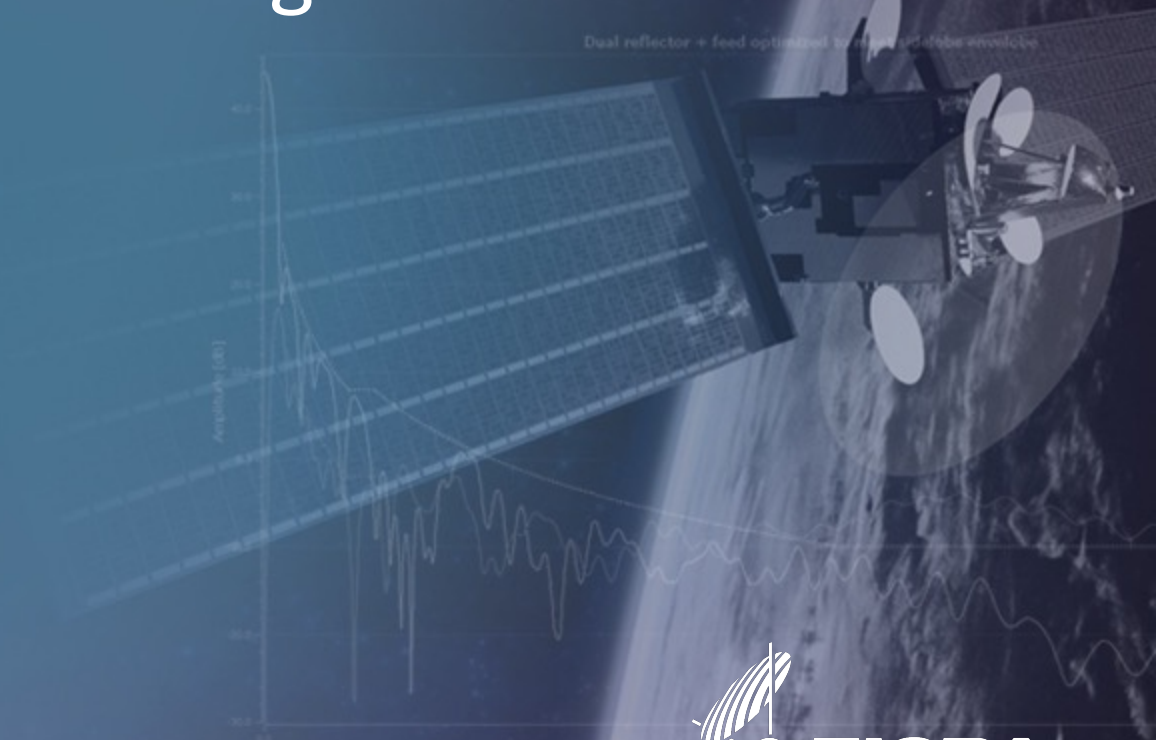


$$\hat{\mathbf{n}} \times \mathbf{E}^i = \hat{\mathbf{n}} \times L_0 \mathbf{J}_s, \quad \mathbf{r} \in S.$$

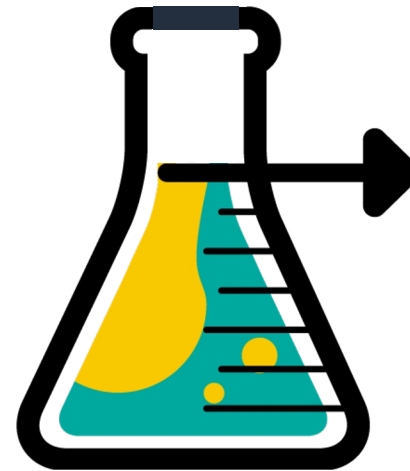
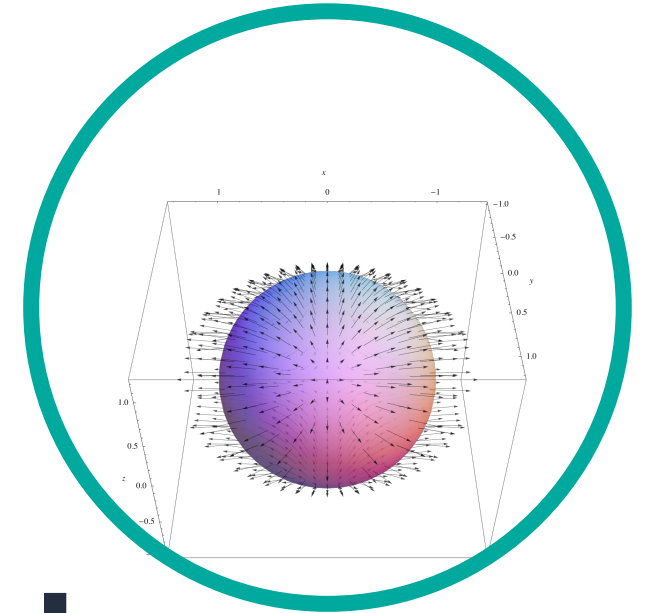
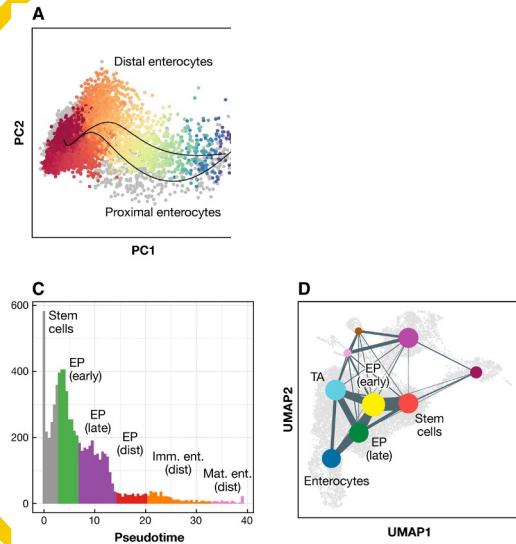
Scientific Machine Learning

Christian Buus Michelsen @ TICRA

2025/06/04



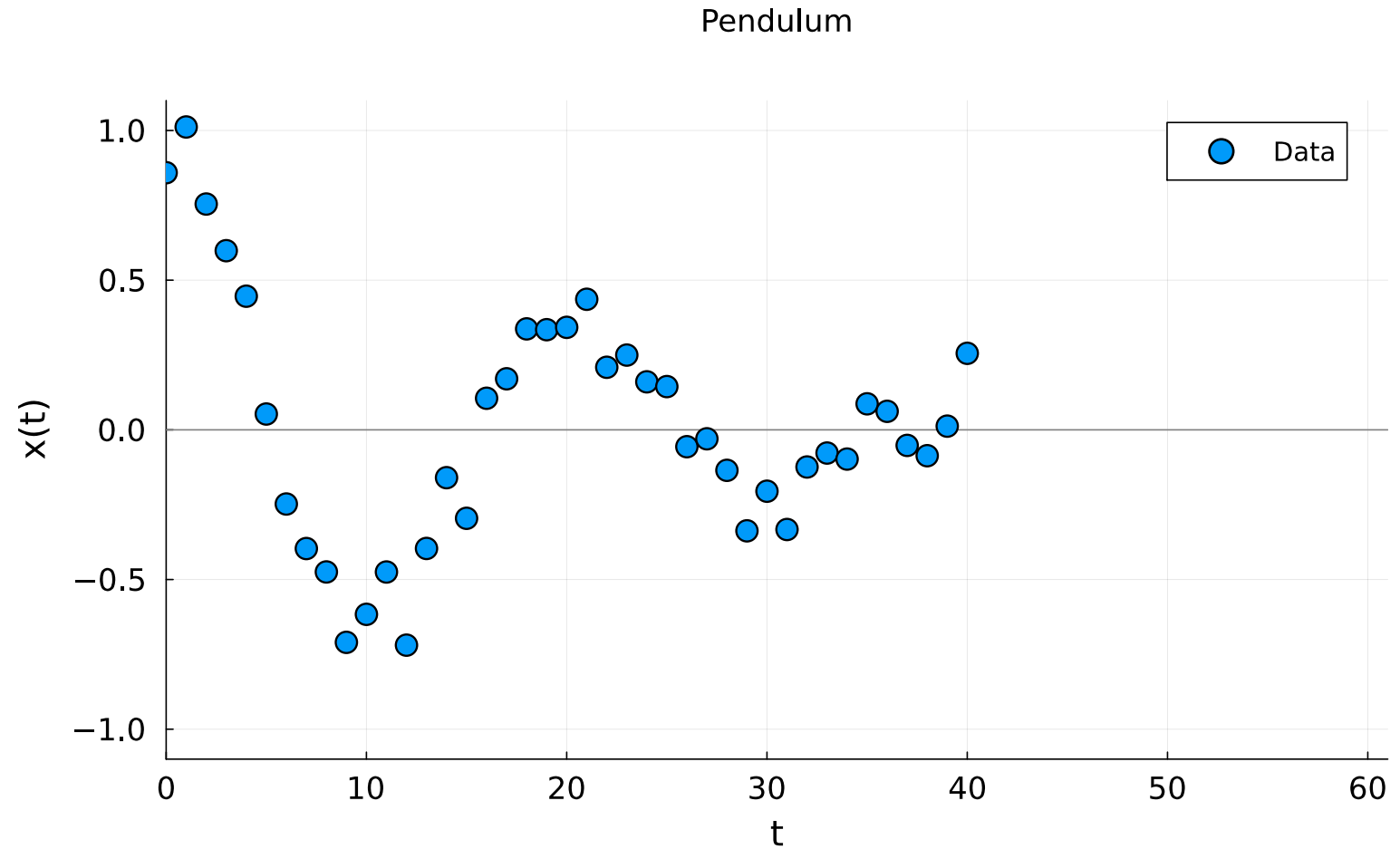
SciML: model-based, data-efficient machine learning



**Good
Predictions**

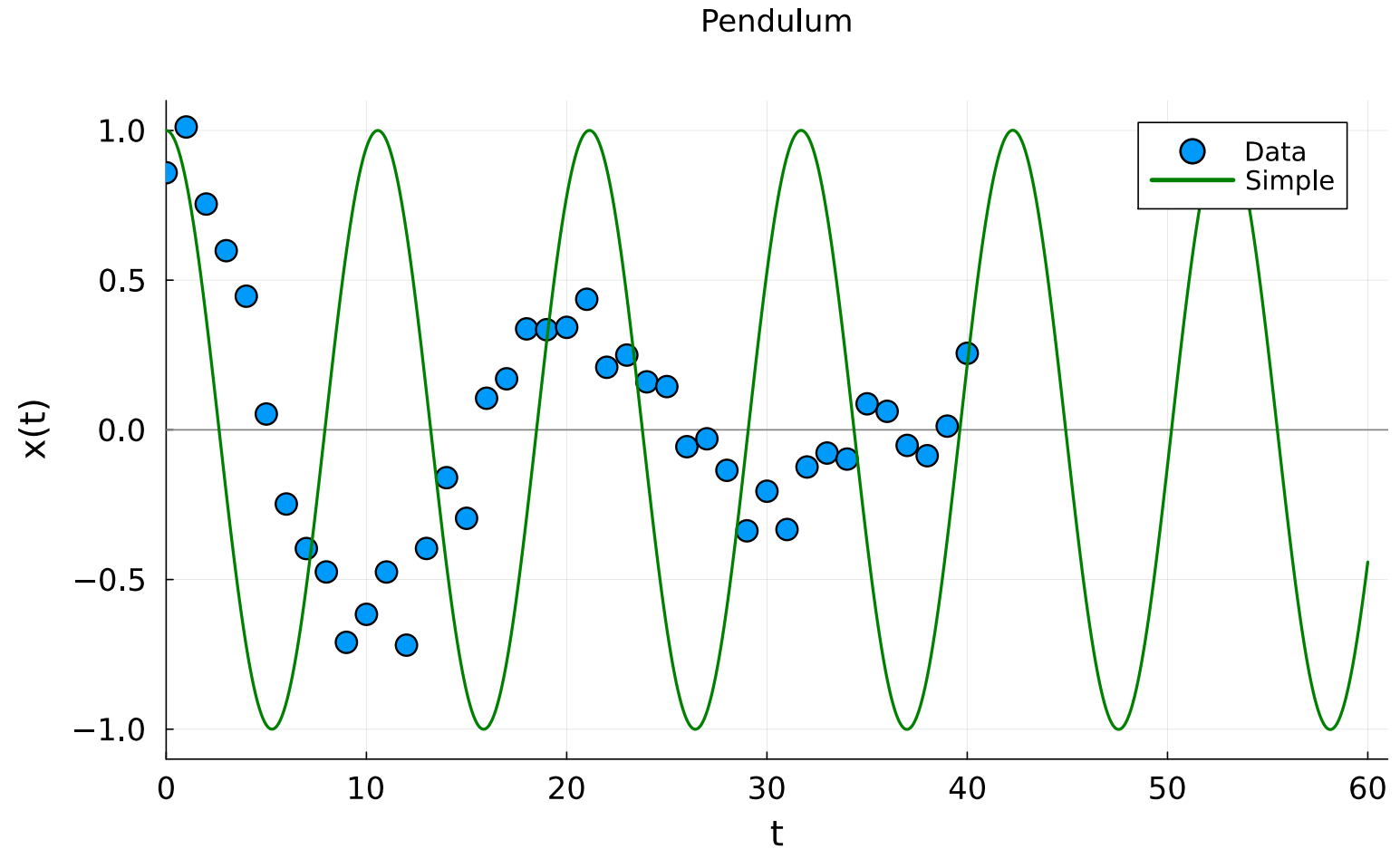
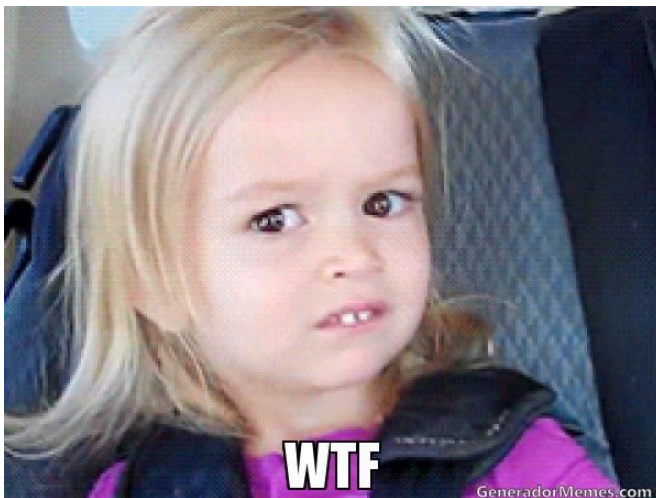
Simple Harmonic Oscillator

$$m\ddot{x} + kx = 0$$



Simple Harmonic Oscillator?

$$m\ddot{x} + kx = 0$$

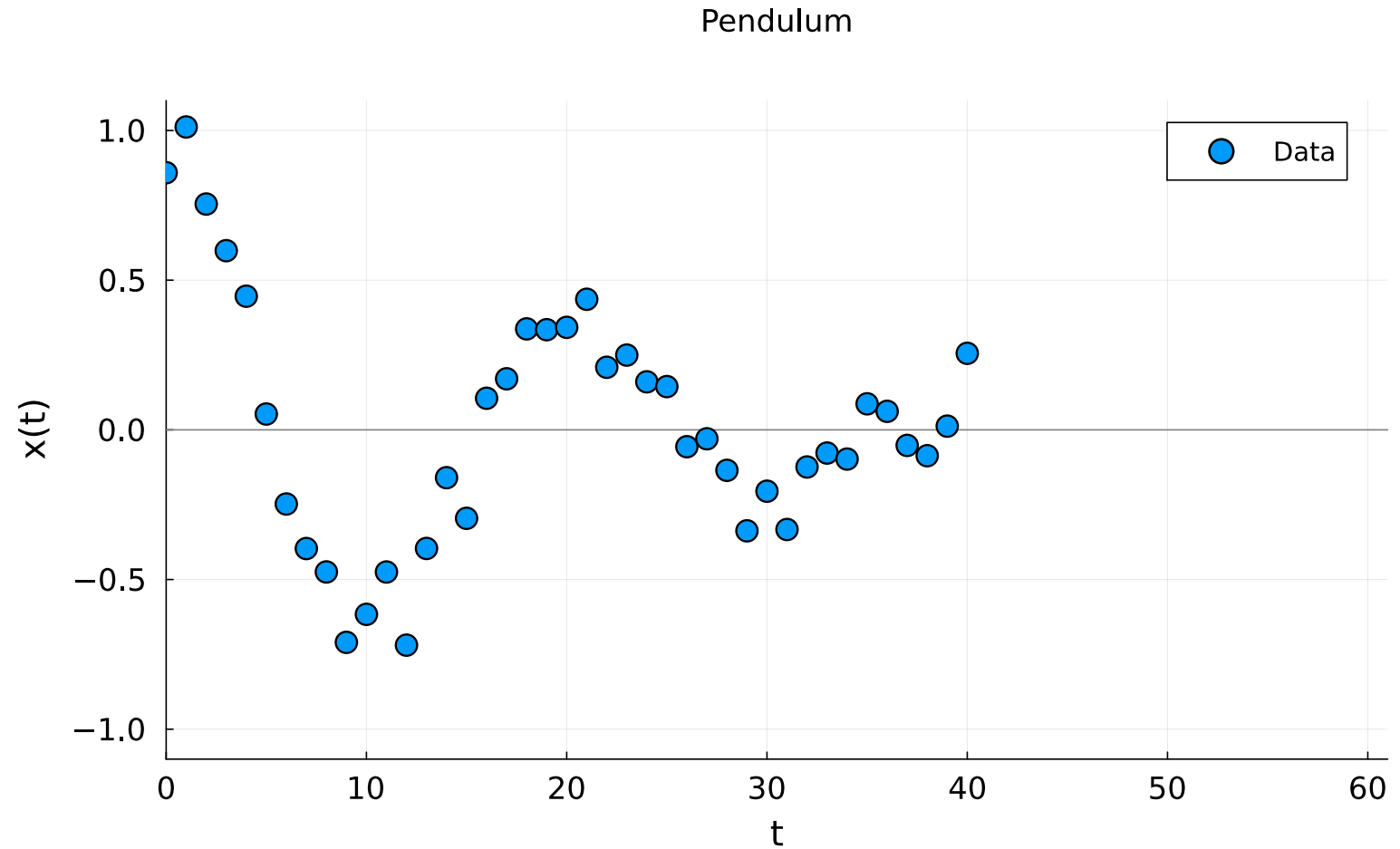


Neural networks

NN = Universal approximators

(Universal Approximation Theorem, G. Cybenko 1989)

$$x(t) = NN(t)$$

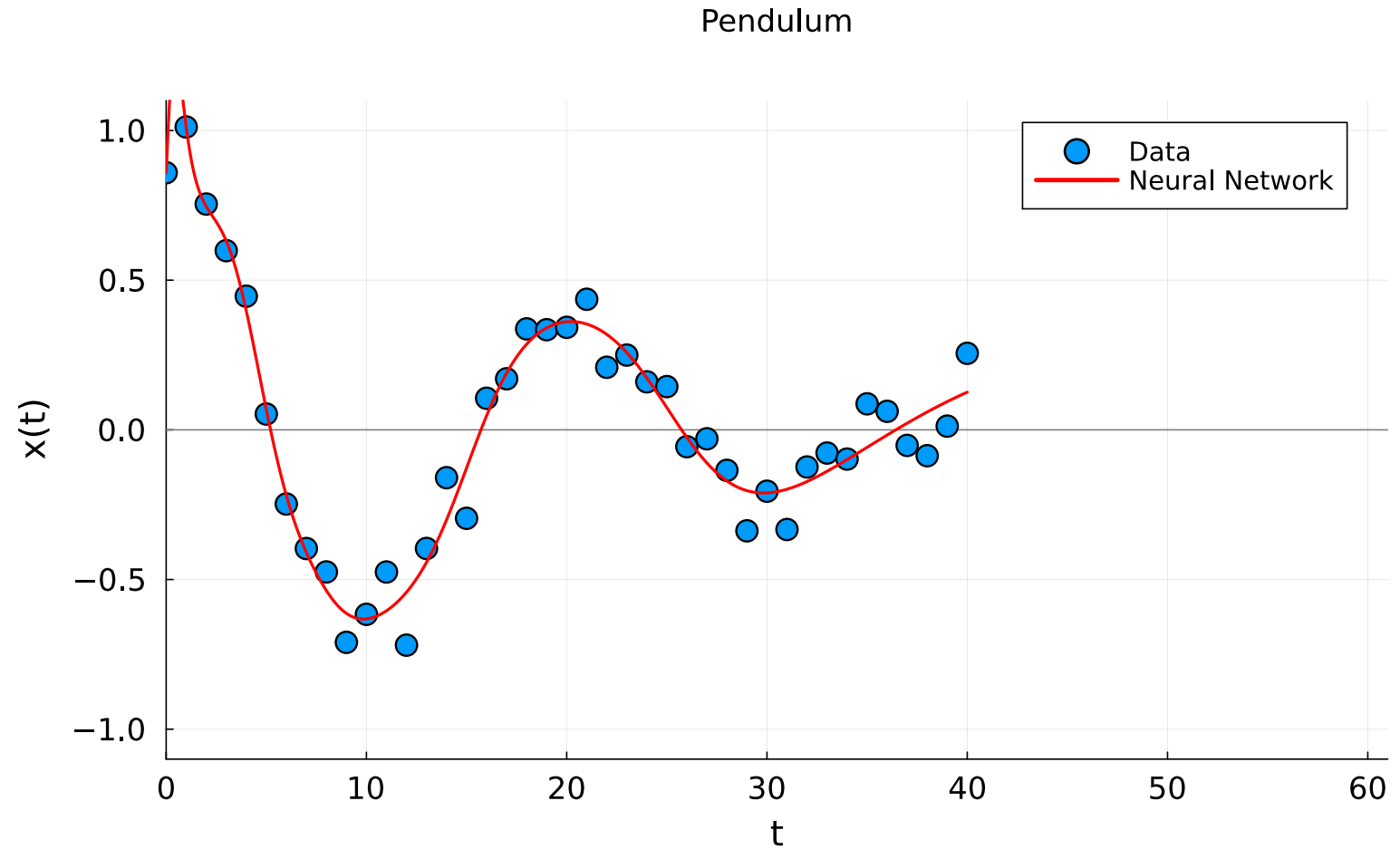


Neural networks

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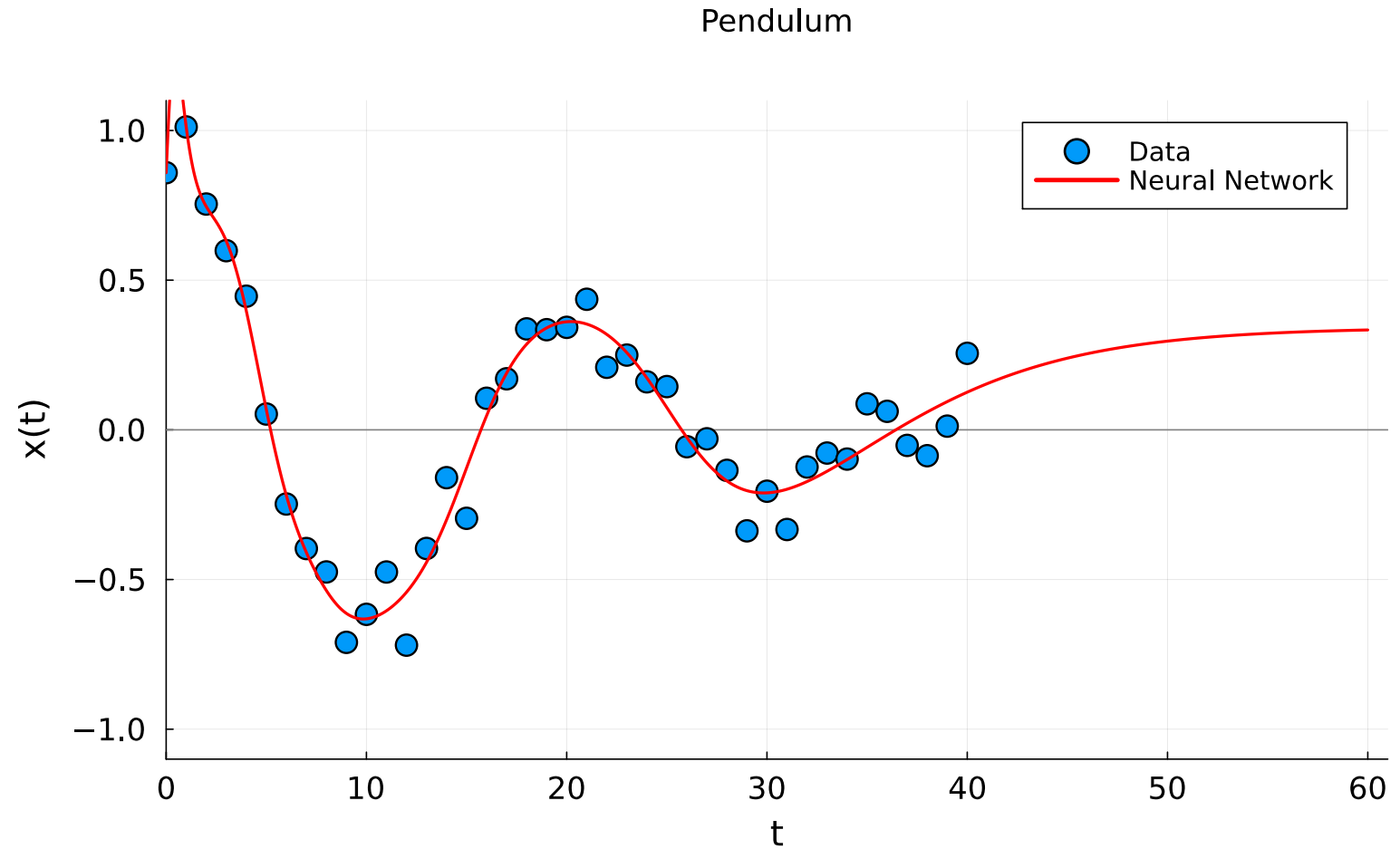


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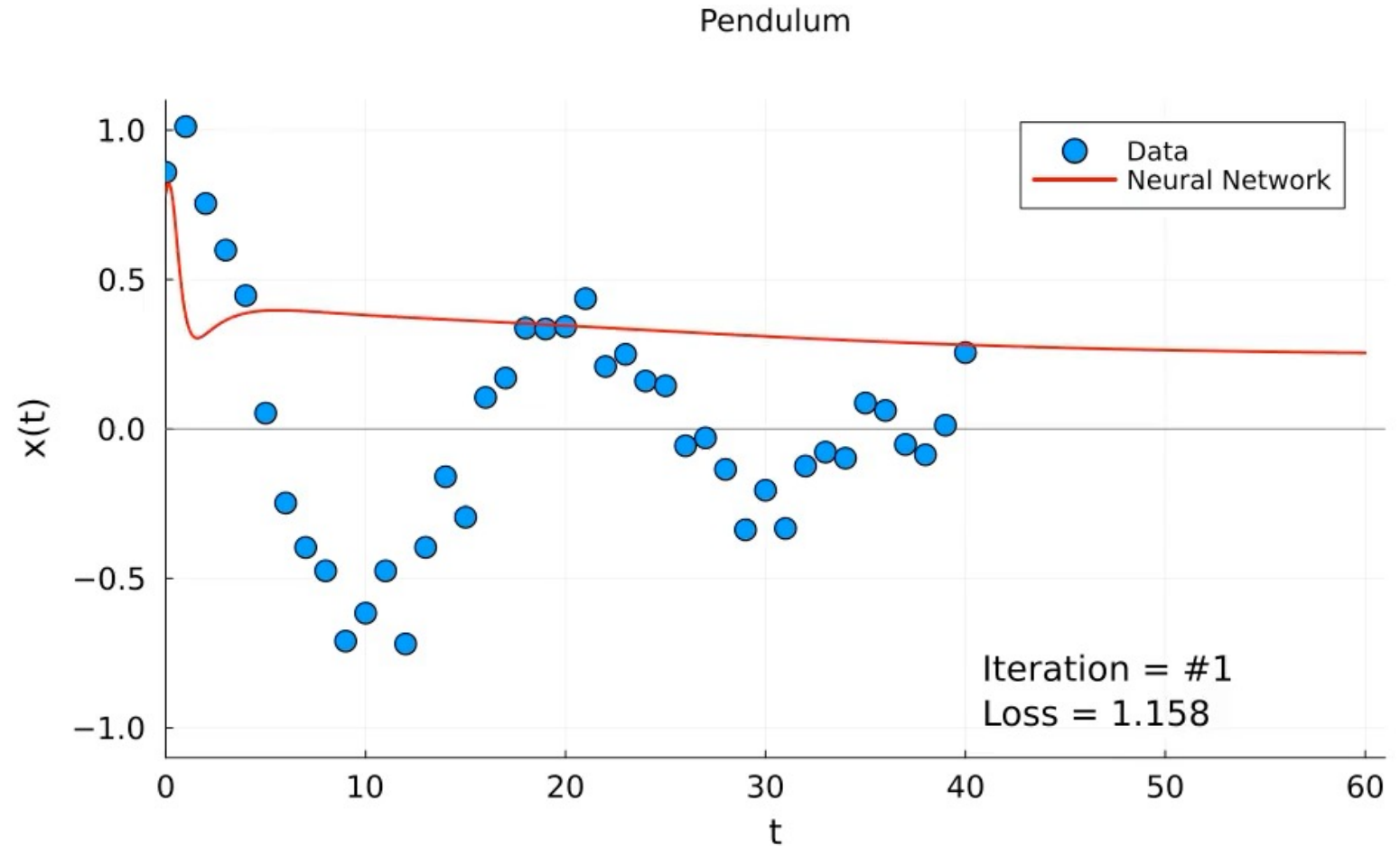


Neural networks

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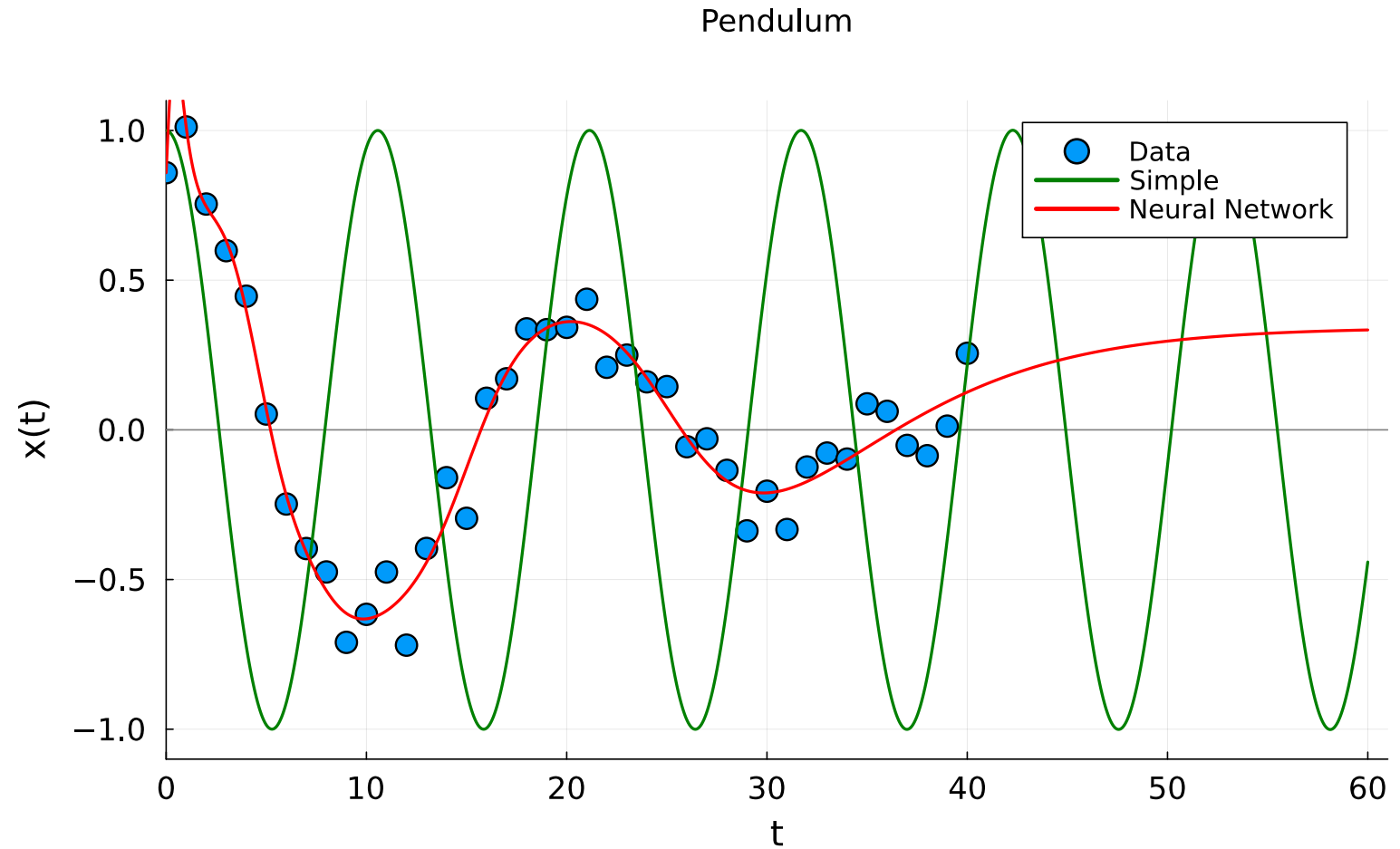


Neural networks

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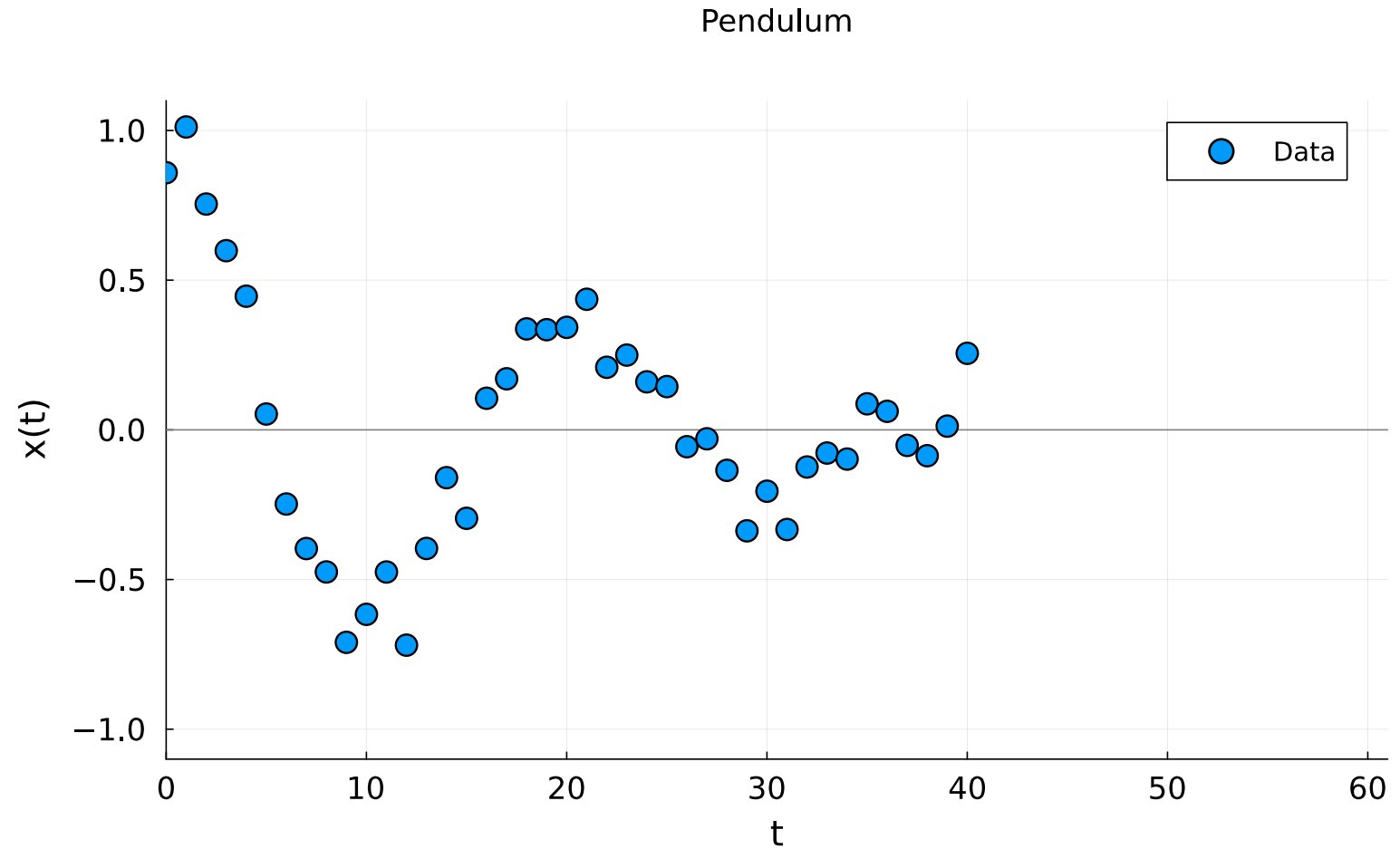
Harmonic Oscillator?

2nd order ODE → 1st order system:

$$\dot{x} = v$$

$$\dot{v} = -\frac{kx}{m}$$

$$m\ddot{x} + kx = 0$$



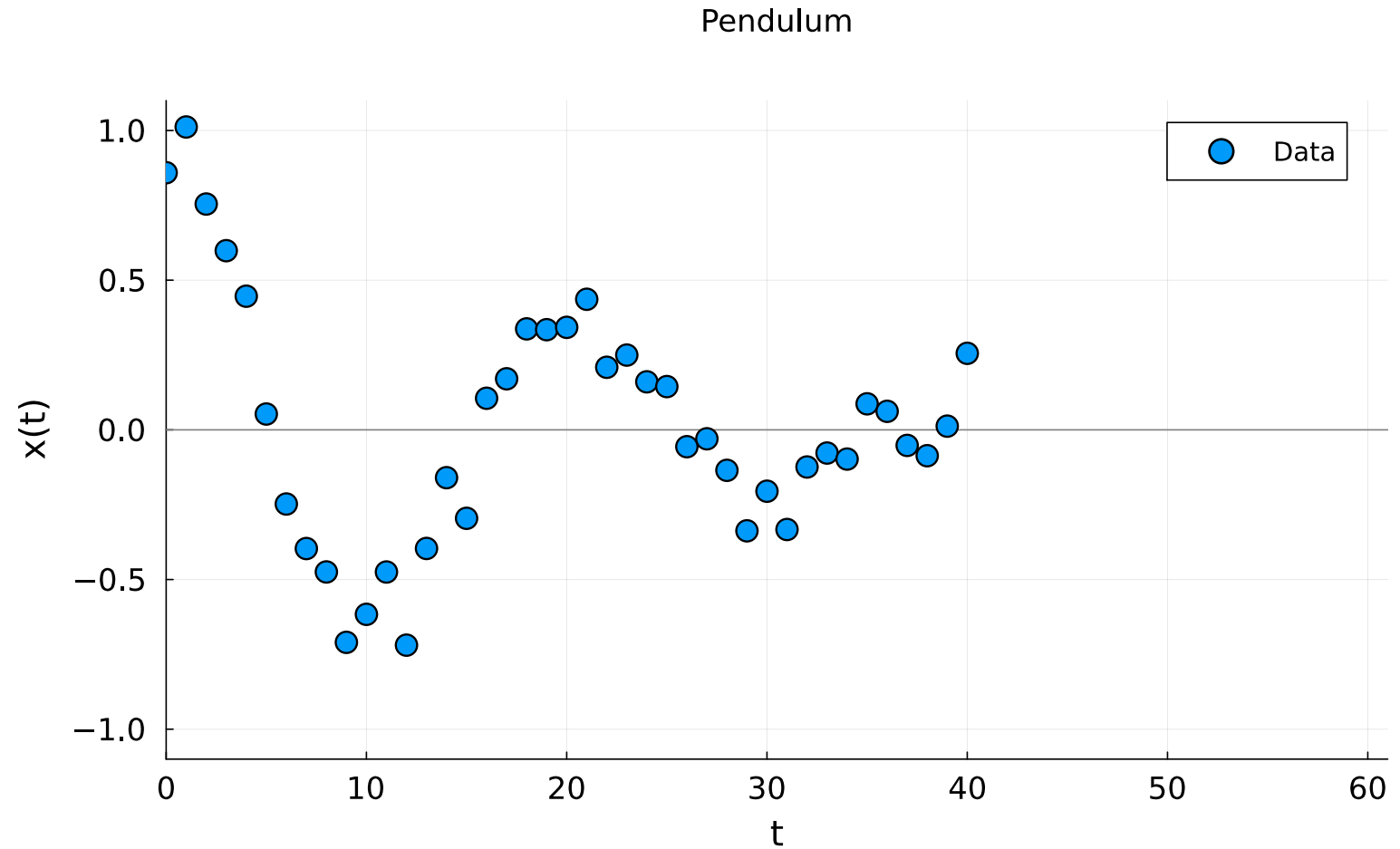
Harmonic Oscillator?

2nd order ODE → 1st order system:

$$\dot{x} = v$$

$$\dot{v} = -\frac{kx + NN(v)}{m}$$

$$m\ddot{x} + kx = 0$$



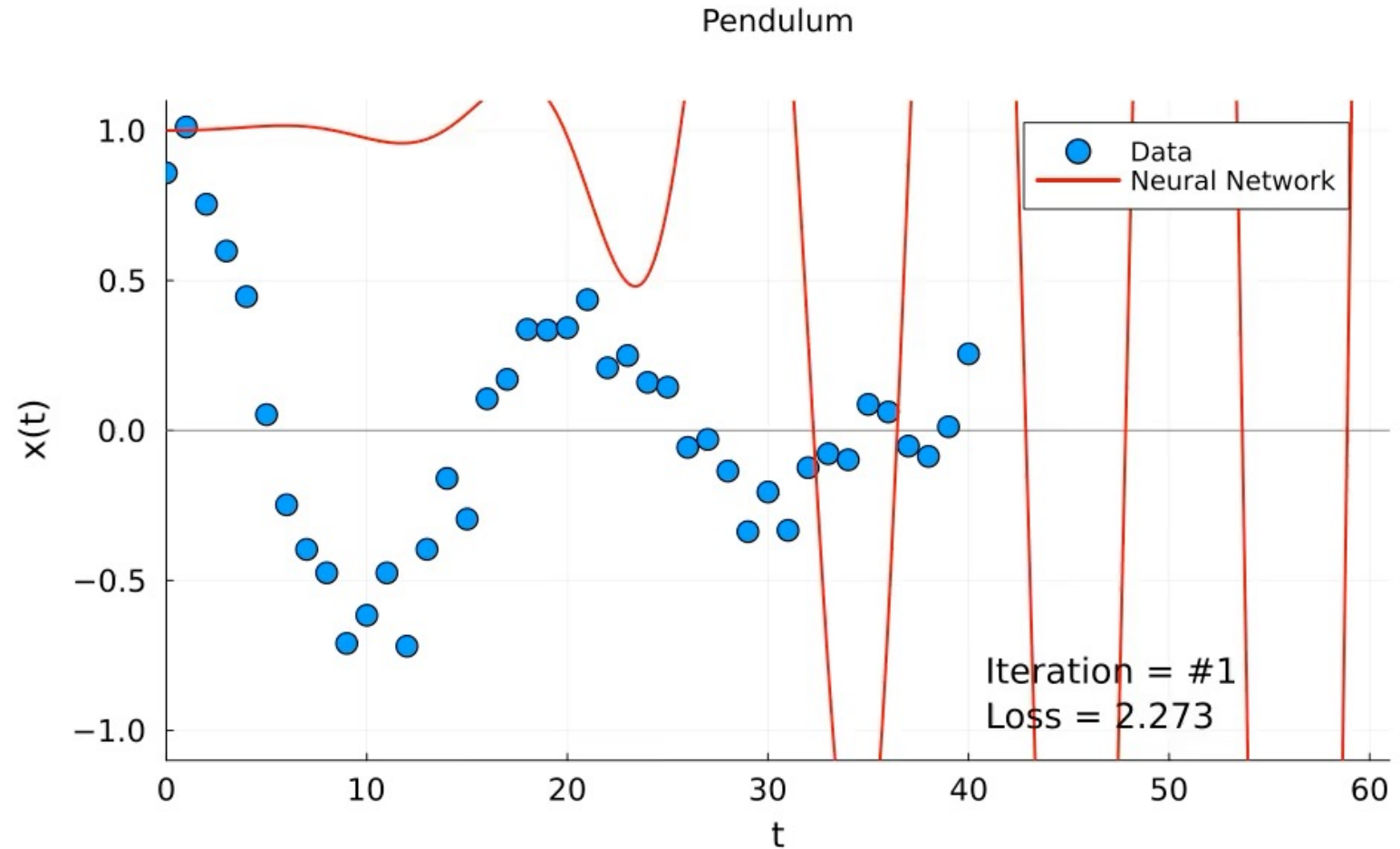
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Harmonic Oscillator?

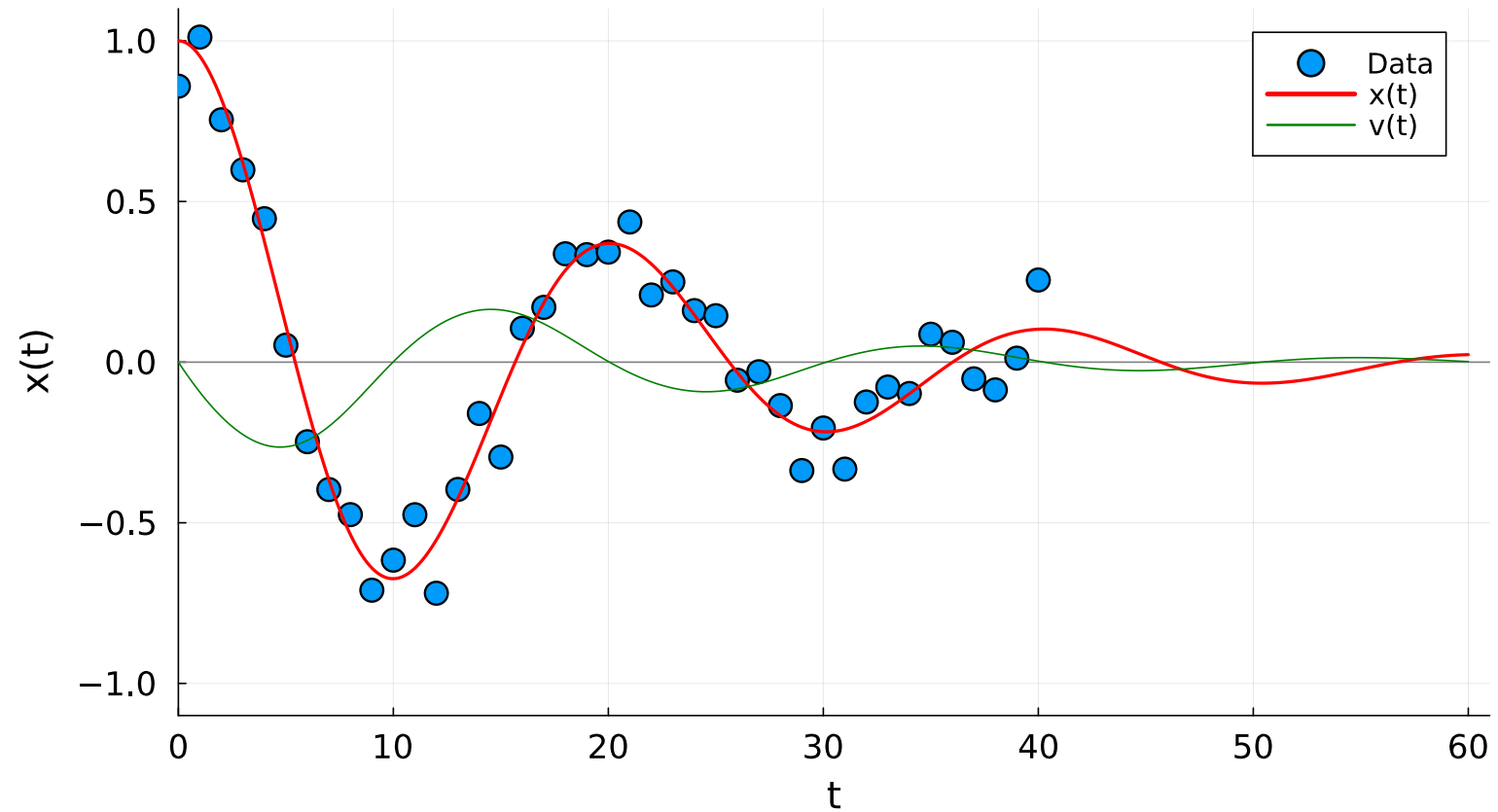
2nd order ODE → 1st order system:

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$$m\ddot{x} + kx = 0$$

Pendulum



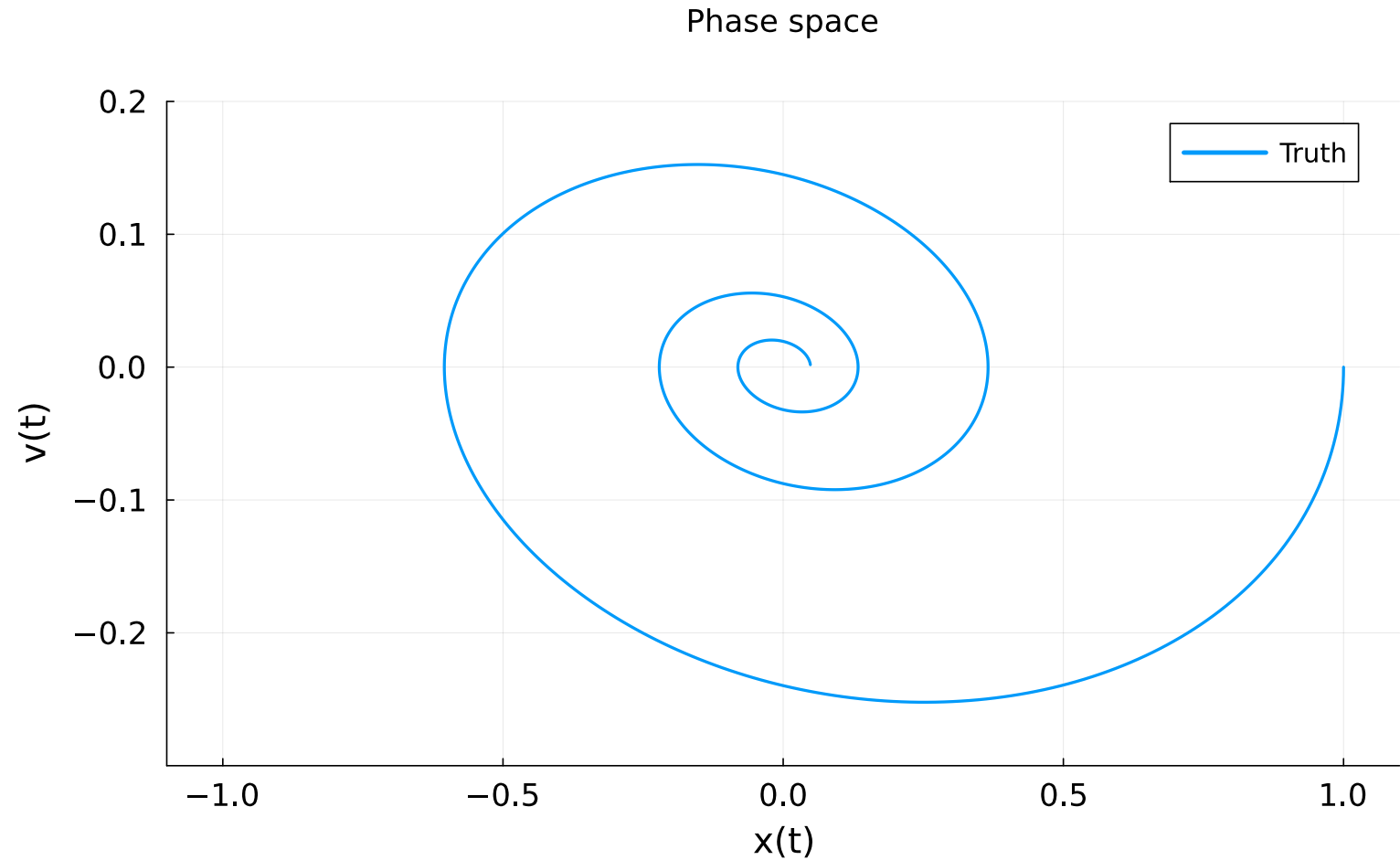
Harmonic Oscillator?

2nd order ODE → 1st order system:

$$\dot{x} = v$$

$$\dot{v} = -\frac{kx + NN(v)}{m}$$

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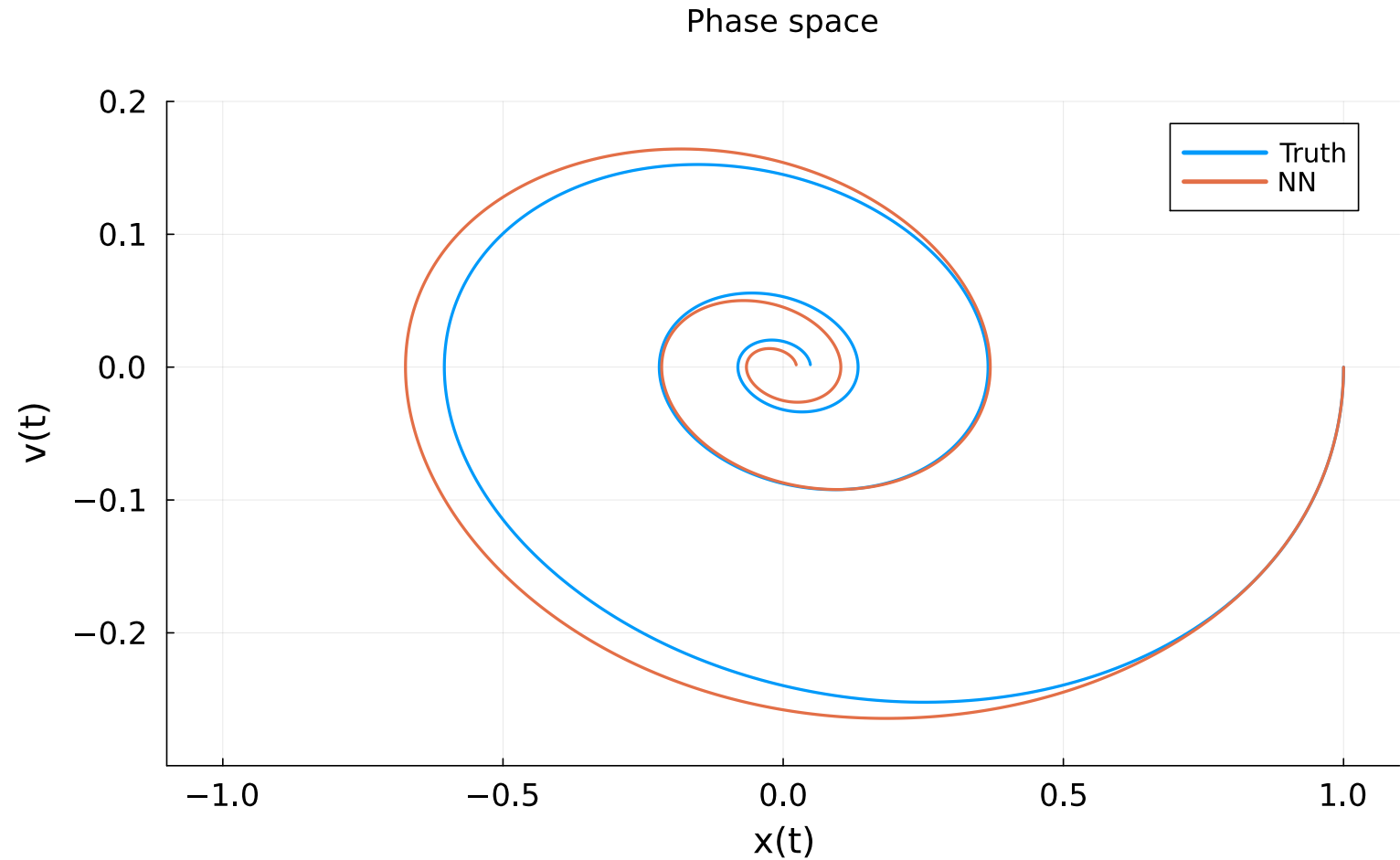
Harmonic Oscillator?

2nd order ODE → 1st order system:

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Harmonic Oscillator?

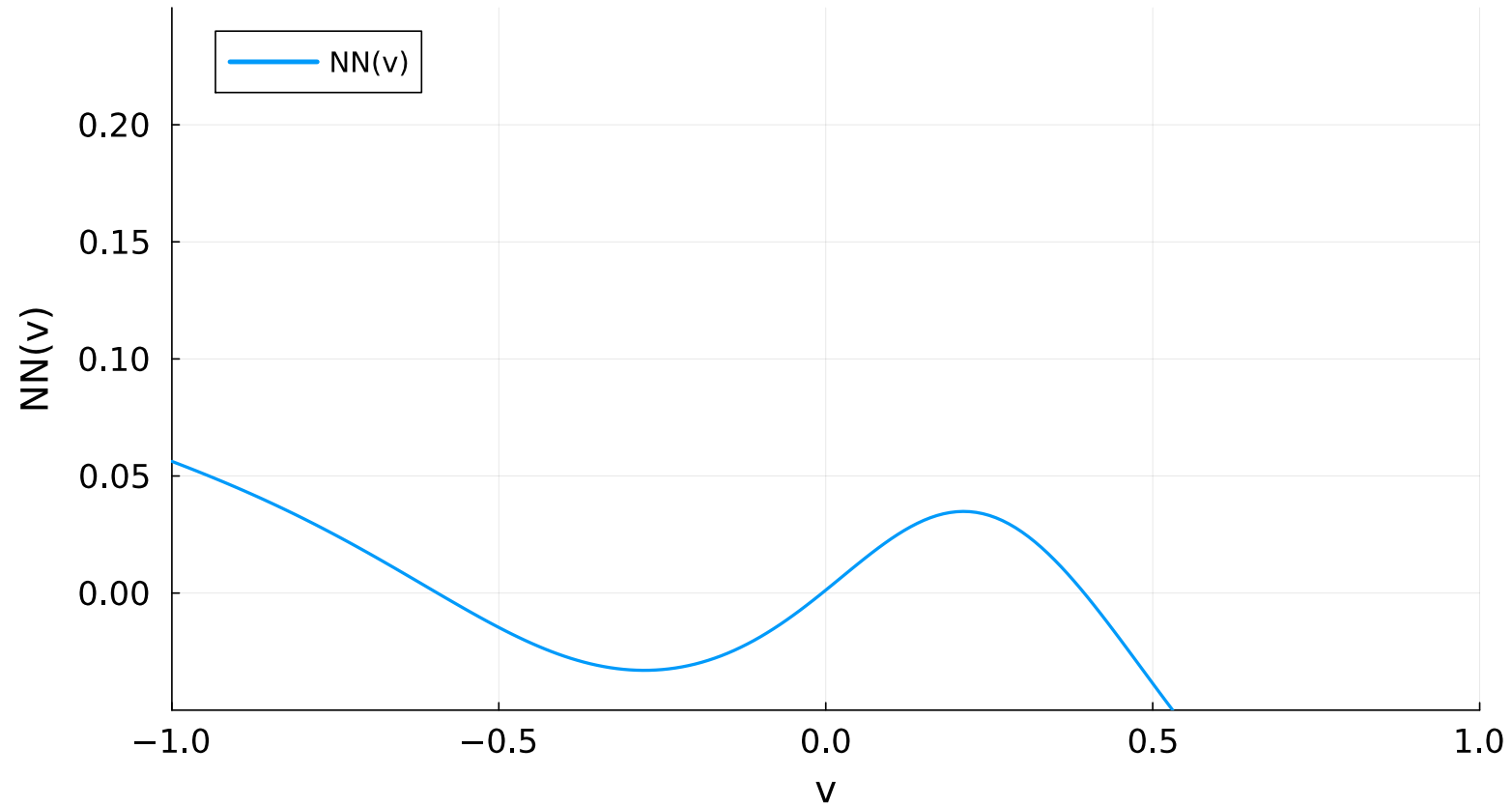
2nd order ODE → 1st order system:

$$\dot{x} = v$$

$$\dot{v} = -\frac{kx + NN(v)}{m}$$

$$m\ddot{x} + kx = 0$$

Learnt representation of v



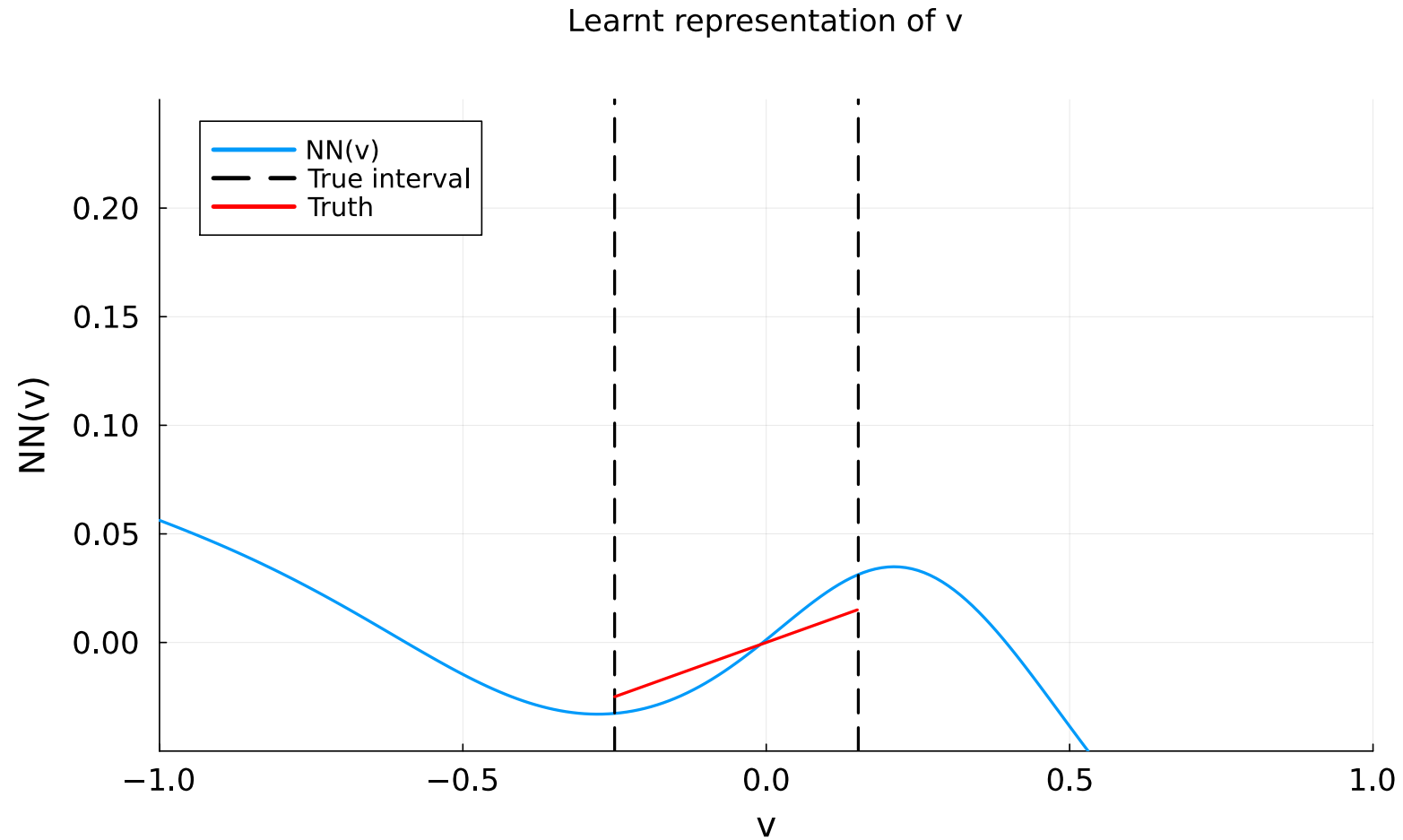
Damped Harmonic Oscillator!

2nd order ODE → 1st order system:

$$\dot{x} = v$$

$$\dot{v} = -\frac{kx + bv}{m}$$

$$m\ddot{x} + b\dot{x} + kx = 0$$



Machine learning

```
function loss_nn( $\theta$ )  
    y_pred = NN(x_train,  $\theta$ )  
    loss = MSE(y_pred, y_train)  
    return loss  
end
```

Scientific

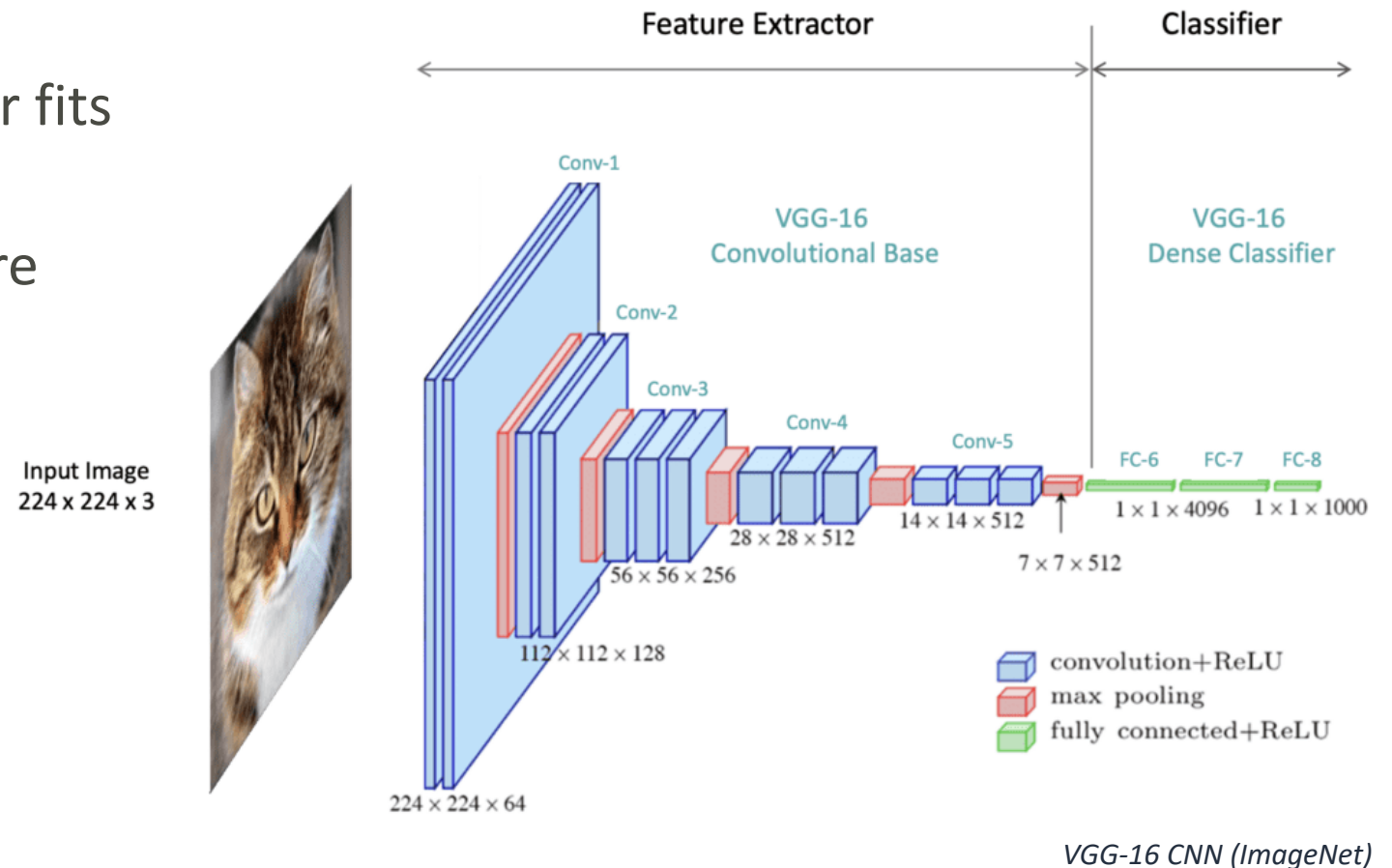
```
function damped_harmonic(u, p, t)  
    x, v = u          # states  
    m, k, b = p        # parameters  
  
     $\partial x = v$   
     $\partial v = -1 / m * (k * x + b * v)$   
  
    return [ $\partial x$ ,  $\partial v$ ] # derivatives  
end
```

Scientific Machine Learning

```
function sciml_harmonic(u, p, t)  
    x, v = u          # states  
    m, k,  $\theta$  = p      # parameters  
  
     $\partial x = v$   
     $\partial v = -1 / m * (k * x + \text{NN}(v, \theta))$   
  
    return [ $\partial x$ ,  $\partial v$ ] # derivatives  
end
```

Structure

- The major advances in machine learning were due to encoding more structure into the model
- More structure = faster and better fits from less data
- Convolutional Neural Networks are structure assumptions



Extrapolation and generalization

- LIGO Black Hole dynamics from the gravitational wave data

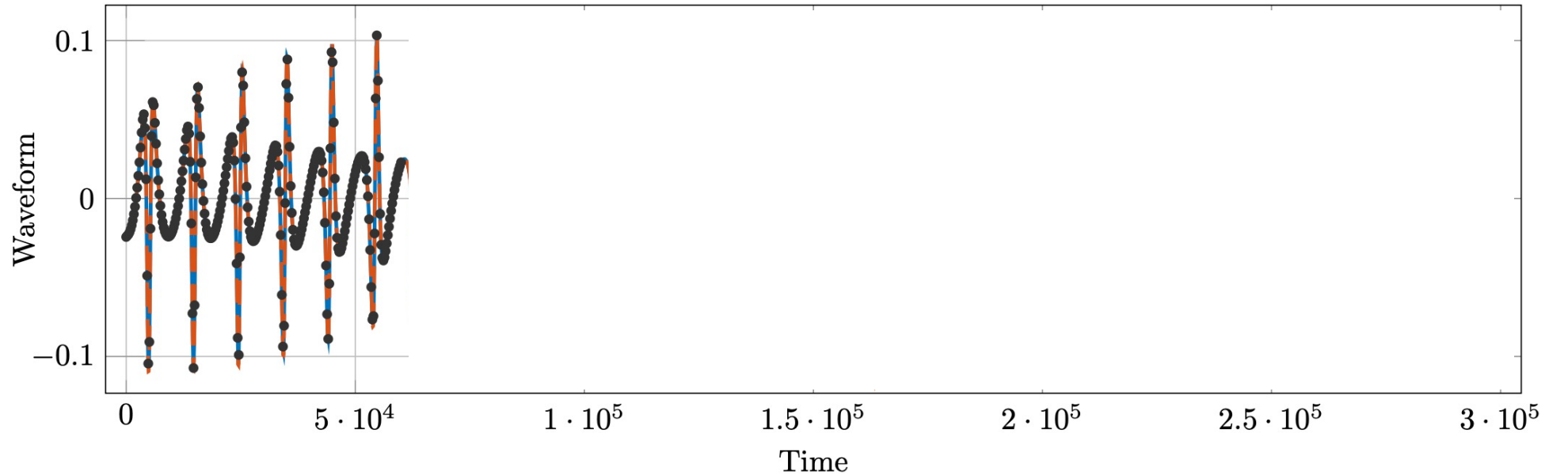
Upon denoting $\mathbf{x} = (\phi, \chi, p, e)$, we propose the following family of UDEs to describe the two-body relativistic dynamics:

$$\dot{\phi} = \frac{(1 + e \cos(\chi))^2}{Mp^{3/2}} (1 + \mathcal{F}_1(\cos(\chi), p, e)), \quad (5a)$$

$$\dot{\chi} = \frac{(1 + e \cos(\chi))^2}{Mp^{3/2}} (1 + \mathcal{F}_2(\cos(\chi), p, e)), \quad (5b)$$

$$\dot{p} = \mathcal{F}_3(p, e), \quad (5c)$$

$$\dot{e} = \mathcal{F}_4(p, e), \quad (5d)$$



TICRA



Founded in 1971



Copenhagen, Denmark



Electromagnetic radiation



Flagship product: TICRA Tools



Long partnership with the European Space Agency (ESA), spacecraft manufacturers, and satellite operators



50 employees
≥ 80% with MSc
~ 60% with Ph.D.



TICRA TOOLS



GRASP



ESTEAM



CHAMP3D



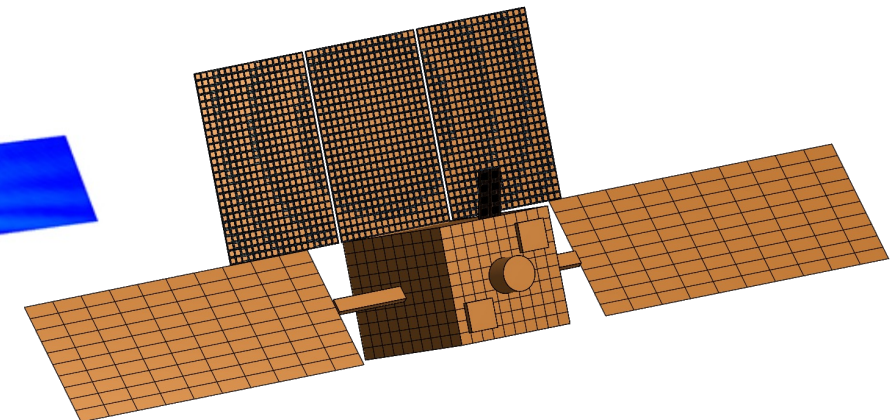
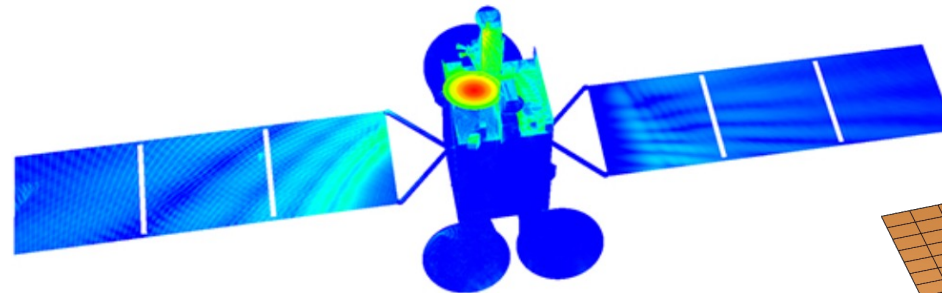
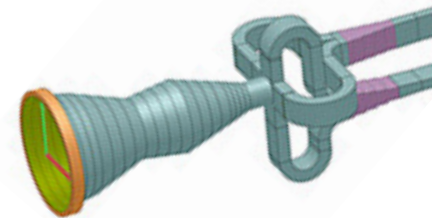
QUPES



POS



UQ



TICRA Core Customers

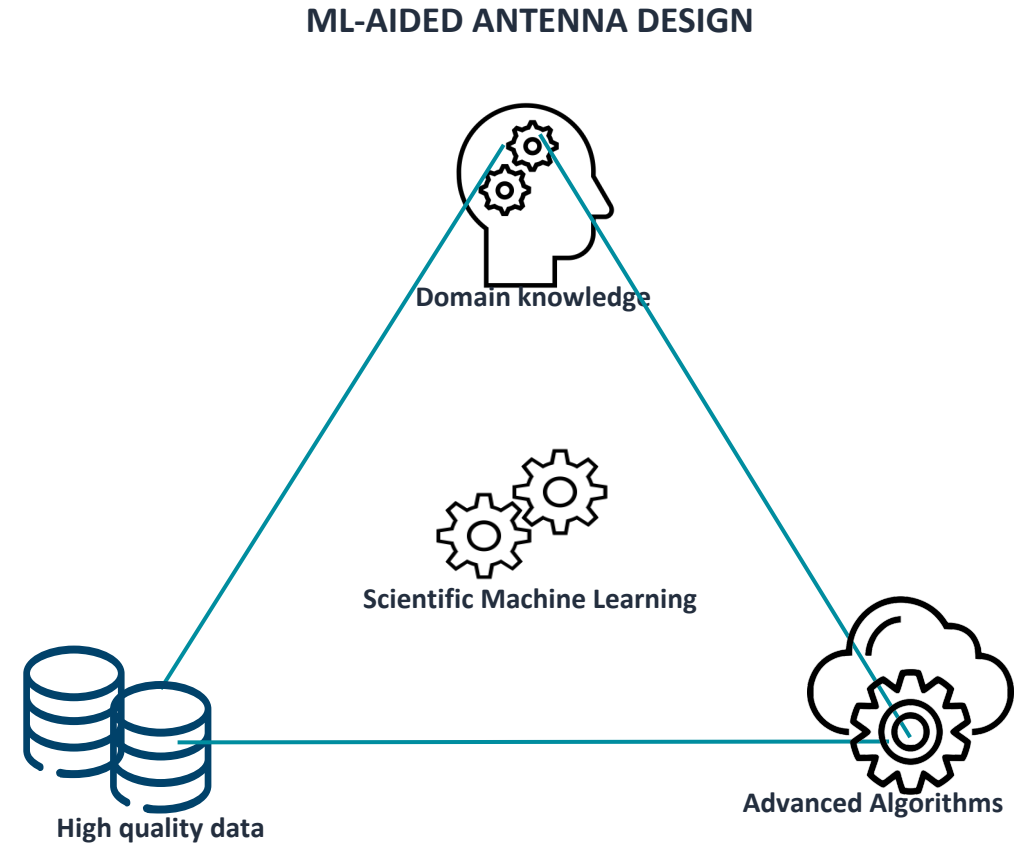
- Space agencies
- Satellite operators
- Satellite, payload and antenna manufacturers



Design Philosophy – Scientific Machine Learning

Core assets:

- Tailored, state-of-the-art simulation and optimisation tools for antenna design
- Solutions to antenna design task that competitors cannot currently solve



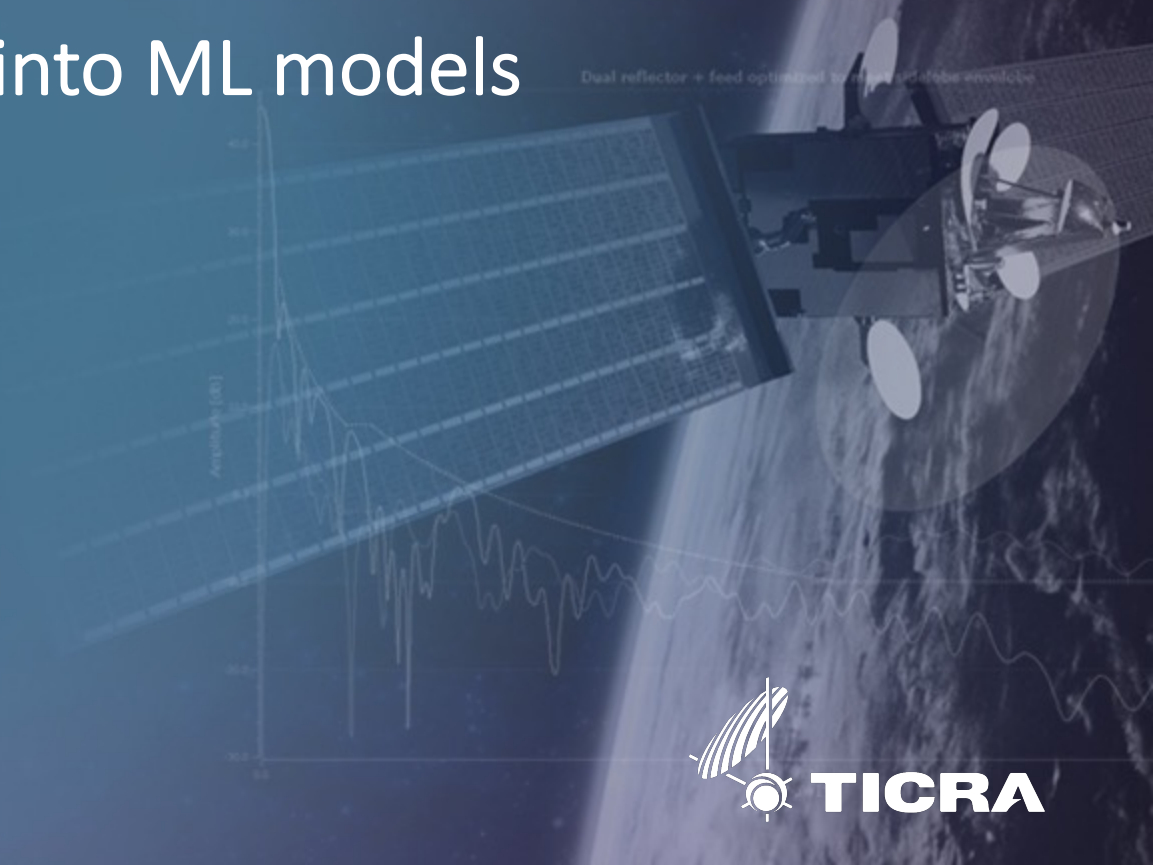
$$\hat{\mathbf{n}} \times \mathbf{E}^i = \hat{\mathbf{n}} \times L_0 \mathbf{J}_s, \quad \mathbf{r} \in S.$$

Incorporating physics into ML models

2025/06/04



www.ticra.com

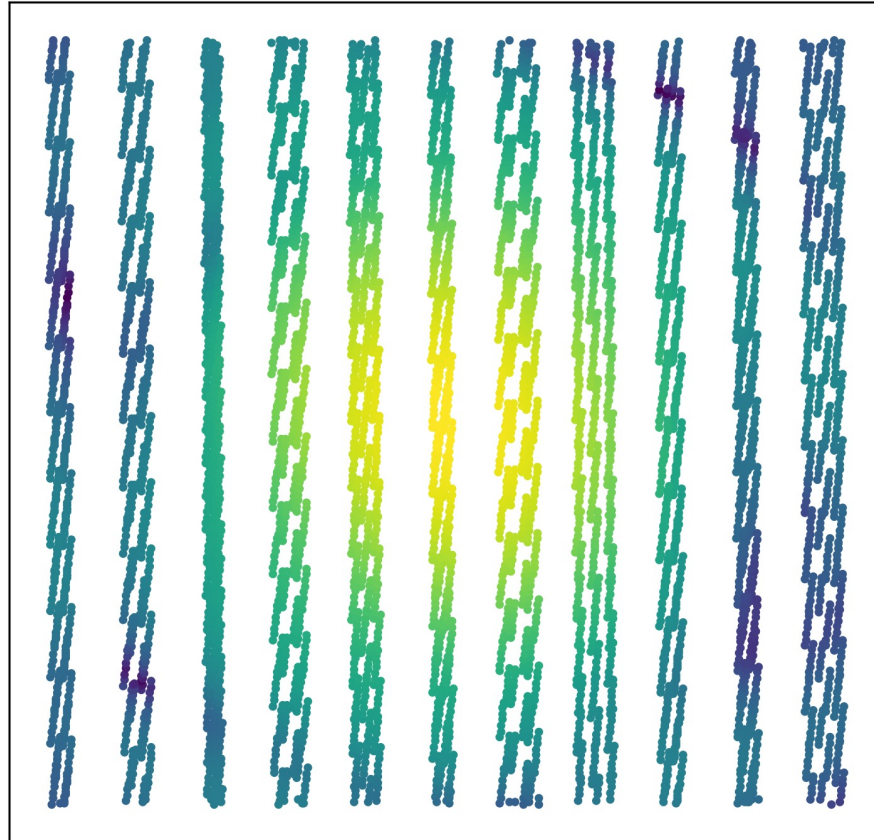


Why incorporate physics?

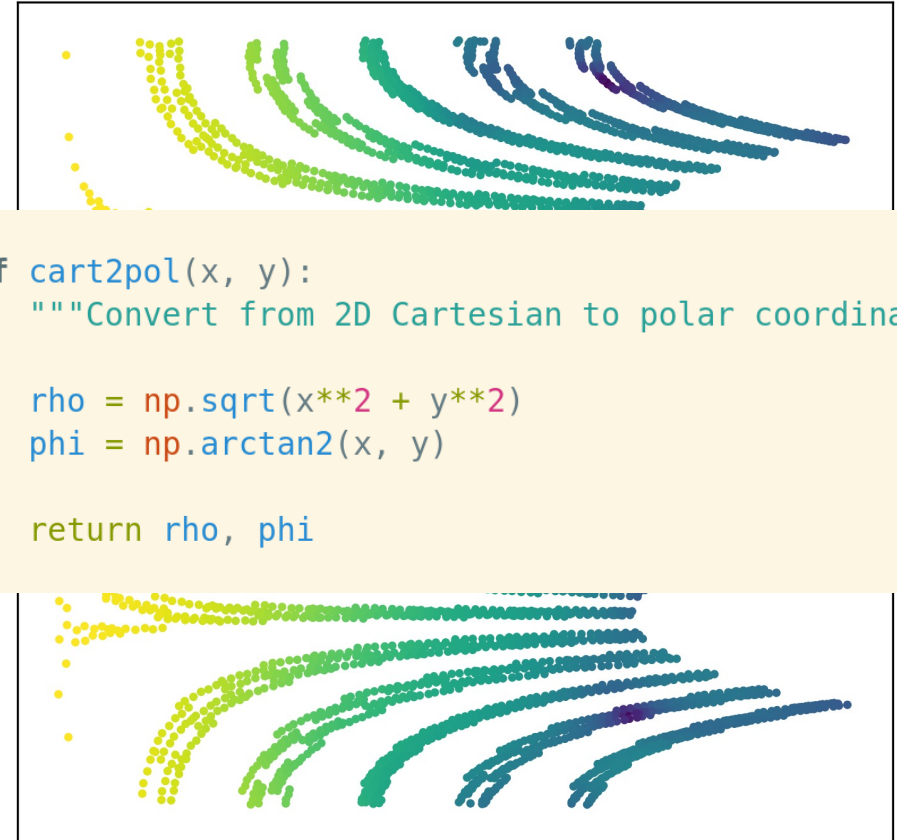
- Traditional methods for solving SciML problems can be slow
 - ML surrogate models could alleviate computational bottlenecks
- SciML data has rich structure that we can take advantage of
 - Data is generated by physics and therefore well-defined (unlike e.g. predicting human behaviour)
 - The physics is often theoretically well-understood
- Incorporating physics makes prediction task easier
 - Shrinks space of possible solutions
 - Acts as a regularizer
 - Can allow for extrapolation, instead of just interpolation
 - Can make models more interpretable and/or trustworthy

Basic example

Original



Transformed



```
1 def cart2pol(x, y):  
2     """Convert from 2D Cartesian to polar coordinates."""  
3  
4     rho = np.sqrt(x**2 + y**2)  
5     phi = np.arctan2(x, y)  
6  
7     return rho, phi
```

$$\hat{\mathbf{n}} \times \mathbf{E}^i = \hat{\mathbf{n}} \times L_0 \mathbf{J}_s, \quad \mathbf{r} \in S.$$

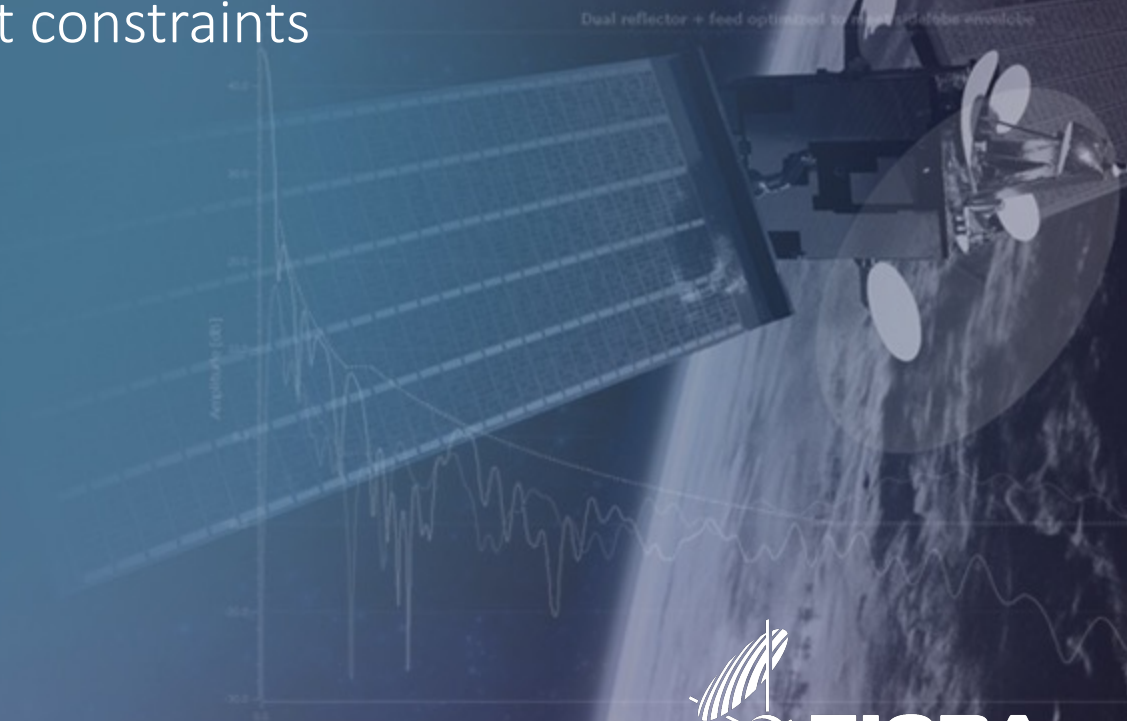
PINNs (Physics-informed NN)

Enforcing physics through soft constraints

2025/06/04



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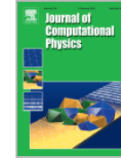
Enforcing physics through soft constraints: PINNs

- Introduced in 2019





Journal of Computational Physics

Volume 378, 1 February 2019, Pages 686-707



Physics-informed neural networks: A deep learning framework for solving forward and inverse problems involving nonlinear partial differential equations

M. Raissi^a, P. Perdikaris^b  , G.E. Karniadakis^a

- Idea:

- Given a PDE, e.g. $(\nabla^2 + k^2)\mathbf{E}(\mathbf{x}) = 0$, approximate its solution with a NN

- Train it to minimize
$$\underbrace{|\mathbf{E}^{\text{pred}}(\mathbf{x}_b) - \mathbf{E}^{\text{true}}(\mathbf{x}_b)|^2}_{\text{data loss}} + \underbrace{|(\nabla^2 + k^2)\mathbf{E}^{\text{pred}}(\mathbf{x}_c)|^2}_{\text{PDE loss}}$$

Enforcing physics through soft constraints: PINNs

>14k citations, making it the most cited numerical methods paper of the 21st century

Still, lots of problems:

- Training instabilities, especially in high-frequency domain
- Only works for small networks (typically less than 0.5M parameters)
- No accuracy guarantees, as opposed to traditional numerical methods
- Uses expensive second order optimization methods (L-BFGS), which has implications for activations functions
- etc.

**Characterizing possible failure modes
in physics-informed neural networks**

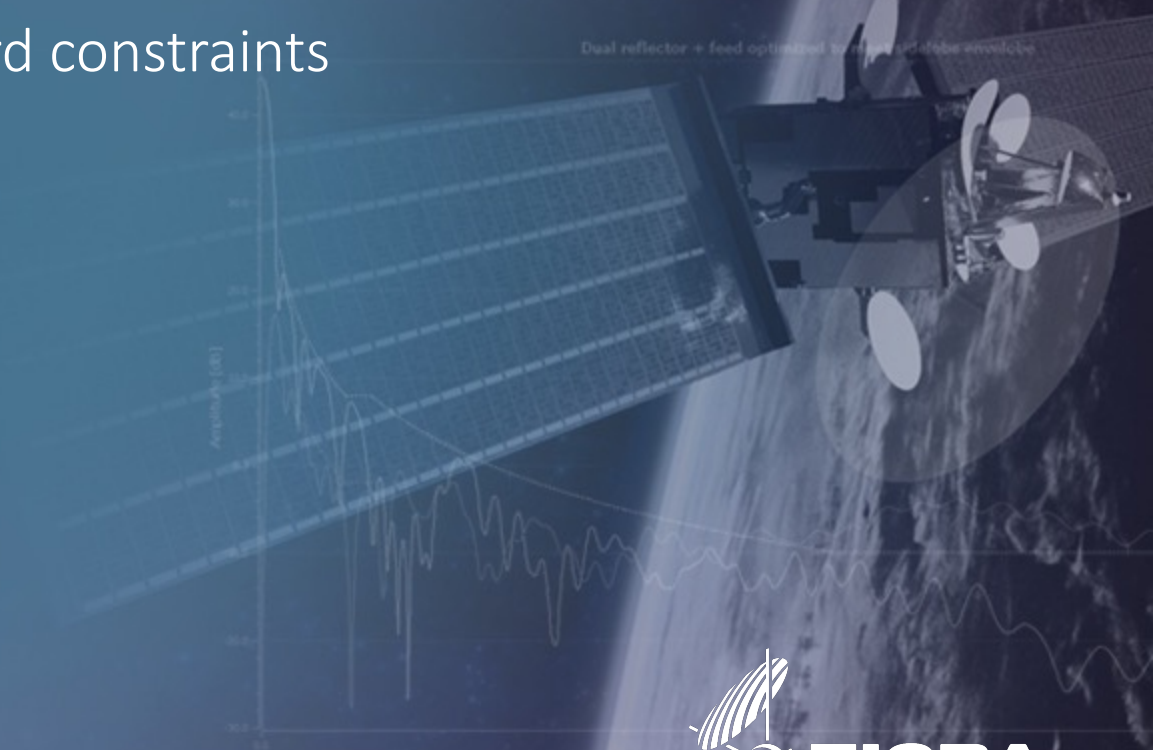
Aditi S. Krishnapriyan^{*,1,2}, Amir Gholami^{*,2},
Shandian Zhe³, Robert M. Kirby³, Michael W. Mahoney^{2,4}

$$\hat{\mathbf{n}} \times \mathbf{E}^i = \hat{\mathbf{n}} \times L_0 \mathbf{J}_s, \quad \mathbf{r} \in S.$$

Satisfying physical laws

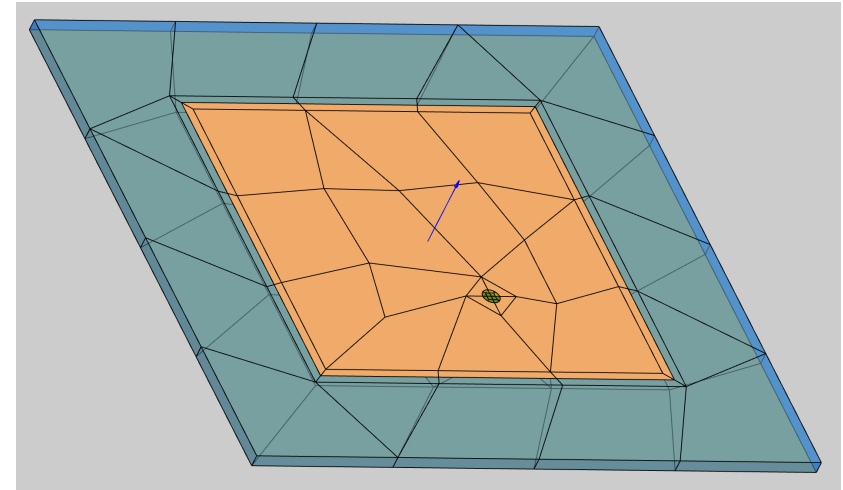
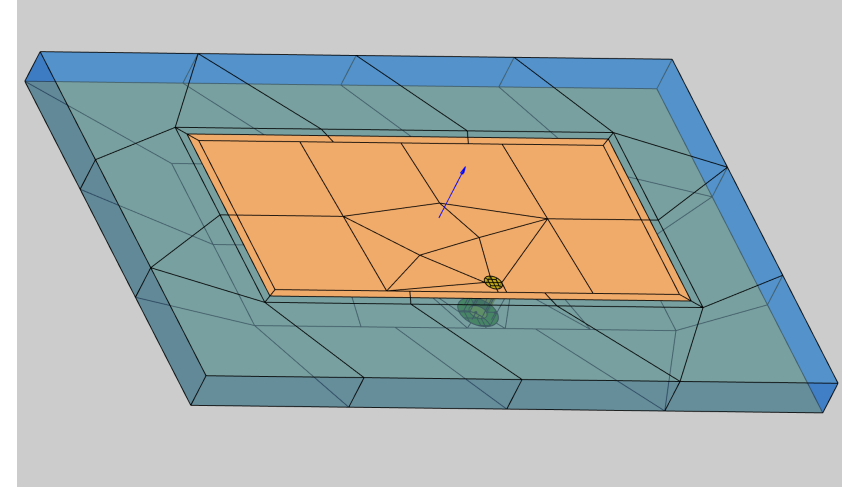
Enforcing physics through hard constraints

2025/06/04

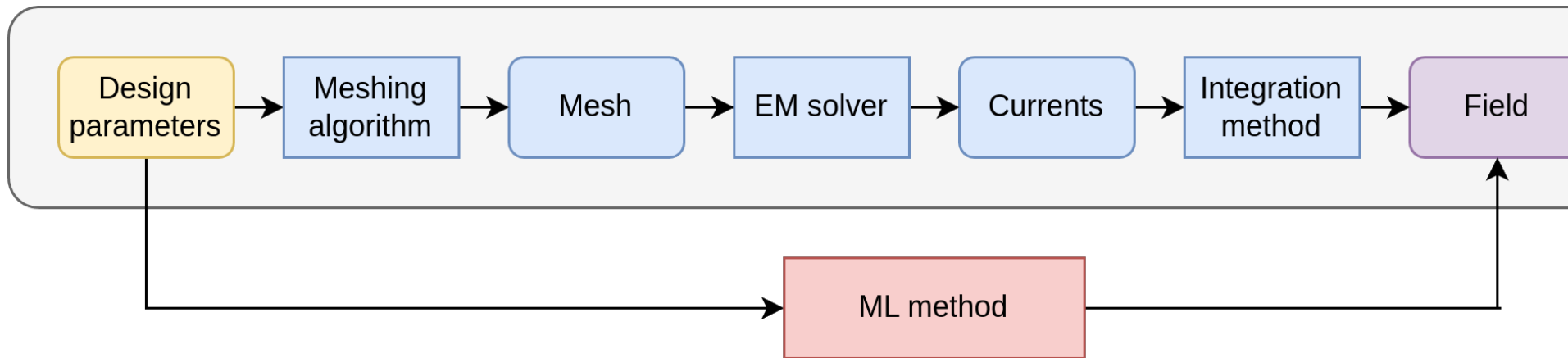


Enforcing physics through hard constraints: Via problem formulation

- Suppose you were designing an antenna, trying out different designs
- Every change requires you to wait *minutes* before you can see if it got better
- Train a surrogate model to predict the antenna's EM field from the design parameters!



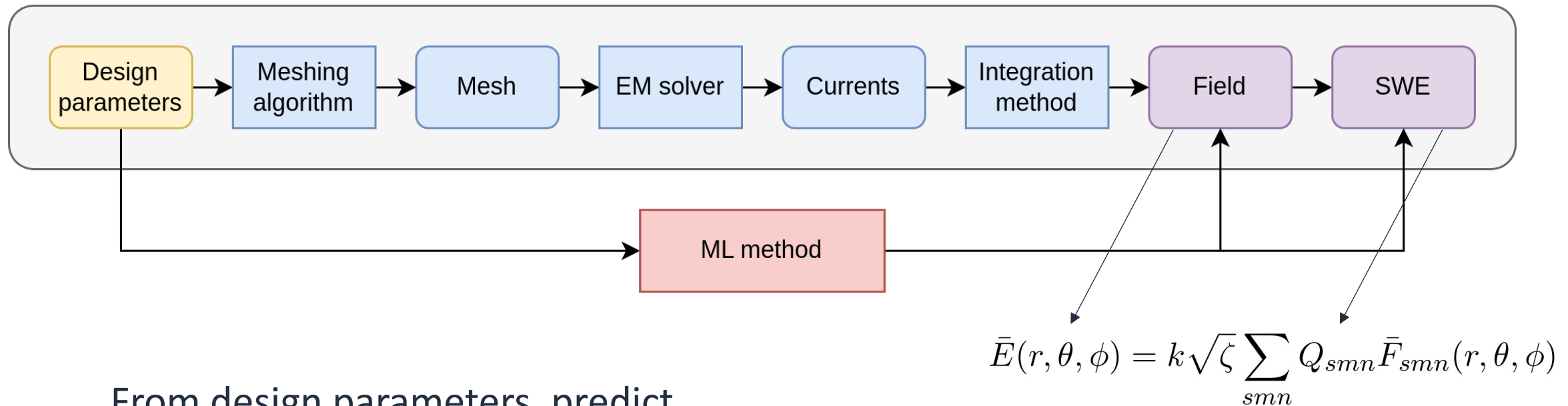
Enforcing physics through hard constraints: Via problem formulation



From design parameters, predict

- EM field in grid (3264 predicted variables)

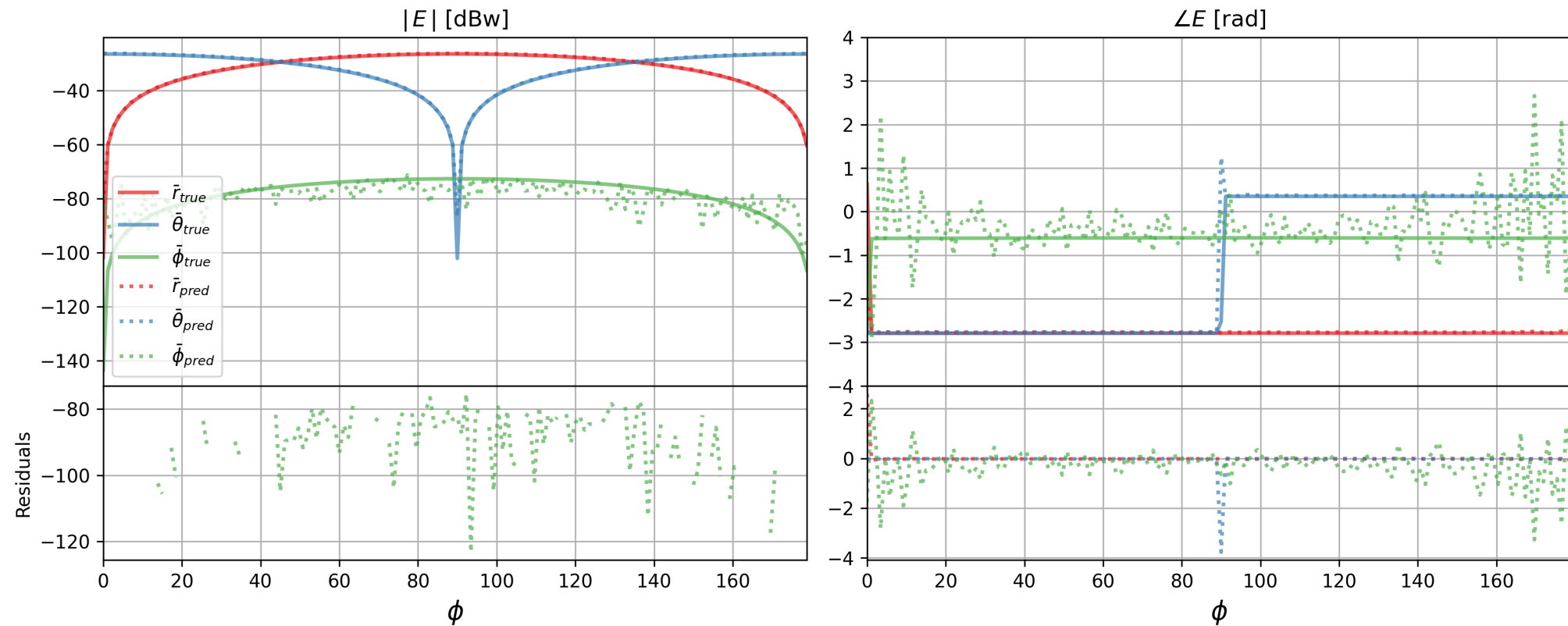
Enforcing physics through hard constraints: Via problem formulation



From design parameters, predict

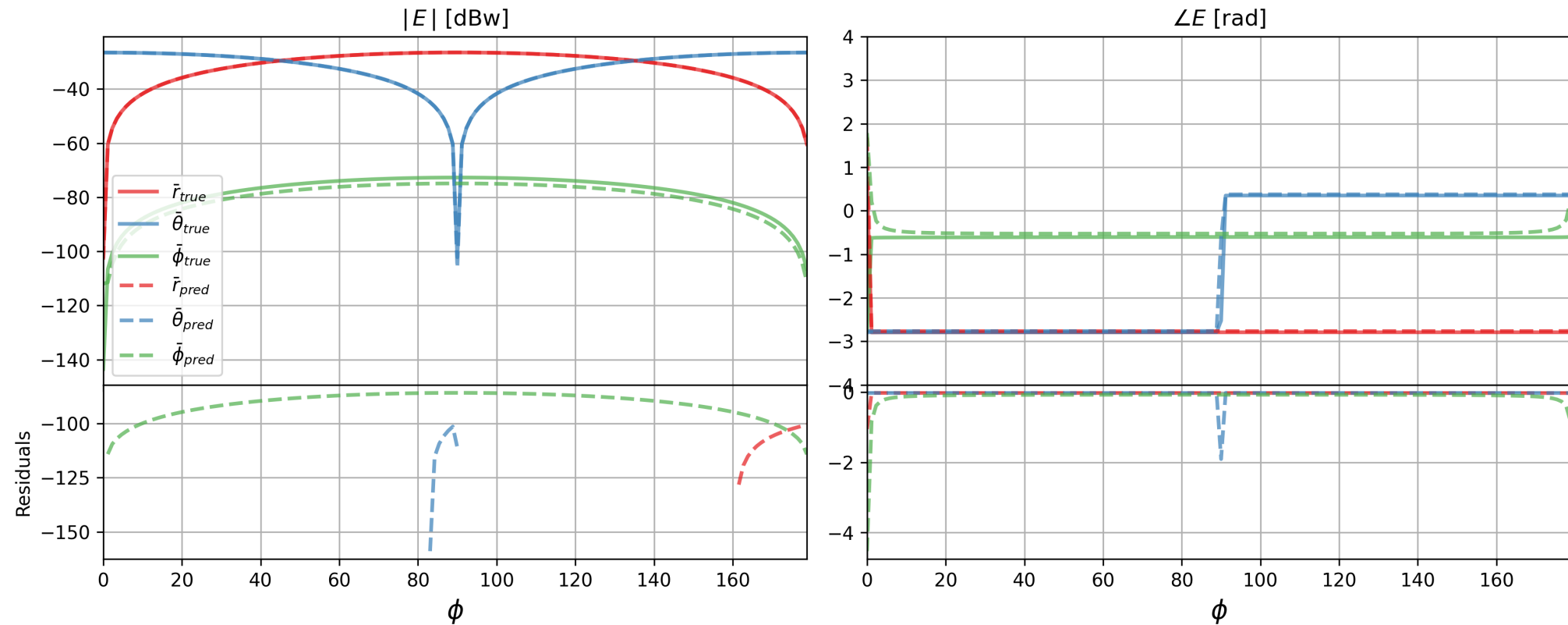
- EM field in grid (3264 predicted variables)
- Expansion (SWE) coefficients encoding the EM field (96 predicted variables)
 - Compressed representation
 - Guarantees that the predicted field is a solution to Maxwell's equations (!!)

Enforcing physics through hard constraints: Via problem formulation



Good performance, but quite jittery/unphysical

Enforcing physics through hard constraints: Via problem formulation



Still good performance, but much more physically correct
(this stuff matters to domain experts!)

Thank you!

Christian Buus Michelsen

Senior ML Engineer @ TICRA

Scientific Machine Learning 2025-06-04

<https://github.com/ChristianMichelsen/SciMLPresentation>