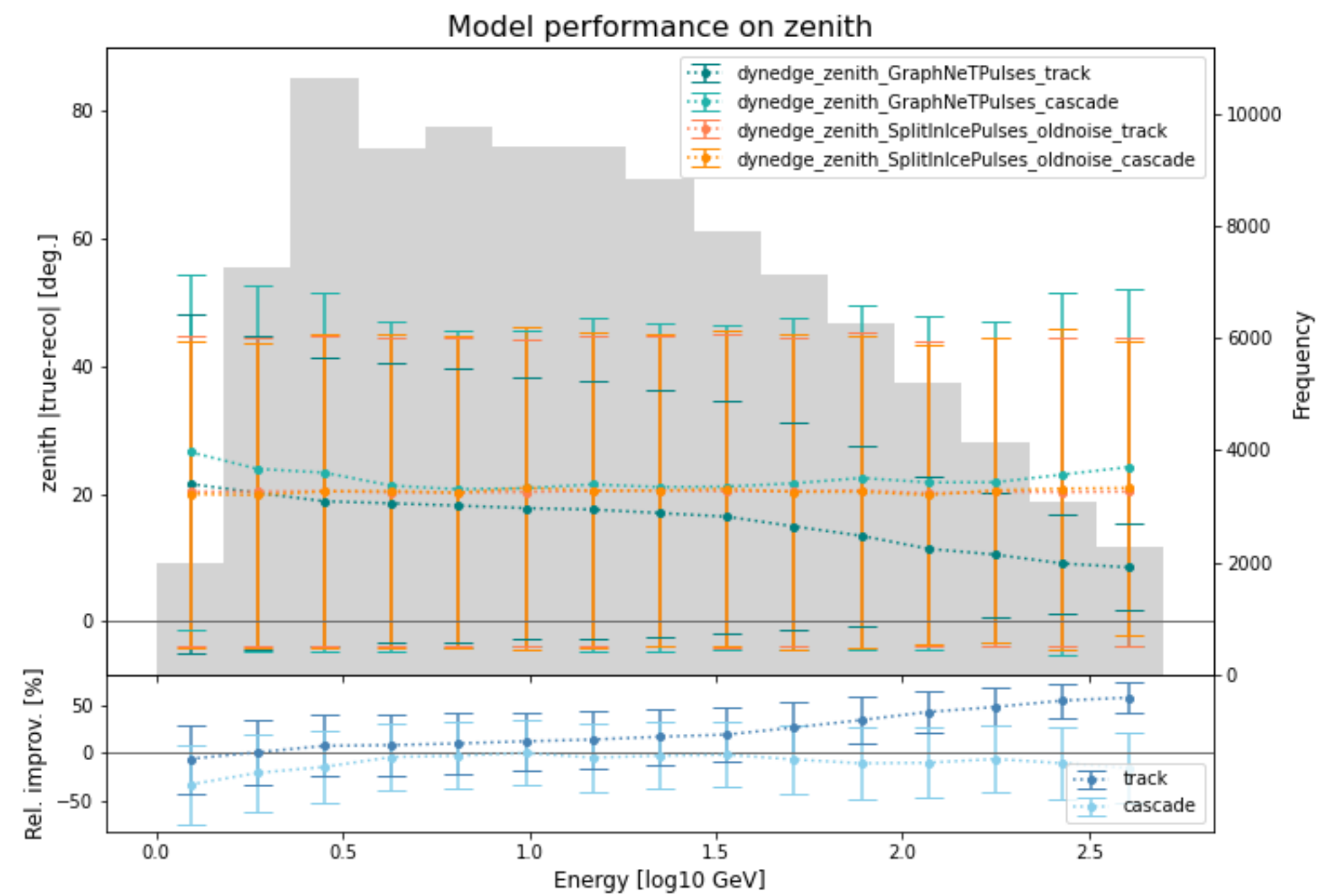


Approach 4: Use zenith kappa estimation as a parameter for event selection



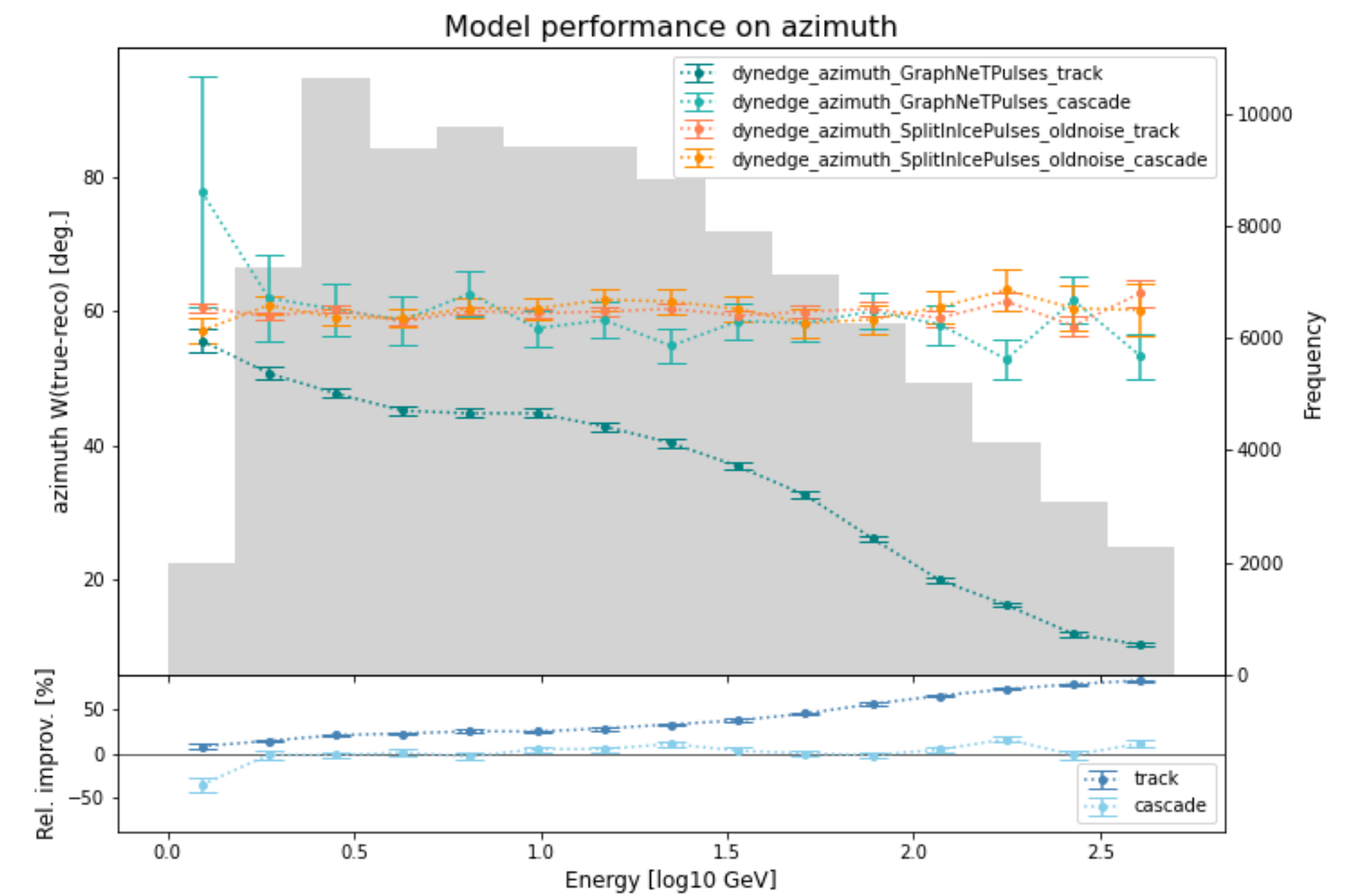
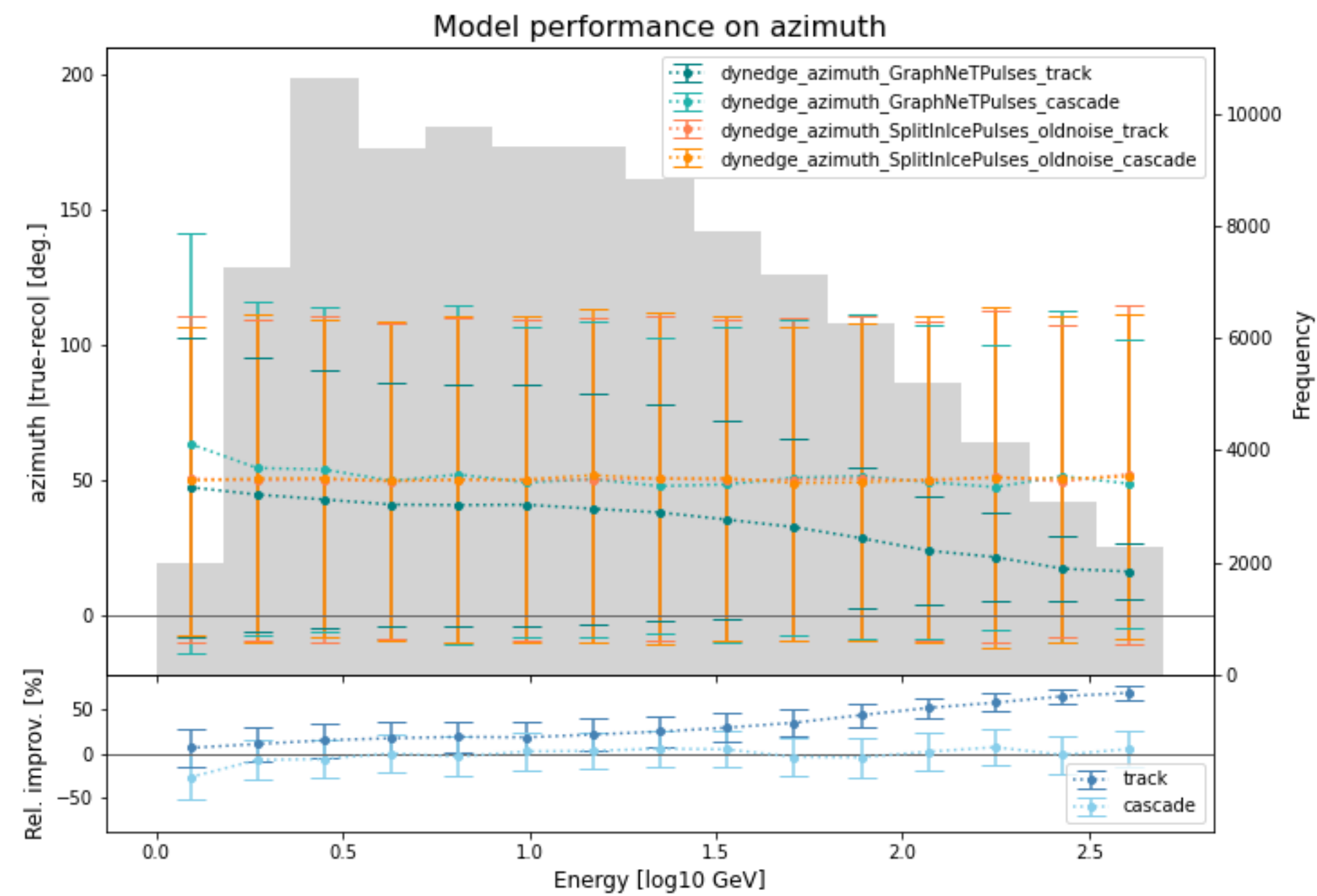
Approach 3: Use number of pulses as a parameter for event selection

Zenith



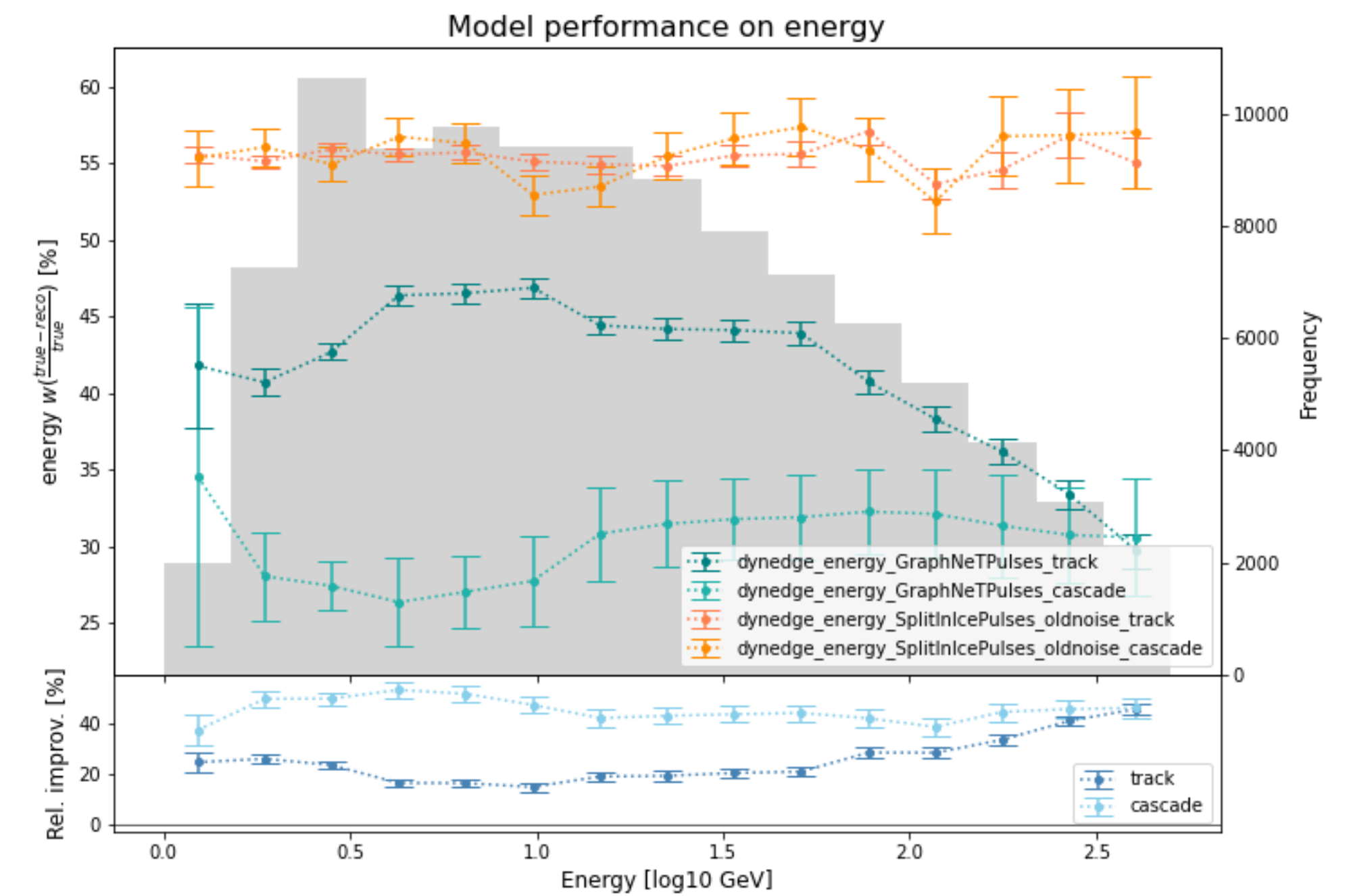
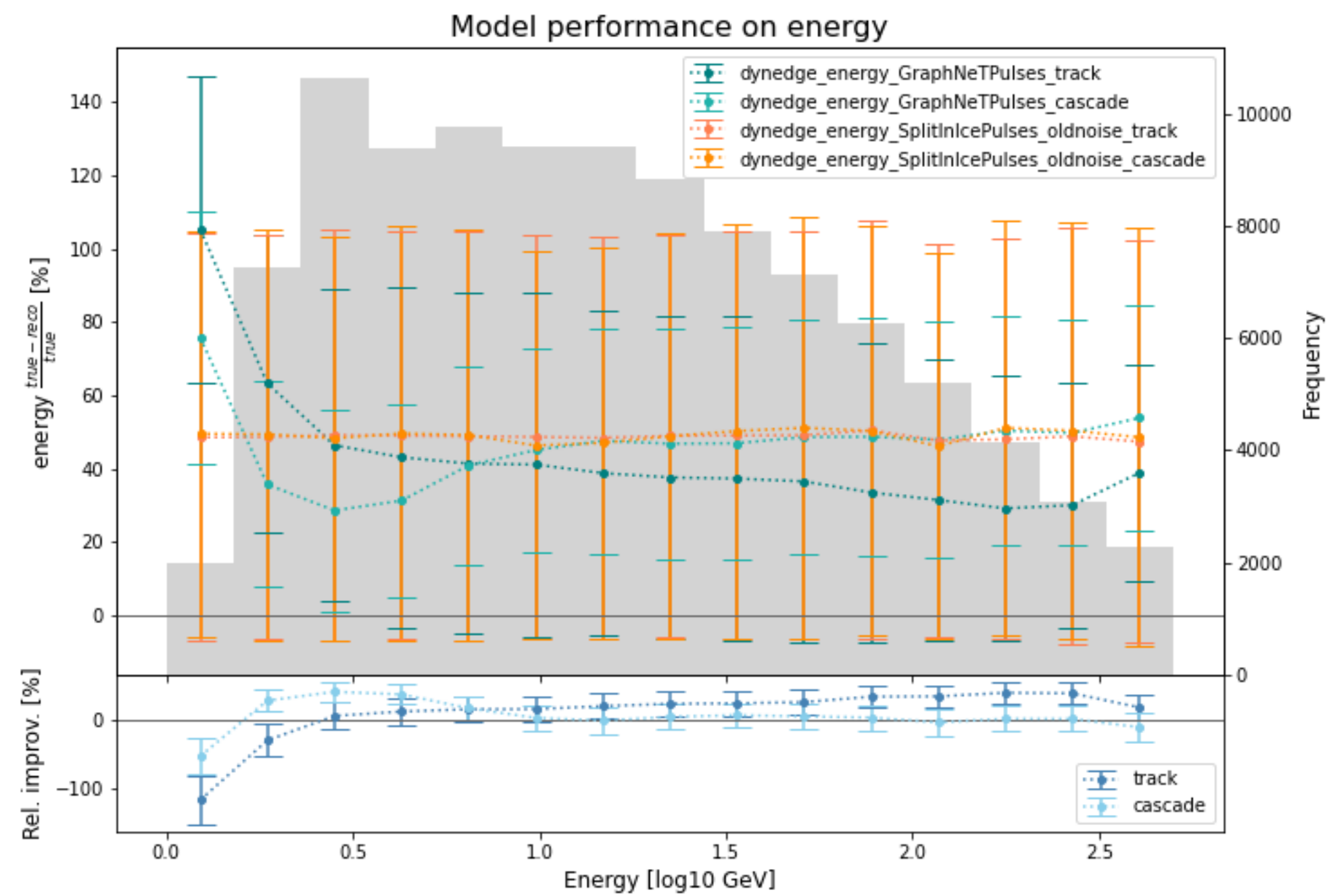
Approach 3: Use number of pulses as a parameter for event selection

Azimuth



Approach 3: Use number of pulses as a parameter for event selection

Energy



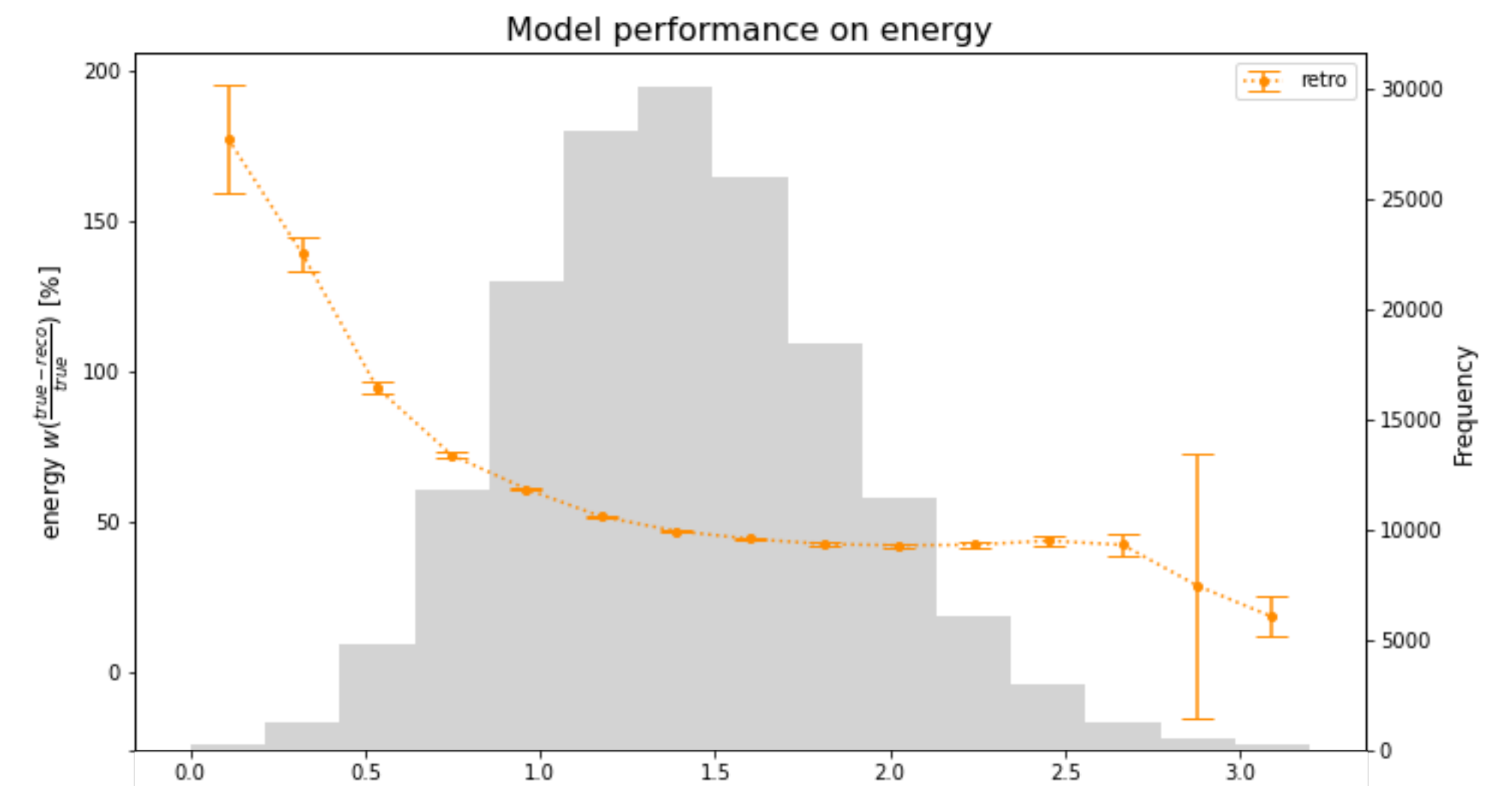
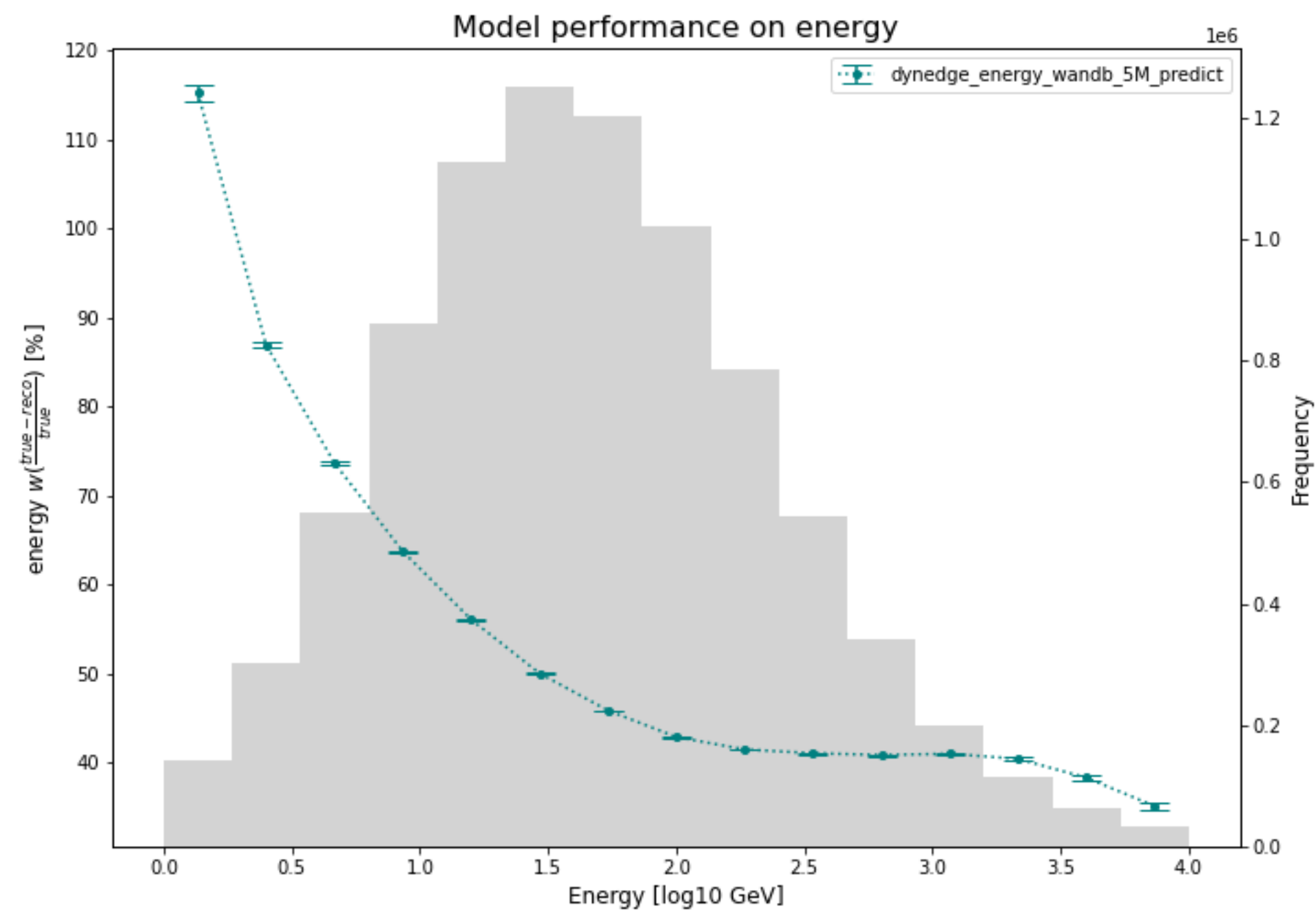
Conclusion:

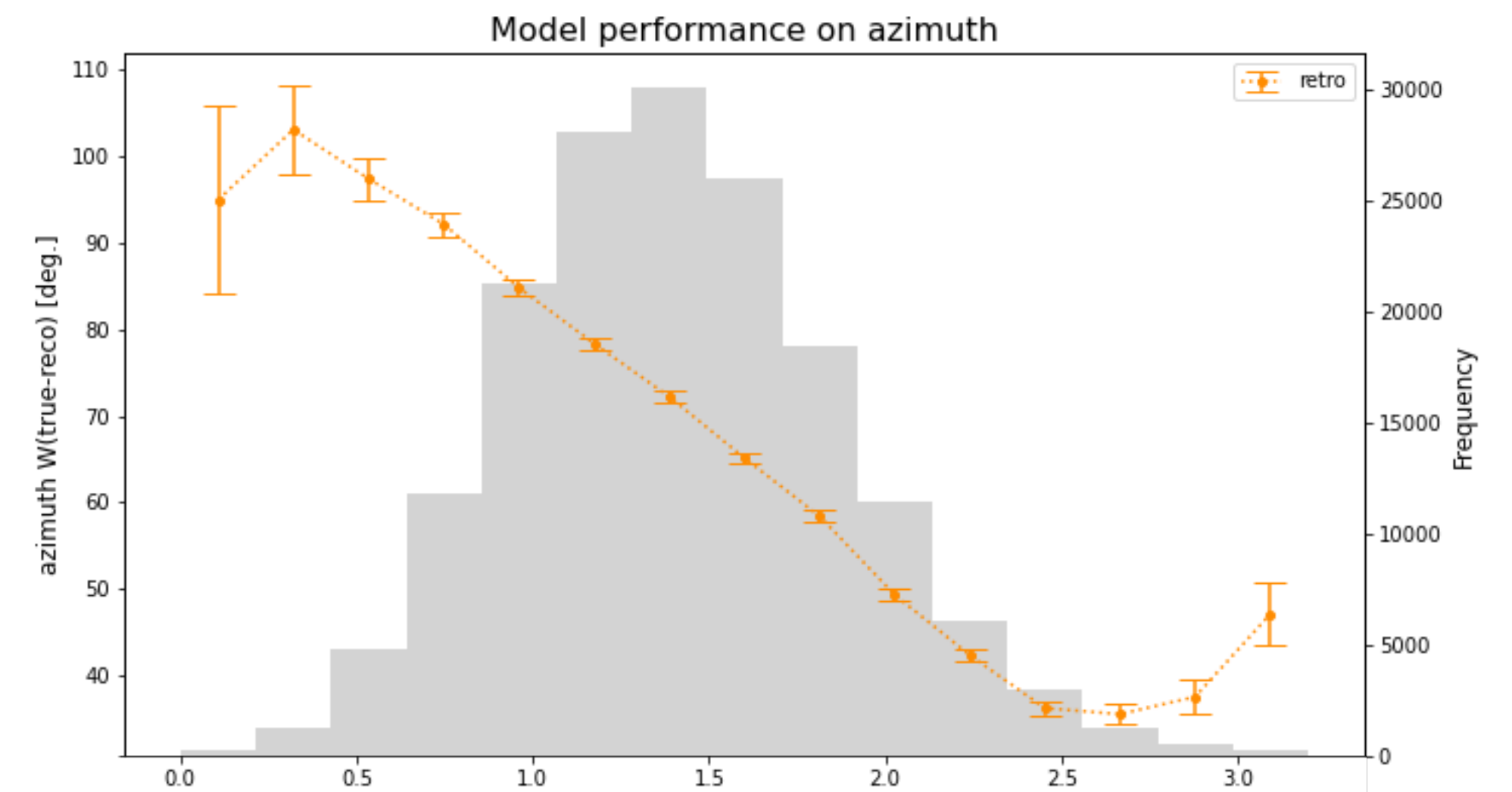
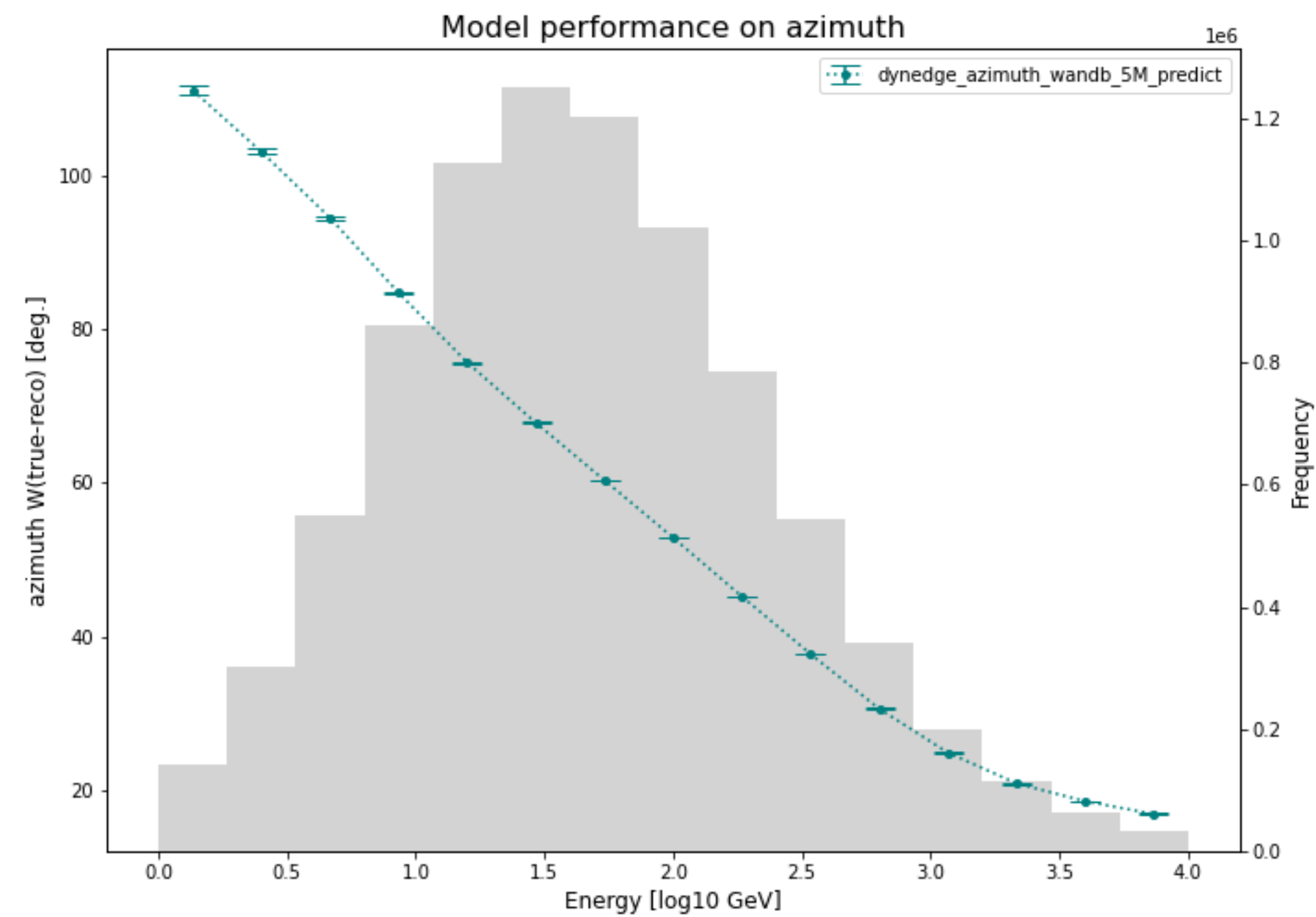
Simple event selection can improve reconstruction performance.

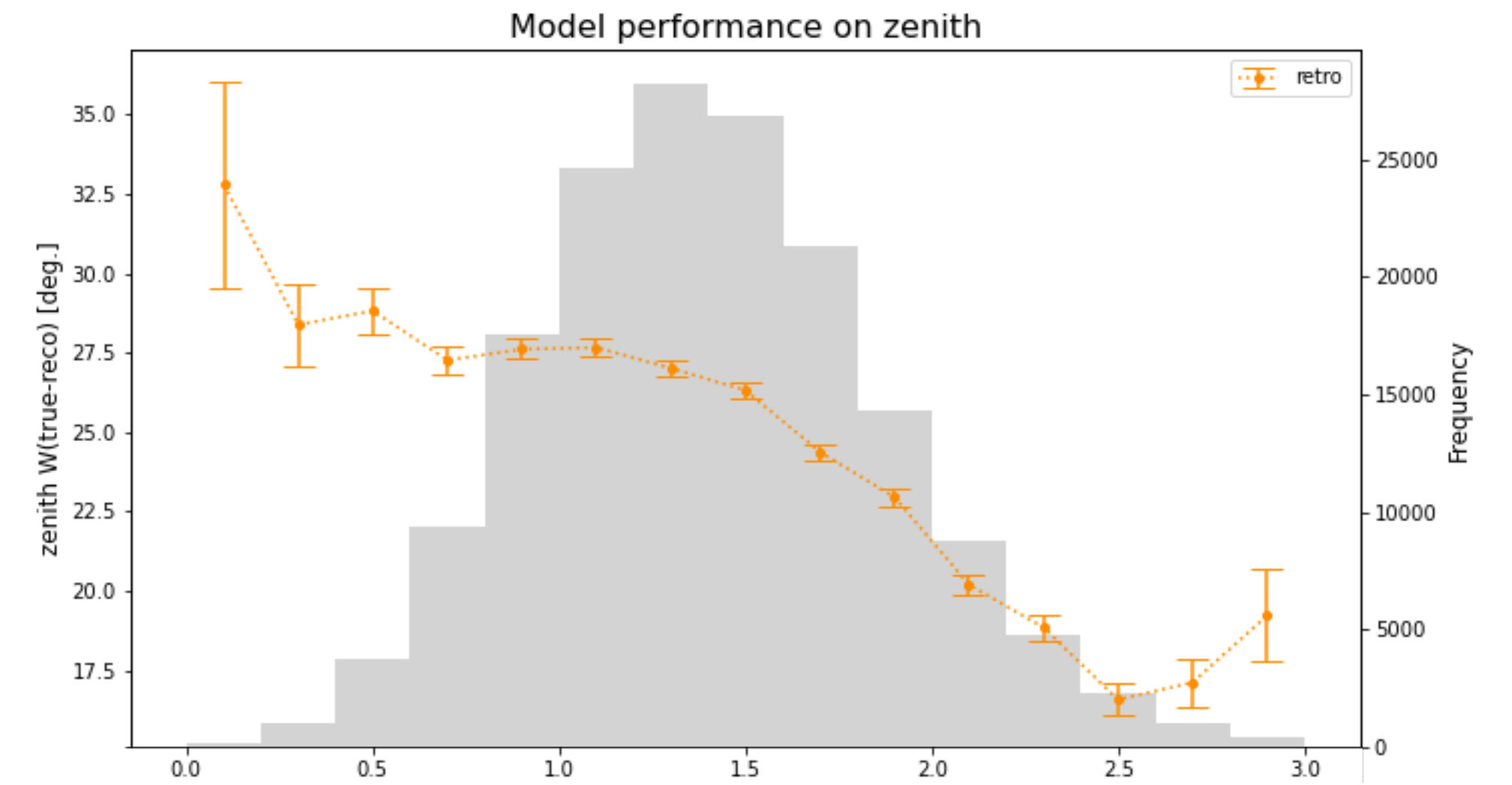
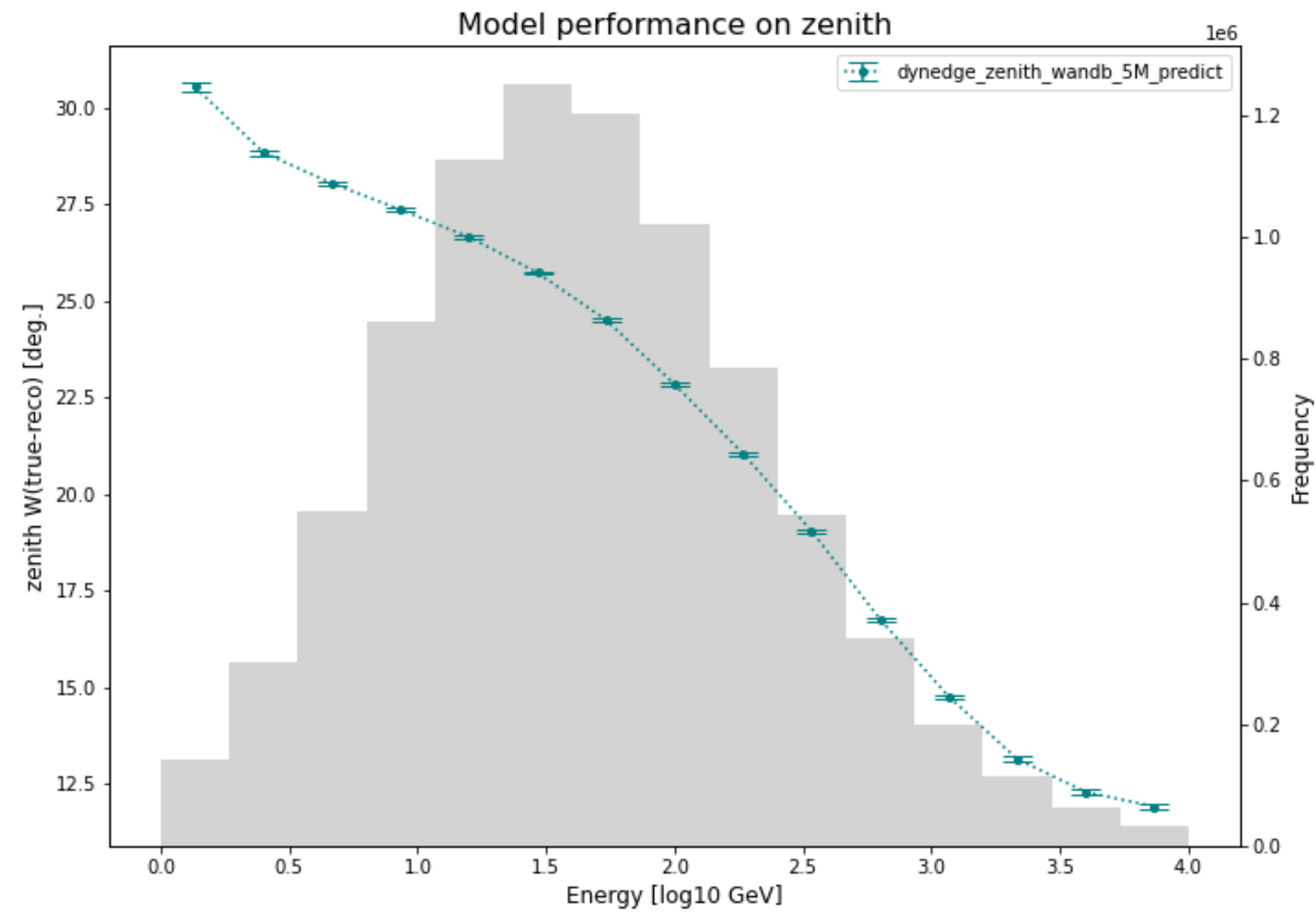
More sophisticated methods like GNNs or current OscNext tools should improve the cleaned events beyond the old noise model.

Intermezzo 2

Quality of Cleaned Events







Introduction

My Work

Conclusions & Outlook

Conclusions

Interaction Time Reconstruction

Non-linear transformation can be beneficial for some regression tasks.

In the case of interaction time, it allows the GNN to outperform retro in the desired energy ranges.

Pulse Cleaning

The more sophisticated GNN is better at cleaning the additional Upgrade noise than the simple (but already good) GNN.

Event Cleaning Pipeline

GNNs allow for higher efficiency and purity rates than the current OscNext cleaning pipeline.

- + The new selection of events are well suited for regression with the GNN

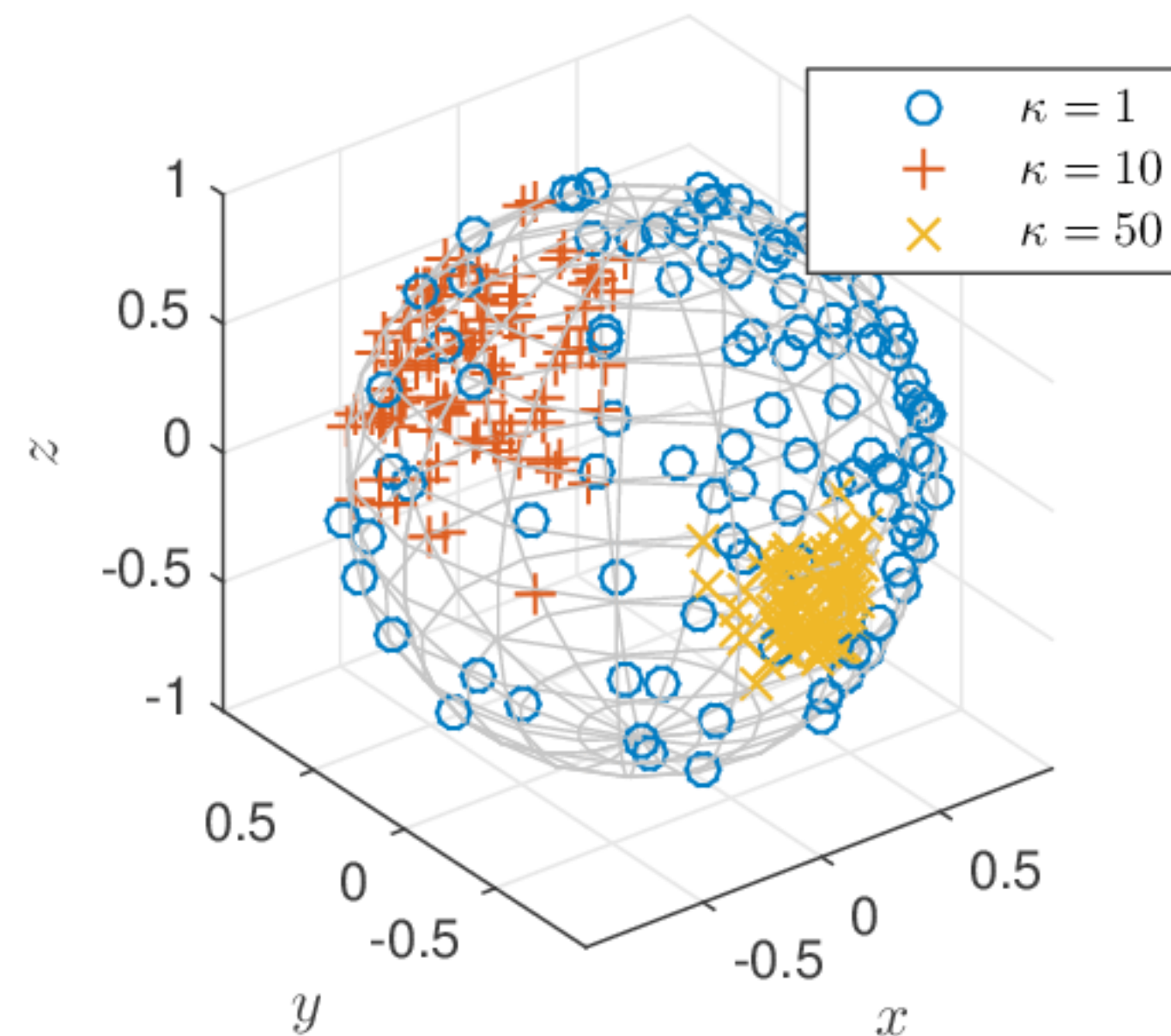
Regression of cleaned pulses

Reconstruction of cleaned pulses nullify the effect of the extra noise in many but not all cases.

- + Applying a simple event selection criterion makes this true in all but a few ranges.

Thank you!





$$p_n(\mathbf{x}|\boldsymbol{\mu}, \kappa) = C_n(\kappa) \exp(\kappa \boldsymbol{\mu}^T \mathbf{x})$$

$$\mathcal{L} = -\log p_n(\mathbf{x}|\boldsymbol{\mu}, \kappa) = -\log(\kappa) + \log(2\pi) + \log(I_0(\kappa))$$